

Introduction to Rheology of complex fluids

Brief Lecture Notes

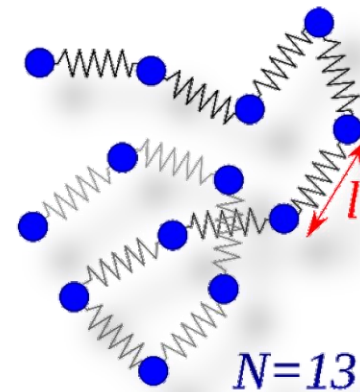
Linear Viscoelasticity

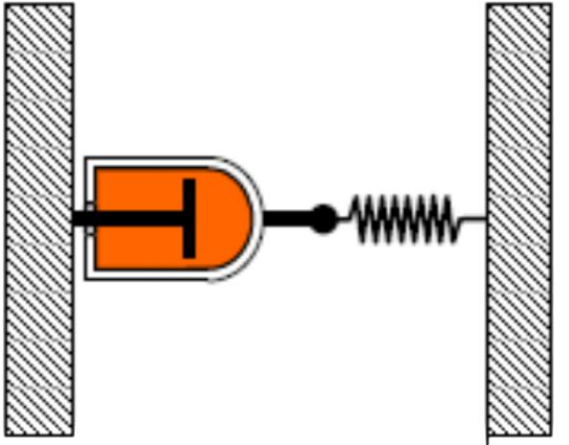




Contents

- Introductory Lecture
- Simple Flows
- Material functions & Rheological Characterization
- Experimental Observations
- Generalized Newtonian Fluids
- **Generalized Linear viscoelastic Fluids**
- Nonlinear Constitutive Models





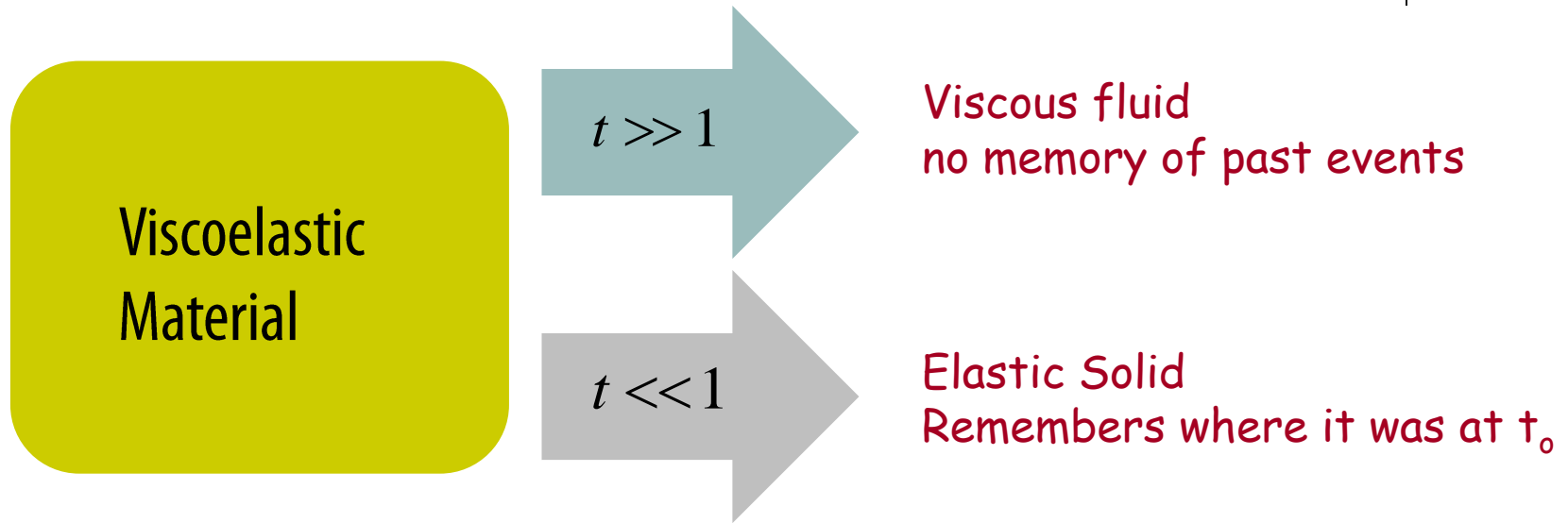
Maxwell Model

- Constitutive modelling is the art and science of finding appropriate tensorial expressions for the stress as a function of the deformation to match observed material behavior
- The Maxwell model is empirical (like Newton's and Hooke's laws) and its validity depends on how well it predicts material behavior

Maxwell Model



Differential approach, based on “additivity” ideas of elasticity, which hold for small deformations



Hook's Law for elastic solids
Valid for infinitesimally small displacements

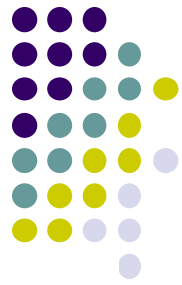
$$\underline{\underline{\tau}}(t) = G \underline{\underline{\gamma}}(t_0, t)$$

Newton's Law for viscous fluids
Valid for arbitrarily large displacement gradients

$$\underline{\underline{\tau}}(t) = \eta \underline{\underline{\dot{\gamma}}}(t)$$

Maxwell Model

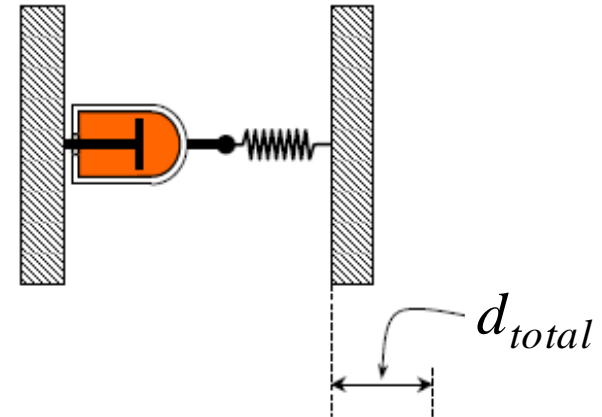
$$\begin{cases} \dot{\gamma}_{xy}(t) = \frac{\partial}{\partial t} \gamma_{xy}(t_o, t) \\ \gamma_{xy}(t_o, t) = \int_{t_o}^t \dot{\gamma}_{xy}(t') dt' \end{cases}$$



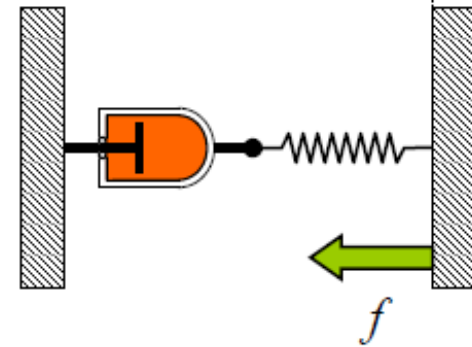
Maxwell model combines the viscous and the elastic behavior in series.

