# Algebraic Geometry over Groups

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# **Equations over free groups**

Fix  $\mathbb{F}$  a free (non-abelian) group of rank at least 2, and consider a finite set  $\Phi$  of equations

$$w_i(x_1,\ldots,x_n)=1$$

in n unknowns. Let  $G = G(\Phi)$  be the group with presentation

$$\langle x_1,\ldots,x_n|w_i(x_1,\ldots,x_n)\rangle.$$

A solution of  $\Phi$  defines a homomorphism

$$G \to \mathbb{F}$$
,

and, conversely, such a homomorphism defines a solution of  $\Phi$ . So the 'variety' associated to  $\Phi$  is really just  $\text{Hom}(G,\mathbb{F})$ . This is the object we shall attempt to describe.

# First examples

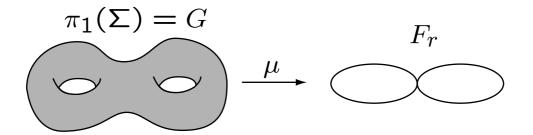
ullet  $G=F_r$  the free group of rank r. Then  $\operatorname{Hom}(G,\mathbb{F})\equiv \mathbb{F}^r.$ 

•  $G=\mathbb{Z}^r$  the free abelian group of rank r. Let  $\mu:G\to\mathbb{Z}$  be projection onto the first factor. Any homomorphism  $f:G\to\mathbb{F}$  decomposes as

$$G \xrightarrow{\alpha} G \xrightarrow{\mu} \mathbb{Z} \to \mathbb{F}$$

for some automorphism  $\alpha$ . So we have an epimorphism

$$GL_r(\mathbb{Z}) \times \mathbb{F} \to \mathsf{Hom}(G,\mathbb{F}).$$



•  $G=\pi_1(\Sigma)$  the fundamental group of a closed orientable surface of genus g>1, and let  $\mu:G\to F_r$  be the homomorphism induced by the inclusion of  $\Sigma$  as the boundary in the handlebody of genus r. Then every homomorphism  $G\to \mathbb{F}$  decomposes as

$$G \xrightarrow{\alpha} G \xrightarrow{\mu} F_r \to \mathbb{F}$$

for some automorphism  $\alpha$  of G arising from an automorphism of  $\Sigma$ . So we have an epimorphism

$$\operatorname{\mathsf{Aut}}(\mathbf{\Sigma}) imes \mathbb{F}^r o \operatorname{\mathsf{Hom}}(G,\mathbb{F}).$$

# **Makanin-Razborov Diagrams**

A general description of  $Hom(G, \mathbb{F})$  along these lines was first given by Makanin and Razborov.

**Theorem 1 (Makanin, Razborov)** To every finitely generated group G there is associated a finite tree of homomorphisms from G to  $\mathbb{F}$ , called a Makanin-Razborov diagram. Each group in the tree is a limit group, and each homomorphism  $G \to \mathbb{F}$  factors through a branch of the diagram, after composing at each stage with automorphisms of the limit groups.

# **Limit groups**

There are many equivalent definitions of limit groups. This one will best suit our purposes.

**Definition 2** A group G is a limit group if, for any finite subset  $S \subset G$ , there exists a homomorphism  $f: G \to \mathbb{F}$ , such that f|S is injective.

Here are the simplest examples.

- Free groups
- Free abelian group
- ullet Fundamental groups of closed surfaces of Euler characteristic less than -1

The rest of this talk is devoted to explaining the proof of theorem 1 (skating over some details). Its principle assertions are about the finiteness of the tree. The next theorem shows that the tree is only finitely long.

## Theorem 3 Let

$$G_1 \rightarrow G_2 \rightarrow G_3 \rightarrow \cdots$$

be a sequence of epimorphisms of finitely generated groups. Then the corresponding sequence of monomorphisms

 $\mathsf{Hom}(G_1,\mathbb{F}) \leftarrow \mathsf{Hom}(G_2,\mathbb{F}) \leftarrow \mathsf{Hom}(G_3,\mathbb{F}) \leftarrow \cdots$ eventually stabilizes. The proof of theorem 3 makes use of a little classical algebraic geometry.

**Theorem 4 (Hilbert's Basis Theorem)** If R is a Noetherian ring then the polynomial ring R[x] is also Noetherian.

In particular, every descending sequence of algebraic varieties

$$X_1 \supset X_2 \supset X_3 \supset \dots$$

eventually terminates.

**Proof of theorem 3:** Embed  $\mathbb{F} \hookrightarrow SL_2(\mathbb{R})$ . (For example, a hyperbolic metric on a punctured sphere gives an embedding  $\mathbb{F} \hookrightarrow PSL_2(\mathbb{R})$ .) This lifts to  $SL_2(\mathbb{R})$ .) This induces an embedding

$$\mathsf{Hom}(G,\mathbb{F}) \to \mathsf{Hom}(G,SL_2(\mathbb{R})).$$

Fix a presentation

$$G = \langle g_1 \dots g_m | r_1, r_2, \dots \rangle.$$

A homomorphism  $f: G \to SL_2(\mathbb{R})$  is just a choice of values for the  $f(g_i)$  such that the relations  $f(r_j)$  are satisfied. In other words,

$$\mathsf{Hom}(G, SL_2(\mathbb{R})) \hookrightarrow SL_2(\mathbb{R})^m$$

as a subvariety. (I think Richard would rather I said sub-scheme.) By Hilbert's Basis Theorem, the resulting decreasing sequence of varieties eventually stabilizes. **QED** 

The remainder of the proof of theorem 1 consists of showing that the diagram is finitely wide.

