A comparison of two and three dimensional multi-scale simulations as applied to porous heterogeneous materials

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## Collaborators



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### **Objective:**

Better understand complicated dynamics at the bulk scale by building up our understanding of the compaction dynamics from simple models at the particle scale.

### **Solution Procedure:**

Two and three dimensional Hydro-code calculations: CTH (Eulerian), EPIC (Lagrangian), EMU(periadynamics)

# Outline



- High Strain Rate (> 10<sup>5</sup> 1/s)
  - Two-Dimensional Mesoscale simulations of Tungsten Carbide
  - Three-Dimensional WC simulations
  - Wet and Dry Sand
- Low Strain Rate (< 10<sup>3</sup> 1/s)
  - 2D and 3D simulations of Sand



### Tungsten Carbide: Plane Strain Simulations







### Plane Strain Impact Experiments

Strain-rate: > 10<sup>5</sup> s<sup>-1</sup>









- Duplicates geometry of experiments
- 2-D and 3D simulations of porous granular materials (Baer, Benson and others)
- Calculations contain ~1,400 particles, idealized as circles (rods in 3D), with periodic y-direction BC
- CTH (explicit Eulerian finite difference code) with ~12 cells across particle diameter
- WC modeled with Mie-Gruneisen EOS, elastic-perfectly plastic strength, and failure at a specified tensile stress
- Bulk material properties obtained from open literature
- Ridged driver plate with constant velocity (simulations between 5~7,000 m/s)

Pressure (GPa)

2.0

1.8

1.6

1.4

1.2

1.0

0.8

0.6

0.4

0.2



- Dynamic stress bridging
- Compaction wave, 5 particle thick •
- Two-dimensional flow field,  $\sigma_{ii} \neq 0$ ٠



#### Newton (Principia, 1687)



#### Average in lateral direction to determine bulk response



## 2D Mesoscale Baseline Results



#### **Baseline Configuration:**



### Multiple regimes of behavior:

- 1. Rigid: Simple material translation soliton wave
- Compaction: A) Elastic: grain deformation is mostly elastic below MPD
  B) Elastic-Plastic: mixed deformation above MPD
- 3. Plastic



### **Parametric:**

- Vary *material realization* holding the bulk density fixed.
- Vary the *dynamic yield strength*.
- Vary the *fracture stress*.



## Material Realization:



#### Ordered Grains



#### Material Perturbations







![](_page_14_Picture_1.jpeg)

#### Material Realization:

![](_page_14_Figure_3.jpeg)

Bulk response highly dependent upon material/particle arrangement

Increasing material perturbation collapses bulk response

![](_page_15_Picture_1.jpeg)

### Variations in Dynamic Yield Strength

![](_page_15_Figure_3.jpeg)

- Specified flow stress determines Hugoniot intercept
- MPD density is invariant to yield
- Rigid response is invariant to yield

![](_page_16_Picture_1.jpeg)

### Variations in Dynamic Fracture Strength

![](_page_16_Figure_3.jpeg)

- WC spall strength is 2~1.4 GPa depending on shock level.
- Fracture strength have no effect on bulk behavior above 2 GPa.
- As fracture strength is reduced bulk stiffness is reduced.

![](_page_17_Picture_0.jpeg)

# **Three-Dimensional Simulations**

Loose Dry Tungsten Carbide

![](_page_18_Picture_1.jpeg)

Constructing three dimensional random geometries, at high pack densities, can be challenging.

![](_page_18_Figure_3.jpeg)

## 3D Geometries

![](_page_19_Picture_1.jpeg)

### Initial Results exhibited geometry dependence

![](_page_19_Figure_3.jpeg)

Particle Boundaries

![](_page_20_Picture_1.jpeg)

### Stiction (welding) versus Sliding

![](_page_20_Figure_3.jpeg)

- The degree of stiction varies due to interface contact
- Since neighboring particles are assigned different material numbers, a sliding interface can be imposed.