Use of Spring (elastic behavior) and dashpot (fluid behavior) in series.

Initial State:
No Force Imposed



Final State:
Force, f , resist to the displacement



The (small) displacements can be added

The total displacement is: $d_{total} = d_{spring} + d_{dashpot}$

When the resistances are in parallel, the Kelvin-Voigt model is derived

AS

Maxwell Model



The force on the spring:

$$f = G_{sp} d_{spring}$$

The force on the dashpot:

$$f = \mu \frac{d(d_{dash})}{dt}$$

The total
Displacement

$$d_{total} = d_{spring} + d_{dashpot}$$

$$\frac{d(d_{total})}{dt} = \frac{d(d_{spring})}{dt} + \frac{d(d_{dashpot})}{dt}$$

$$\frac{d(d_{total})}{dt} = \frac{1}{G_{sp}} \frac{df}{dt} + \frac{1}{\mu} f$$

$$f + \frac{\mu}{G_{sp}} \frac{df}{dt} = \mu \frac{d(d_{total})}{dt}$$



Maxwell Model

$$f + \frac{\mu}{G_{sp}} \frac{df}{dt} = \mu \frac{d(d_{total})}{dt}$$

In Shear

$$\tau_{yx} + \frac{\eta_o}{G_o} \frac{\partial \tau_{yx}}{\partial t} = \eta_o \dot{\gamma}_{yx}$$

G_o Relaxation Modulus

For all stress comp

$$\tau + \frac{\eta_o}{G_o} \frac{\partial \tau}{\partial t} = \eta_o \dot{\gamma}$$

Two parameters

$$\lambda = \frac{\eta_o}{G_o}$$

Relaxation Time

$$\eta_o$$

Zero-Shear Viscosity

Is this generalization correct?



Integral form of Maxwell Model

Addition of contributions of past events with “fading” memory to predict the stress at the current time:

$$\underline{\underline{\tau}}(t) = \int_{-\infty}^t \left\{ \left(\frac{\eta_o}{\lambda} \right) e^{-(t-t')/\lambda} \right\} \underline{\underline{\dot{\gamma}}}(t') dt' =$$
$$- \int_{-\infty}^t \left\{ \left(\frac{\eta_o}{\lambda^2} \right) e^{-(t-t')/\lambda} \right\} \underline{\underline{\gamma}}(t, t') dt'$$

Two parameters

$$\lambda = \frac{\eta_o}{G_o}$$

Relaxation Time

$$\eta_o$$

Zero-Shear Viscosity

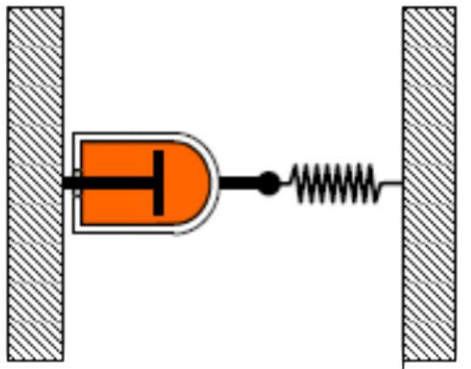
The stress at time t depends on the rate of strain at time t and the rate of strain at all past times t' with a weighting factor that decays exponentially (backwards) in time.

OR

The history of strain at all past times

$$\left\{ \left(\frac{\eta_o}{\lambda^2} \right) e^{-(t-t')/\lambda} \right\}$$

(Fading) Memory function



Maxwell Model Predictions in Rheological Flows



Simple Shear Flow

Kinematics

$$\underline{v}(y,t) = \dot{\zeta}(t) y \underline{e}_x$$

$$\dot{\zeta}(t) = \dot{\gamma}_o = \text{constant}$$

Material
Properties

$$\eta \equiv \frac{\tau_{yx}}{\dot{\gamma}_o}$$

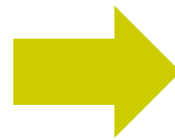
$$\Psi_1 \equiv \frac{\tau_{xx} - \tau_{yy}}{\dot{\gamma}_o^2}$$

$$\Psi_2 \equiv \frac{\tau_{yy} - \tau_{zz}}{\dot{\gamma}_o^2}$$

Steady Shear Flow



$$\underline{\underline{\tau}} + \frac{\eta_o}{G_o} \underbrace{\frac{\partial \underline{\underline{\tau}}}{\partial t}}_0 = \eta_o \dot{\underline{\underline{\gamma}}}$$



$$\underline{\underline{\tau}} = \eta_o \dot{\underline{\underline{\gamma}}}$$

Constitutive
Model

$$\eta \equiv \frac{\tau_{yx}}{\dot{\gamma}_o} = \eta_o$$

Cannot Predict
Shear Thinning

$$\Psi_1 \equiv \frac{\tau_{xx} - \tau_{yy}}{\dot{\gamma}_o^2} = 0 \quad \Psi_2 \equiv \frac{\tau_{yy} - \tau_{zz}}{\dot{\gamma}_o^2} = 0$$

Cannot Predict
Normal Stresses



Start up of Simple Shear Flow

Kinematics

$$\underline{v}(y, t) = \dot{\zeta}(t) y \underline{e}_x$$

$$\dot{\zeta}(t) = \dot{\gamma}_o H(t)$$

Unidirectional Flow

$$\dot{\gamma} = \begin{pmatrix} 0 & \dot{\zeta}(t) & 0 \\ \dot{\zeta}(t) & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

Material Properties

$$\eta^+ \equiv \frac{\tau_{yx}}{\dot{\gamma}_o}$$

$$\Psi_1^+ \equiv \frac{\tau_{xx} - \tau_{yy}}{\dot{\gamma}_o^2}$$

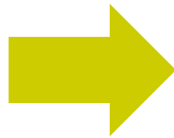
$$\Psi_2^+ \equiv \frac{\tau_{yy} - \tau_{zz}}{\dot{\gamma}_o^2}$$