**Definition 5** Let G be a finitely generated group. A factor set is a finite set of proper quotients

$$\{q_i:G\to L_i\}$$

such that any homomorphism  $f:G \to \mathbb{F}$  factors as

$$G \xrightarrow{\alpha} G \xrightarrow{q_i} L_i \to \mathbb{F},$$

where  $\alpha$  is a 'modular' automorphism of G.

I won't define modular automorphisms, but if G isn't a limit group then the group of modular automorphisms is trivial.

**Theorem 6** Every non-free finitely generated group has a factor set

$$\{q_i:G\to L_i\}$$

with each  $L_i$  a limit group.

## A nice reduction

There's a nice observation that reduces theorem 6 to the case of limit groups straight away. Suppose G is not a limit group. Then there exist elements  $g_1, \ldots, g_n$  such that any homomorphism  $f: G \to \mathbb{F}$  kills one of the  $g_i$ . Now

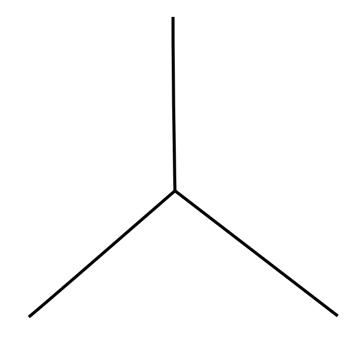
$$\{q_i: G \to L_i = G_i/\langle\langle g_i \rangle\rangle\}$$

is a factor set for G.

## Metric trees

Metric trees (also known as  $\mathbb{R}$ -trees) generalize the usual (simplicial) notion of tree. A metric space is *geodesic* if every pair of points are joined by an isometrically embedded interval.

**Definition 7** A metric tree is a geodesic metric space (T,d) in which every geodesic triangle is isometric to a tripod.



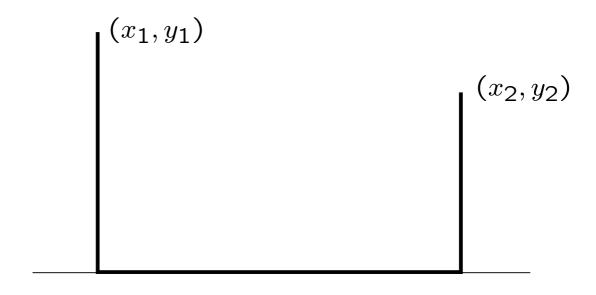
Simplicial trees are clearly metric trees. Here's a non-simplicial example.

**Example 8 (The SNCF metric)** Consider the metric on  $\mathbb{R}^2$  given by

$$d((x, y_1), (x, y_2)) = |y_1 - y_2|$$

and

$$d((x_1, y_1), (x_2, y_2)) = |y_1| + |x_1 - x_2| + |y_2|$$
  
for  $x_1 \neq x_2$ .



#### G-trees

A metric tree equipped with an action of a finitely generated group G by isometries is called a G-tree. Here we review a few of the basics of the theory of group actions on trees.

A G-tree T is trivial if there is a point of T fixed by G.

T is *minimal* if it contains no proper G-invariant subtrees.

**Lemma 9** Every non-trivial G-tree contains a unique minimal subtree, which is a countable union of lines.

# Cayley graphs

Let G be a group, and S a generating set. Then the *Cayley graph* of G with respect to S is the graph with vertex set G and an edge (g,h) if

$$h = gs$$

for some  $s \in S$ . The Cayley graph has a G-action inherited from left-multiplication by G, and a G-invariant metric given by counting the number of edges in the shortest path.

**Example 10** Loops in the Cayley graph correspond to relations between the generators. So a group has a Cayley graph which is a tree if and only if it's free.

Fix a generating set for  $\mathbb{F}$ , such that its Cayley graph T is a tree. Then a homomorphism f:  $G \to \mathbb{F}$  induces an action of G on T, where

$$g: t \mapsto f(g)t$$
.

Denote the minimal G-invariant subtree of T by  $T_f$ .

# The space of trees

Let A(G) be the set of non-trivial minimal G-trees. It can be endowed with a topology, known as equivariant Gromov-Hausdorff topology. I won't give details of this topology here.

Let  $\mathbb{P}\mathcal{A}(G)$  be the quotient space arising from identifying (T,d) with  $(T,\lambda d)$  for all  $\lambda>0$ . The space of interest is

$$\mathfrak{I}(G) \subset \mathbb{P}\mathcal{A}(G)$$

the closure of  $\{T_f|f\in \operatorname{Hom}(G,\mathbb{F})\}$ , the subspace of G-trees arising from homomorphisms to  $\mathbb{F}$ .