## Compaction Wave

![](_page_21_Picture_1.jpeg)

Pressure at 1,00e-06 seconds

![](_page_21_Figure_3.jpeg)

![](_page_22_Picture_0.jpeg)

400 m/s

300 m/s

0.25

Sliding

3.00E+10

2.00E+10

**Stiction** 

400 m/s. 300 m/s 2.005+10 1.00E+10 200 m/s 200 m/s 1.00E+10 100 m/d 0.00E+00 D.00E+00 0.05 0.3 0.35 0.1 0.15 0.2 0.25 0.05 0.1 0.15 0.2 Longitudinal Distance (cm) Longitudinal Distance, x (cm)

ĝ

3.00E+10

- General smooth nature of 3D simulations
- Precursor wave

500 m/s

## Lateral Stress

![](_page_23_Picture_1.jpeg)

![](_page_23_Figure_2.jpeg)

Sliding allows lateral stress to change sign

## Shear Stress

![](_page_24_Picture_1.jpeg)

![](_page_24_Figure_2.jpeg)

• Wave profile is consistent with plateau at 5 GPa, except for 3D Stiction

## Summary Stress

![](_page_25_Picture_1.jpeg)

![](_page_25_Figure_2.jpeg)

![](_page_26_Picture_0.jpeg)

# Summary Stress

![](_page_26_Figure_2.jpeg)

- 2D stiction and 3D sliding are nearly identical
- Both however under predict experiments at high stress
- Stiction like response better simulates the data at higher stress But what else might differ?

# Rise Times

![](_page_27_Picture_1.jpeg)

### Swegle and Grady shock rise time relation: $\mathcal{E} = \sigma^n$

- $n \sim 4$ : homogeneous metals and ceramics
- $n \sim 2$ : layered polycarbonate aluminum, stainless steel, or glass
- **n** ~ 1: granular materials: WC, SiO<sub>2</sub>, TiO<sub>2</sub>, and sugar

![](_page_27_Figure_6.jpeg)

# Fully Consolidated

![](_page_28_Picture_1.jpeg)

Variations in bulk response is more pronounced for granular materials as opposed to consolidated materials.

![](_page_28_Figure_3.jpeg)

![](_page_29_Picture_0.jpeg)

# Wet and Dry Sand

### How does our view of wet sand sand change?

## Experimental Data

![](_page_30_Picture_1.jpeg)

### Hugoniot "sand" data is not consistent

![](_page_30_Figure_3.jpeg)

## Dry Sand

![](_page_31_Picture_1.jpeg)

#### Distribution of material properties

Parameter	Quartz	Water
Density, $\rho \left[ g/cm^3 \right]$	2.65	0.998
Zero stress shock speed, $C_0 [km/s]$	-	1.921
x-cut	5.610	-
z-cut	6.329	-
Hugoniot slope, s	-	1.921
x-cut	1.07	-
z-cut	1.56	-
Grüneisen coefficient, $\Gamma = V(\partial P / \partial E)_V$	0.9	0.35
Specific heat, $C_V [J/(g-K)]$	0.85	8.32
Bulk Dynamic yield strength, Y [GPa ]	-	0.
x-cut (low, average, high)	4.1, 5.8, 7.0	-
z-cut (low, average, high)	8.2, 10.3, 12.4	-
Poisson's ratio, v	0.15	0.5
Fracture strength, $\sigma_{s}$ [ <i>GPa</i> ]	0.044 - 15 GPa	0.0001

![](_page_31_Figure_4.jpeg)

![](_page_31_Figure_5.jpeg)

Rearrangement zone

![](_page_32_Picture_0.jpeg)

![](_page_32_Picture_1.jpeg)

![](_page_32_Picture_2.jpeg)

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![](_page_32_Figure_5.jpeg)

- This time 2D stiction simulations *over predict* bulk stiffness
- A *reduction* in strength is necessary to match experiment
- Distribution of strength provides some underlying skeletal strength

![](_page_33_Picture_0.jpeg)

### Wet Sand

![](_page_33_Picture_2.jpeg)

7% (by weight) moisture ... but how do we insert the water?

![](_page_33_Figure_4.jpeg)

![](_page_33_Figure_5.jpeg)

Ligaments

![](_page_33_Figure_7.jpeg)

- Reduced yield strength was used.
- Bulk stiffness varies with water distribution
- Coatings induce sliding and provide less bulk stiffness

Experimental data from Chapman, Tsembelis & Proud Proceedings of the 2006 SEM, St. Louis, MO June 4-7 2006

![](_page_34_Picture_0.jpeg)

### Near Saturated Sand

![](_page_34_Picture_2.jpeg)

#### 22% (by weight) moisture

![](_page_34_Figure_4.jpeg)

### Adjusted strength calculations are now too stiff Do not see the large variation between 20% and 22%

![](_page_35_Picture_1.jpeg)

### Recent Results:

![](_page_35_Figure_3.jpeg)

This time 2D stiction and 3D sliding do not correspond

![](_page_36_Picture_0.jpeg)