Start up of Simple Shear Flow



$$\tau + \frac{\eta_o}{G_o} \frac{\partial \tau}{\partial t} = \eta_o \dot{\gamma}$$

$$\tau(t=0) = 0$$



Constitutive Model

$$\tau_{xx} + \frac{\eta_o}{G_o} \frac{\partial \tau_{xx}}{\partial t} = \eta_o \dot{\gamma}_{xx} = 0 \quad \Rightarrow \quad \tau_{xx} = 0$$

$$\tau_{yy} + \frac{\eta_o}{G_o} \frac{\partial \tau_{yy}}{\partial t} = \eta_o \dot{\gamma}_{yy} = 0 \quad \Rightarrow \quad \tau_{yy} = 0$$

$$\tau_{zz} + \frac{\eta_o}{G_o} \frac{\partial \tau_{zz}}{\partial t} = \eta_o \dot{\gamma}_{zz} = 0 \quad \Rightarrow \quad \tau_{zz} = 0$$

$$\tau_{yx} + \frac{\eta_o}{G_o} \frac{\partial \tau_{yx}}{\partial t} = \eta_o \dot{\gamma}_o H(t)$$

$$\tau_{yx}(t) = \int_{-\infty}^t \left(\frac{\eta_o}{\lambda} \right) e^{-(t-t')/\lambda} \dot{\gamma}_o H(t') dt' = \left(\frac{\eta_o}{\lambda} \right) \dot{\gamma}_o \int_0^t e^{-(t-t')/\lambda} H(t') dt'$$

$$= \left(\frac{\eta_o}{\lambda} \right) \dot{\gamma}_o \int_0^t e^{-(t-t')/\lambda} dt' \quad \overset{u = \frac{t-t'}{\lambda}}{=} \left(\frac{\eta_o}{\lambda} \right) \dot{\gamma}_o \int_{-t/\lambda}^0 e^u \lambda du = \eta_o \dot{\gamma}_o e^u \Big|_{-t/\lambda}^0 = \eta_o \dot{\gamma}_o (1 - e^{-t/\lambda})$$

Start up of Simple Shear Flow



$$\tau_{yx}(t) = \eta_o \dot{\gamma}_o (1 - e^{-t/\lambda})$$

$$\eta^+ \equiv \frac{\tau_{yx}}{\dot{\gamma}_o} = \eta_o (1 - \exp(-t/\lambda))$$

It can predict the gradual increase of shear stress

$$\Psi_1^+ \equiv \frac{\tau_{xx} - \tau_{yy}}{\dot{\gamma}_o^2} = 0 \quad \Psi_2^+ \equiv \frac{\tau_{yy} - \tau_{zz}}{\dot{\gamma}_o^2} = 0$$

Cannot Predict
Normal Stresses

Step strain Test



Kinematics

$$\underline{v}(y, t) = \dot{\zeta}(t) y \underline{e}_x$$

$$\dot{\zeta}(t) = \lim_{\varepsilon \rightarrow 0} \begin{cases} 0 & t < 0 \\ \dot{\gamma}_o, & 0 \leq t < \varepsilon \\ 0 & t \geq \varepsilon \end{cases} = \dot{\gamma}_o \delta^+(t)$$

$$\dot{\gamma}_o \varepsilon = \text{constant} = \gamma_o$$

Unidirectional
Flow

Material
Properties

$$G(t, \gamma_o) \equiv \frac{\tau_{yx}}{\gamma_o}$$

$$G_{\Psi_1} \equiv \frac{\tau_{xx} - \tau_{yy}}{\gamma_o^2}$$

$$G_{\Psi_2} \equiv \frac{\tau_{yy} - \tau_{zz}}{\gamma_o^2}$$

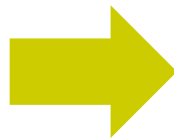
Relaxation Modulus

Step strain Test



$$\tau + \frac{\eta_o}{G_o} \frac{\partial \tau}{\partial t} = \eta_o \dot{\gamma}$$

$$\tau(t=0) = 0$$



$$\left\{ \begin{array}{l} \tau_{xx} + \frac{\eta_o}{G_o} \frac{\partial \tau_{xx}}{\partial t} = \eta_o \underbrace{\dot{\gamma}_{xx}}_0 = 0 \quad \longrightarrow \quad \tau_{xx} = 0 \\ \tau_{yy} + \frac{\eta_o}{G_o} \frac{\partial \tau_{yy}}{\partial t} = \eta_o \underbrace{\dot{\gamma}_{yy}}_0 = 0 \quad \longrightarrow \quad \tau_{yy} = 0 \\ \tau_{zz} + \frac{\eta_o}{G_o} \frac{\partial \tau_{zz}}{\partial t} = \eta_o \underbrace{\dot{\gamma}_{zz}}_0 = 0 \quad \longrightarrow \quad \tau_{zz} = 0 \\ \tau_{yx} + \frac{\eta_o}{G_o} \frac{\partial \tau_{yx}}{\partial t} = \eta_o \dot{\gamma}_o \delta^+(t) \end{array} \right.$$

$$\longrightarrow \tau_{yx}(t) = \int_{-\infty}^t \left(\frac{\eta_o}{\lambda} \right) e^{-(t-t')/\lambda} \dot{\gamma}_o \delta(t') dt' = \left(\frac{\eta_o}{\lambda} \right) \dot{\gamma}_o \int_0^t e^{-(t-t')/\lambda} \delta(t') dt' = \left(\frac{\eta_o}{\lambda} \right) \dot{\gamma}_o e^{-t/\lambda}$$

Step strain Test



$$\tau_{yx}(t) = \frac{\eta_o}{\lambda} \dot{\gamma}_o e^{-t/\lambda}$$

$$G(t) \equiv \frac{\tau_{yx}}{\gamma_o} = \frac{\eta_o}{\underbrace{\lambda}_{G_o}} \exp(-t/\lambda)$$

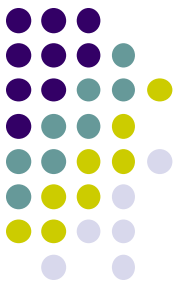
Predicts realistic behavior
for the Relaxation Modulus

$$G_o = G(t = 0)$$

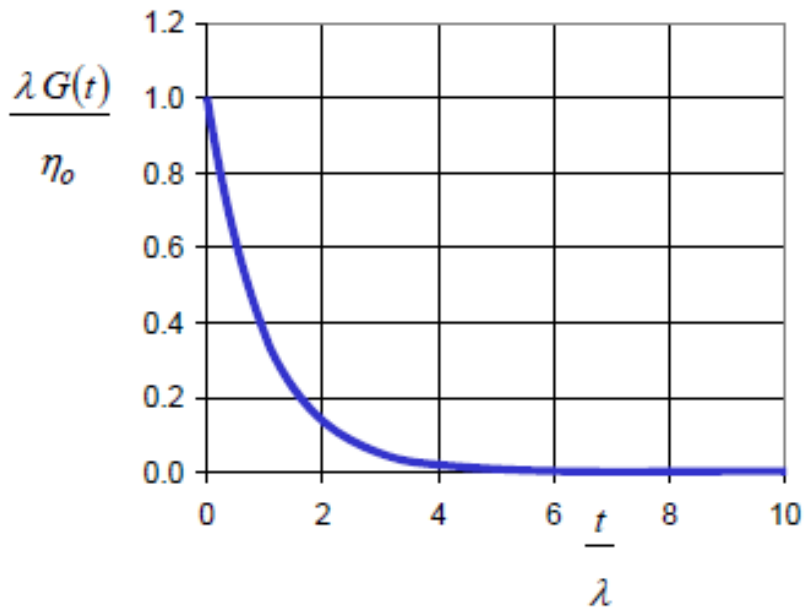
$$G_{\Psi_1} \equiv \frac{\tau_{xx} - \tau_{yy}}{\gamma_o^2} = 0 \quad G_{\Psi_2} \equiv \frac{\tau_{yy} - \tau_{zz}}{\gamma_o^2} = 0$$