# **Strategy**

The strategy for proving theorem 6 is now approximately as follows.

- 1. Show that  $\mathfrak{I}(G)$  is compact.
- 2. Apply compactness to the open cover

$$\mathcal{U} = \{U(k)|k \in G - \{1\}\}$$
 where  $U(k) = \{T|k \in \ker T\}$ .

The theorem would then follow; for by compactness,  $\mathfrak{T}(G)$  is covered by

$$U(k_1),\ldots,U(k_n).$$

In particular, each homomorphism  $f:G\to \mathbb{F}$  factors through one of

$$q_i: G \to L_i = G/\langle\langle k_i \rangle\rangle.$$

The slickest way to show compactness uses a technique of non-standard analysis pioneered by Gromov.

## **Ultralimits**

An ultrafilter  $\omega$  is a finitely additive set function on  $\mathbb{N}$ , such that for every  $S \subset \mathbb{N}$ ,  $\omega(S) \in \{0,1\}$ . An ultrafilter is *principal* if any finite subset  $S \subset \mathbb{N}$  has  $\omega(S) = 1$ .

Fix  $\omega$  a non-principal ultrafilter (existence requires the axiom of choice). Let X be a topological space, and  $x_n \in X$ . Then  $x = \lim_{\omega} x_n$  is the *ultralimit* of  $x_n$  if, for every open neighbourhood U of x,

$$\omega\{n\in\mathbb{N}|x_n\in U\}=1.$$

**Lemma 11** If X is a compact space then every sequence has an ultralimit.

# **Ultraproducts**

Let  $(X_n, d_n, x_n)$  be a sequence of pointed metric spaces. Let

$$Y \subset \prod X_n$$

be the subspace consisting of sequences  $(y_n)$  with  $d_n(x_n, y_n)$  bounded. Then Y inherits a pseudo-metric given by

$$D((y_n),(z_n)) = \lim_{\omega} d_n(x_n,y_n).$$

The *ultraproduct* of the sequence  $(X_n, d_n, x_n)$ , denoted  $(X_\omega, d_\omega)$ , is the associated metric space. It has the following useful properties.

**Lemma 12** Suppose all the  $X_n$  are geodesic. Then so is  $X_{\omega}$ .

Suppose  $T_n$  is a sequence of trees. Then so is  $T_{\omega}$ .

If each  $T_n$  admits a G-action then the induced action on Y descends to  $T_{\omega}$ . Furthermore, a sequence of G-trees converges to its ultralimit in the equivariant Gromov-Hausdorff topology.

It remains to show that  $T_{\omega}$  is non-trivial: then we can pass to the minimal invariant subtree. This is done by carefully choosing the basepoint and scale factor.

Fix a generating set S for G, and define  $\sigma_n$ :  $T_n \to \mathbb{R}$  by

$$\sigma_n(x) = \max_{g \in S} d_n(x, gx).$$

Let  $\delta_n = \inf_{x \in T} \sigma_n(x)$ , and choose  $x_n \in T_n$  to minimize  $\sigma_n$ . Now modify  $T_n$  by dividing the metric by  $\delta_n$ . Let  $t = [(t_n)] \in T_\omega$ . For each  $t_n$  there exists  $g \in S$  with

$$d_n(t_n, gt_n) \ge \sigma_n(x_n) = 1$$

so, by construction, for some  $g \in S$ ,

$$d_{\omega}(t, gt) \geq 1.$$

# Short automorphisms

The first part of the strategy is now complete. If the second part worked, then we could get away without modular automorphisms. The problem is that  $\mathcal{U}$  doesn't cover  $\mathcal{T}(G)$ .

Fix a basis S for G. For  $f: G \to \mathbb{F}$ , define

$$|f| = \max_{g \in S} l(f(s))$$

where l is word length in  $\mathbb{F}$ . A homomorphism f is *short* if

$$|f| < |i_c \circ f \circ \alpha|$$

for all  $c \in \mathbb{F}$  and modular automorphisms  $\alpha$ . The key is the following tricky theorem of Sela.

**Theorem 13** For a sequence of short automorphisms  $f_n: G \to \mathbb{F}$  with  $T_{f_n}$  converging to T, the limit action on T is not faithful.

Part 2 of our strategy now works, after restricting attention to

$$\mathfrak{I}'(G)\subset\mathfrak{I}(G)$$

the closure of the set of G-trees arising from short homomorphisms to  $\mathbb{F}$ . This completes the proof of theorem 6, and so theorem 1.

## **Further directions**

This technique has proved very open to generalization, particularly in describing Hom(G, H) for other groups H.

- Sela has extended his work to cover word hyperbolic groups: groups whose Cayley graphs have uniformly thin triangles.
- Alibegovic has constructed Makanin-Razborov diagrams relative to limit groups.
- Groves is working on a series of papers which would generalize both of these, extending Sela's techniques to groups that are hyperbolic relative to their maximal abelian subgroups.