## Low Strain Rate

![](_page_37_Picture_0.jpeg)

![](_page_37_Picture_1.jpeg)

#### Hopkinson or Kolsky Bar Strain-rate: 500 to 1,600 s<sup>-1</sup>

![](_page_37_Picture_3.jpeg)

**Brad Martin** Air Force Research Laboratory

Weinong Wayne Chen AAE & MSE, Purdue University

Quikrete® #1961 fine grain sand

- Dry conditions with a 1.50 g/cc density
- Specimens 19.05 mm diameter and 9.3 mm thick

![](_page_38_Picture_0.jpeg)

![](_page_38_Picture_1.jpeg)

#### **Preliminary Variation in Confinement Pressure**

![](_page_38_Figure_3.jpeg)

Results provided by Md. E. Kabir (AAE , Purdue University) **Test Conditions:** 

- Quikrete® #1961 fine grain sand
- Dry conditions with a 1.50 g/cc density
- Specimen 19.05 mm diameter and 9.3 mm thick

![](_page_38_Figure_9.jpeg)

## Geometry

![](_page_39_Picture_1.jpeg)

- Parallel
- Lagrangian
- Slide faces resolved

![](_page_39_Figure_5.jpeg)

### CTH (Sandia)

- Massively Parallel
- Eulerian
- Extensive constitutive library

### EMU (Sandia- Silling and Foster)

- Massively Parallel
- peridynamics

![](_page_39_Figure_13.jpeg)

• Constitutive relation under development

![](_page_39_Figure_15.jpeg)

# **CTH Simulations**

![](_page_40_Picture_1.jpeg)

![](_page_40_Figure_2.jpeg)

- Since the driver plate speed << bulk sound speed, the target is in equilibrium ahead of the driver plate.
- Justification for small 3D geometry.
- Average stress is extracted for a given longitudinal position (strain)

## EPIC versus CTH

![](_page_41_Picture_1.jpeg)

- CTH best matches the high strain experimental data when there is *Stiction*
- EPIC best matches the low strain experimental data when there is *Sliding*

#### CTH

![](_page_41_Figure_5.jpeg)

# Summary

![](_page_42_Picture_1.jpeg)

#### High Strain Rate

- At high strain rates, 2D stiction and 3D sliding nearly identical for WC Hugoniot response
- Baseline 3D sliding simulations worked best for Sand
- Even if Hugoniot response for 2D and 3D match, other differences remain: rise times, hot spots (?).

#### Low Strain Rate

- At low strain rate the role of particle boundaries varies.
  - At low strain, stiction is required to match data.
  - At higher strain, particles slide best matches data.

## Review

![](_page_43_Picture_1.jpeg)

#### **Relevant Publications:**

- Borg, JP and Vogler, TJ, *Mesoscale Simulations of a Dart Penetrating Sand*, Inter. J. of Impact Eng., 35(12) Dec. 2008 pg 1435-1440.
- Borg, JP and Vogler, TJ, Mesoscale Simulations of a Dart Penetrating Sand, Inter. J. of Impact Eng., 35(12) Dec. 2008 pg 1435-1440.
- 3. Borg, J.P. and Vogler, T. Mesoscale Calculations of the Dynamic Behavior of a Granular Ceramic. International Journal of Solids and Structures 45 (2008) 1676–1696
- 4. Borg, JP and Vogler, TJ, The Effect of Water Content on the Shock Compaction of Sand, **The European Physical Journal-Special Topics (accepted)**
- 5. Borg, JP and Vogler, TJ *Mesoscale Calculations of Shock Loaded Granular Ceramics*. Shock Compression of Condensed Matter-2007
- 6. Vogler, TJ and Borg, JP *Mesoscale and Continuum Calculations of Wave Profiles for Shock-Loaded Granular Ceramics*. Shock Compression of Condensed Matter-2007
- Borg, J., Lloyd, A., Ward, A., Cogar, J.R., Chapman, D., and Proud, W. G., Computational Simulations of the Dynamic Compaction of Porous Media, Inter. J. of Impact Eng, 33, pg. 109–118, 2006
- 8. Borg, J.P., Chapman, D., Tsembelis, K., Proud, W. G., and Cogar, J.R. Dynamic Compaction of Porous Silica Power, J. Applied Physics, vol. 98 (7), pg. 073509:1-7, 2005.

## Questions?

![](_page_44_Picture_1.jpeg)

![](_page_44_Picture_2.jpeg)

## **Granular Mechanics**