Cannot Predict
Normal Stresses

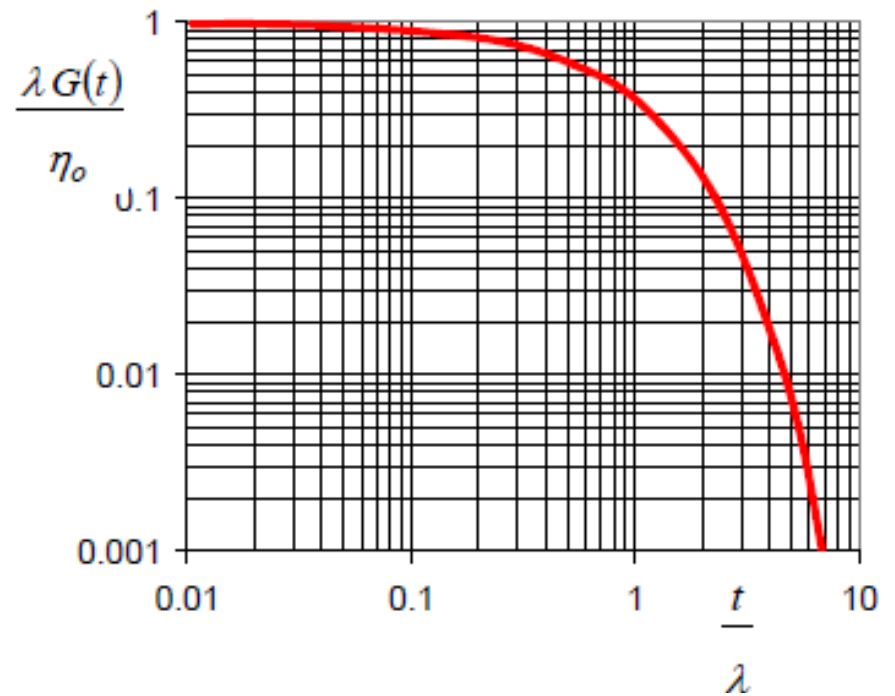
Relaxation Modulus



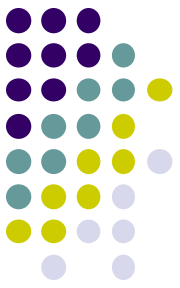
Linear Scale



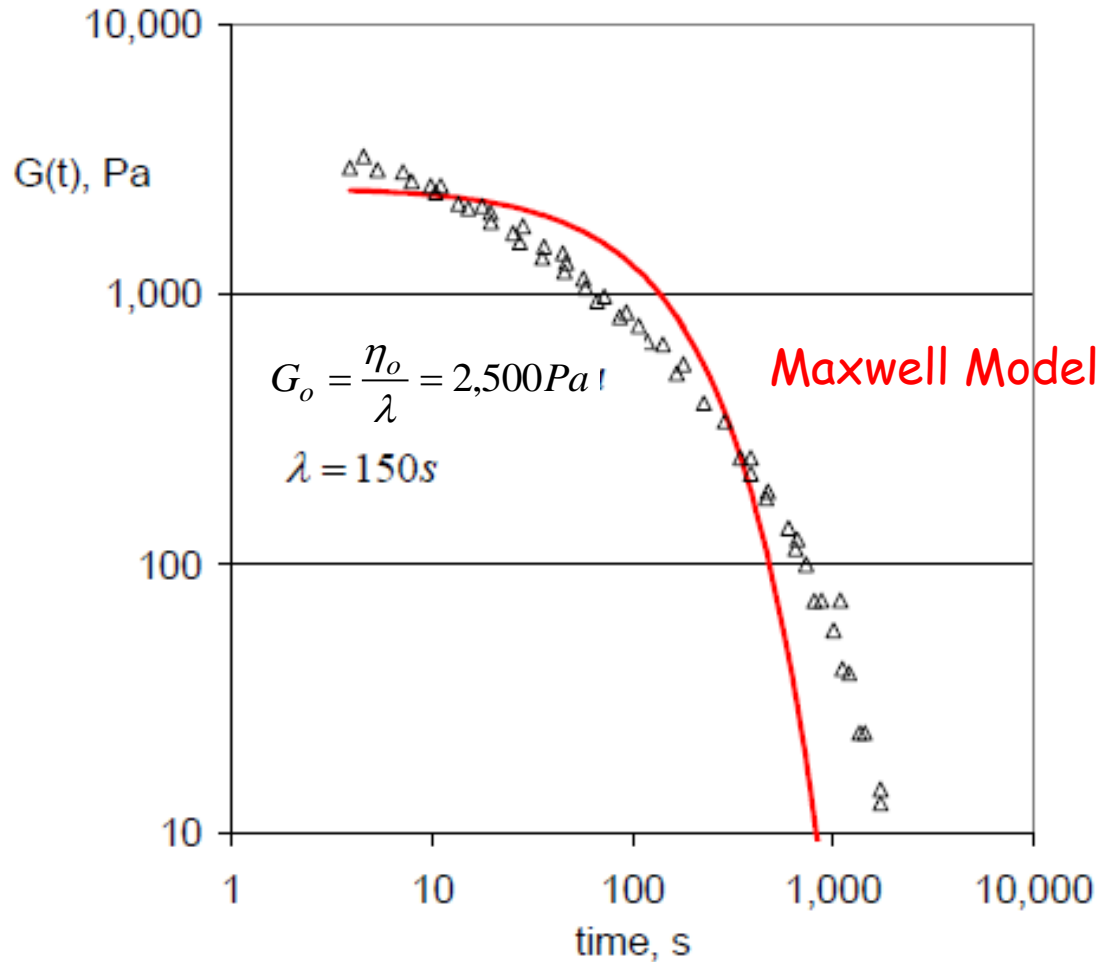
Log- Scale

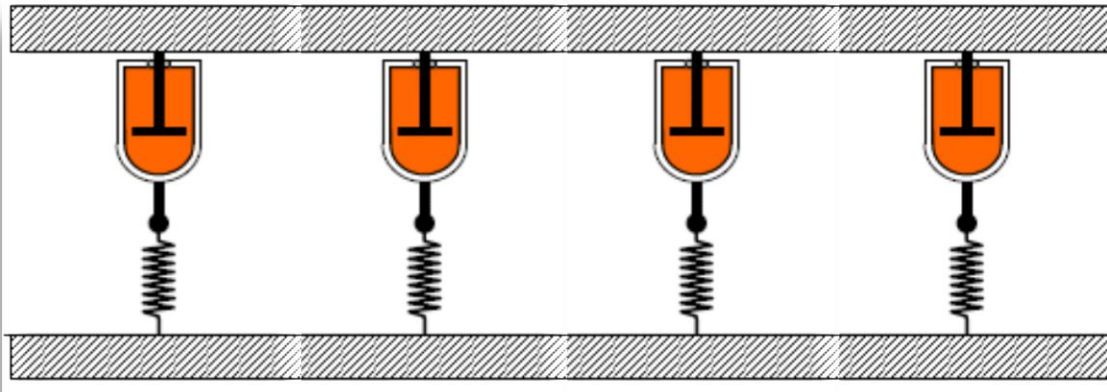


Relaxation Modulus



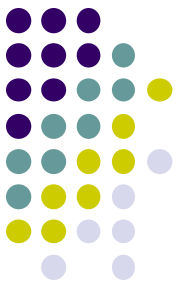
Comparison with Experiments for polystyrene solution, $M_w = 10^6$, again points to the need for model improvement





Generalized
Maxwell model
for multiple
relaxation times

Superposition of Maxwell Models with different relaxation times $\lambda_1 > \lambda_2 > \dots \lambda_N$



$$\tau_{(k)}(t) = \int_{-\infty}^t \left(\frac{\eta_k}{\lambda_k} \right) e^{-(t-t')/\lambda_k} \dot{\gamma}(t') dt'$$

$$\tau(t) = \sum_{k=1}^N \tau_{(k)}(t)$$



$$\tau(t) = \int_{-\infty}^t \sum_{k=1}^N \left[\left(\frac{\eta_k}{\lambda_k} \right) e^{-(t-t')/\lambda_k} \right] \dot{\gamma}(t') dt' =$$

$$- \int_{-\infty}^t \sum_{k=1}^N \left[\left(\frac{\eta_k}{\lambda_k^2} \right) e^{-(t-t')/\lambda_k} \right] \gamma(t, t') dt'$$

2N unknowns
 $\{\eta_k, \lambda_k\}$

Steady Simple & Step Shear



Steady Simple Shear

$$\eta \equiv \frac{\tau_{yx}}{\dot{\gamma}_o} = \sum_{k=1}^N \eta_k$$

Cannot Predict
shear thinning

$$\Psi_1 \equiv \frac{\tau_{xx} - \tau_{yy}}{\dot{\gamma}_o^2} = 0 \quad \Psi_2 \equiv \frac{\tau_{yy} - \tau_{zz}}{\dot{\gamma}_o^2} = 0$$

Cannot predict
normal stresses

Step Shear

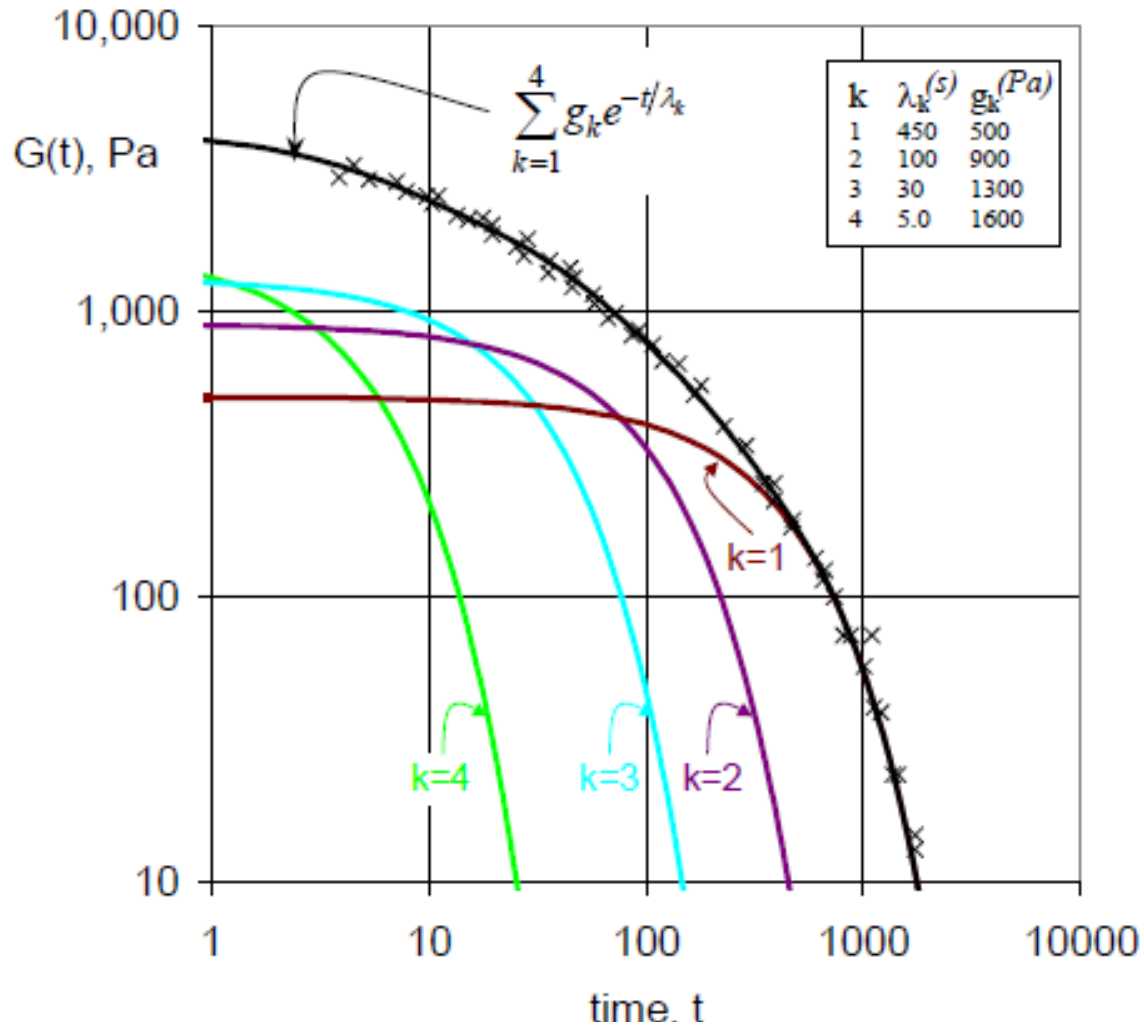
$$G(t) \equiv \sum_{k=1}^N \frac{\eta_k}{\lambda_k} \exp(-t / \lambda_k)$$

Can describe relaxation for
more extended periods of time

$$G_{\Psi_1} \equiv \frac{\tau_{xx} - \tau_{yy}}{\dot{\gamma}_o^2} = 0 \quad G_{\Psi_2} \equiv \frac{\tau_{yy} - \tau_{zz}}{\dot{\gamma}_o^2} = 0$$

Comparison with Experiments

Adding four Maxwell modes improves linear data



SAOS



Kinematics $\underline{v}(y,t) = \dot{\zeta}(t) y \underline{e}_x$

Unidirectional
Flow

$$\dot{\zeta}(t) = \dot{\gamma}_o \cos(\omega t) \quad ; \quad \gamma_o = \dot{\gamma}_o / \omega$$

$$\dot{\gamma} = \begin{pmatrix} 0 & \dot{\zeta}(t) & 0 \\ \dot{\zeta}(t) & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

**Material
Properties**

$$\frac{\tau_{yx}(\gamma_o, t)}{\gamma_o} = G' \sin(\omega t) + G'' \cos(\omega t)$$

$$G'(\omega) = \frac{\tau_o}{\dot{\gamma}_o} \cos(\delta)$$

$$G''(\omega) = \frac{\tau_o}{\dot{\gamma}_o} \sin(\delta)$$

Storage Modulus

Loss Modulus

SAOS

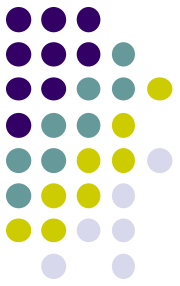
Predictions of GMM

GMM

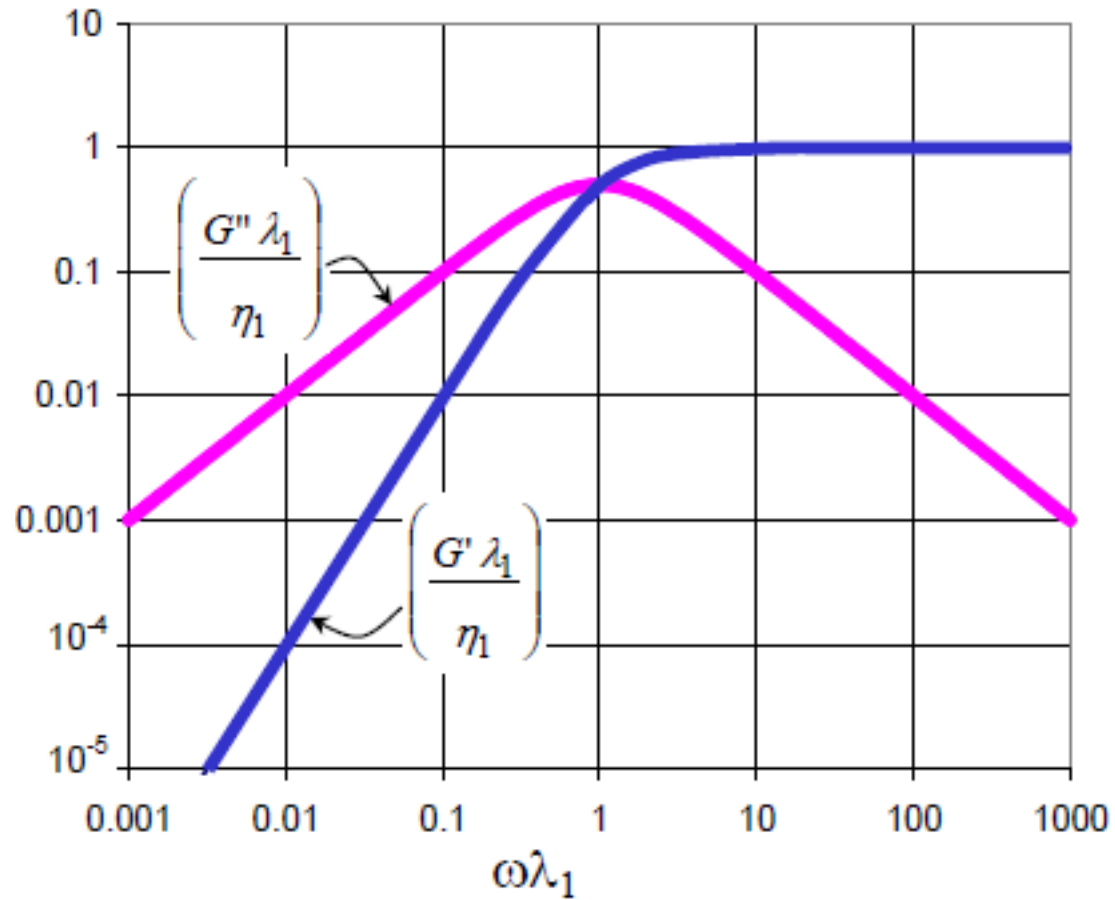
$$\tau(t) = \int_{-\infty}^t \sum_{k=1}^N \left[\left(\frac{\eta_k}{\lambda_k} \right) e^{-(t-t')/\lambda_k} \right] \dot{\gamma}(t') dt'$$

$$G'(\omega) = \sum_{k=1}^N \frac{\eta_k \lambda_k \omega^2}{1 + (\lambda_k \omega)^2}$$

$$G''(\omega) = \sum_{k=1}^N \frac{\eta_k \omega}{1 + (\lambda_k \omega)^2}$$

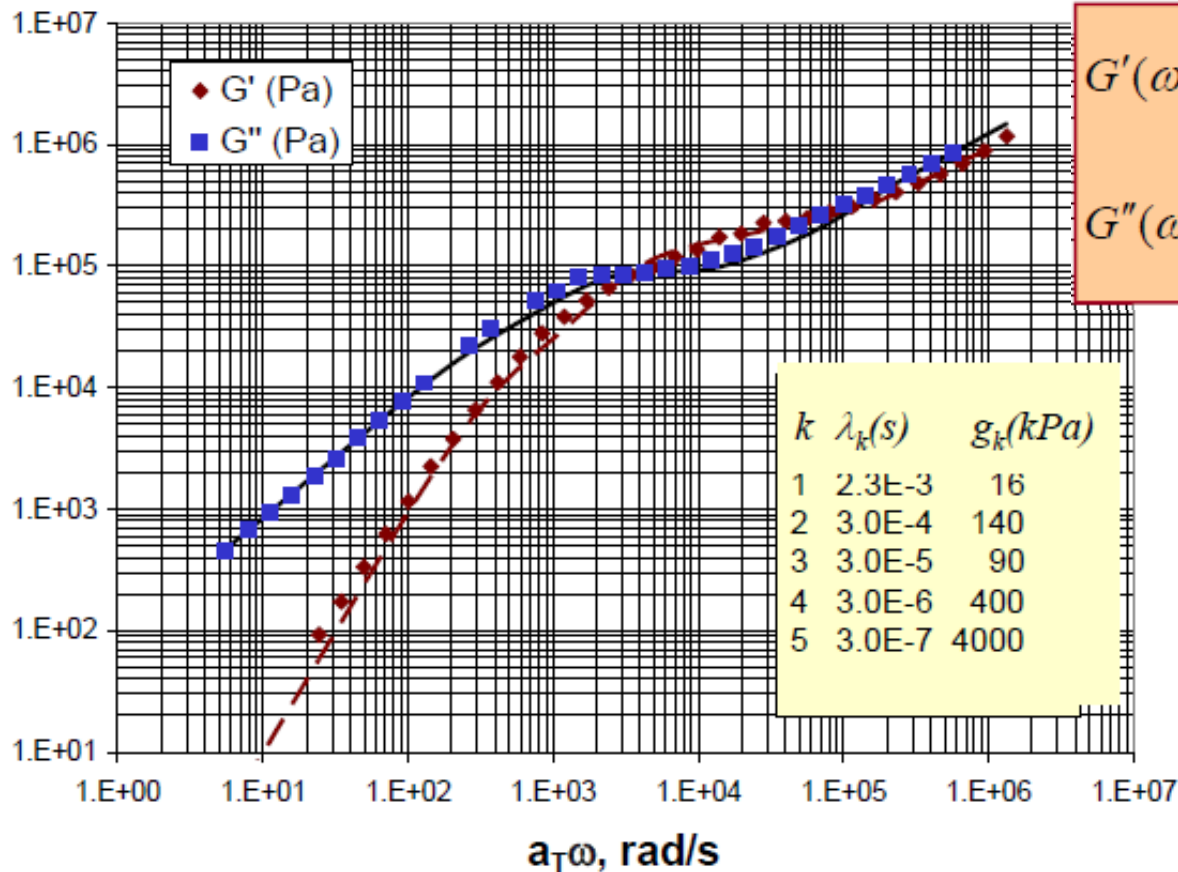


SAOS prediction of the Maxwell model for a single relaxation time



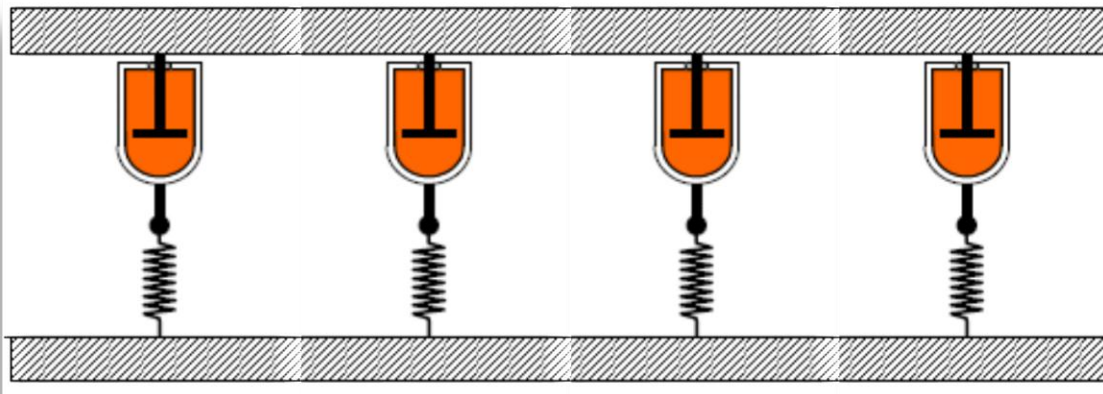


Comparison with experiments of GMM for multiple relaxation times (5 modes)



$$G'(\omega) = \sum_{k=1}^N \frac{\eta_k \lambda_k \omega^2}{1 + (\lambda_k \omega)^2}$$

$$G''(\omega) = \sum_{k=1}^N \frac{\eta_k \omega}{1 + (\lambda_k \omega)^2}$$

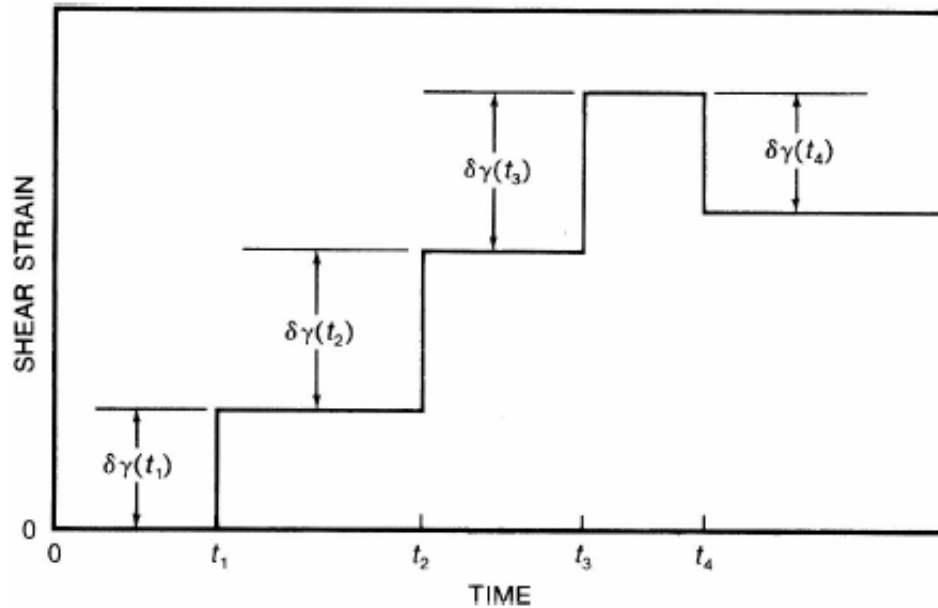


General linear viscoelastic model



Boltzmann Superposition

The experiment of multiple step changes in shear



Consider a sequence of small deformations where their response is linear.

For the 1st deformation the stress is:

$$\tau_{yx}(t) = G(t-t_1) \delta\gamma_{yx}(t_1) \quad t_1 < t < t_2$$

For the 2nd deformation the stress is:

$$\tau_{yx}(t) = G(t-t_1) \delta\gamma_{yx}(t_1) + G(t-t_2) \delta\gamma_{yx}(t_2) \quad t_2 < t < t_3$$

After N deformations:

$$\tau_{yx}(t) = \sum_{i=1}^N G(t-t_i) \delta\gamma_{yx}(t_i) \quad t_N < t$$

General linear viscoelastic model



Continuum
Consideration:

$$\tau_{yx}(t) = \int_0^{\gamma_{yx}(t)} G(t-t') d\gamma_{yx}(t')$$

Change of
Variables

$$d\gamma_{yx}(t') = \dot{\gamma}_{yx}(t') dt'$$

$$\tau_{yx}(t) = \int_{-\infty}^t G(t-t') \dot{\gamma}_{yx}(t') dt'$$

In practise

$$\tau_{yx}(t) = \int_0^t G(t-t') \dot{\gamma}_{yx}(t') dt'$$

It reminds us that we have to take into account the history of the material.

General linear viscoelastic model



Has factorized structure: Nature of fluid * Nature of flow, $\underline{\underline{\gamma}}, \underline{\underline{\dot{\gamma}}}$

For all stress components:

$$\underline{\underline{\tau}}(t) = \int_{-\infty}^t G(t-t') \underline{\underline{\dot{\gamma}}}(t') dt' = \int_{-\infty}^t M(t-t') \underline{\underline{\gamma}}(t, t') dt'$$

$$G(t-t')$$

:Relaxation Modulus

Nature of fluid

$$M(t-t') = \partial G(t-t') / \partial t' \quad \text{:Memory Function}$$

In practice:

$$\underline{\underline{\tau}}(t) = \int_0^t G(t-t') \underline{\underline{\dot{\gamma}}}(t') dt'$$

Steady Shear Flow



Kinematics

$$\underline{v}(y, t) = \dot{\zeta}(t) y \underline{e}_x$$

Unidirectional
Flow

$$\dot{\zeta}(t) = \dot{\gamma}_o = \text{constant}$$

Material
Properties

$$\dot{\gamma} = \begin{pmatrix} 0 & \dot{\zeta}(t) & 0 \\ \dot{\zeta}(t) & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

$$\eta \equiv \frac{\tau_{yx}}{\dot{\gamma}_o}$$

$$\Psi_1 \equiv \frac{\tau_{xx} - \tau_{yy}}{\dot{\gamma}_o^2}$$

$$\Psi_2 \equiv \frac{\tau_{yy} - \tau_{zz}}{\dot{\gamma}_o^2}$$

Steady Shear Flow



$$\tau(t) = \int_{-\infty}^t G(t-t') \dot{\gamma}(t') dt'$$



Constitutive Relation

$$\tau_{yx}(t) = \int_{-\infty}^t G(t-t') \dot{\gamma}_{yx}(t') dt'$$

$$\tau_{ii}(t) = 0$$

$$\Psi_1 \equiv \frac{\tau_{xx} - \tau_{yy}}{\dot{\gamma}_o^2} = 0 \quad \Psi_2 \equiv \frac{\tau_{yy} - \tau_{zz}}{\dot{\gamma}_o^2} = 0$$

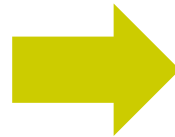
Cannot predict
normal stresses

Steady Shear Flow



Constitutive Relation

$$\tau_{yx}(t) = \int_{-\infty}^t G(t-t') \dot{\gamma}_{yx}(t') dt'$$



$$\begin{aligned}\tau_{yx}(t) &= \int_{-\infty}^t G(t-t') \dot{\gamma}_o dt' \\ &= \dot{\gamma}_o \int_{-\infty}^t G(t-t') dt'\end{aligned}$$

With change of variables

$$s = t - t' \qquad ds = d(t - t') = -dt'$$

$$t' = -\infty \Rightarrow s = \infty \qquad t' = t \Rightarrow s = 0$$

Thus:

$$\tau_{yx}(t) = \dot{\gamma}_o \int_0^{\infty} G(s) ds$$

In the LVE

The viscosity is:

$$\eta \equiv \frac{\tau_{yx}}{\dot{\gamma}_o} = \int_0^{\infty} G(s) ds \rightarrow \eta_o$$

Uniaxial Elongation



Kinematics

$$\underline{\dot{\gamma}} = \underline{\nabla v} + (\underline{\nabla v})^T = 2\dot{\epsilon}_o \begin{pmatrix} -1/2 & 0 & 0 \\ 0 & -1/2 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

Constitutive Model

$$\underline{\tau}(t) = \int_{-\infty}^t G(t-t') \underline{\dot{\gamma}}(t') dt'$$

With change of variables

$$s = t - t' \quad ds = d(t - t') = -dt'$$

$$t' = -\infty \Rightarrow s = \infty \quad t' = t \Rightarrow s = 0$$

$$\underline{\tau}(s + t') = 2\dot{\epsilon}_o \int_0^s G(s) \begin{pmatrix} -1/2 & 0 & 0 \\ 0 & -1/2 & 0 \\ 0 & 0 & 1 \end{pmatrix} ds$$

Extensional Stress

$$\tau_E = \tau_{zz} - \tau_{xx}$$



Start-up of Steady Shear

Kinematics

$$\underline{v}(y,t) = \dot{\zeta}(t) y \underline{e}_x$$

Unidirectional
Flow

$$\dot{\zeta}(t) = \dot{\gamma}_o H(t)$$

$$\dot{\gamma} = \begin{pmatrix} 0 & \dot{\zeta}(t) & 0 \\ \dot{\zeta}(t) & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

Material
Properties

$$\eta^+ \equiv \frac{\tau_{yx}}{\dot{\gamma}_o}$$

$$\Psi_1^+ \equiv \frac{\tau_{xx} - \tau_{yy}}{\dot{\gamma}_o^2}$$

$$\Psi_2^+ \equiv \frac{\tau_{yy} - \tau_{zz}}{\dot{\gamma}_o^2}$$

Stress Growth
Coefficient



Start-up of Steady Shear

$$\underline{\tau}(t) = \int_{-\infty}^t G(t-t') \dot{\gamma}(t') dt'$$



Constitutive Model

$$\tau_{yx}(t) = \int_{-\infty}^t G(t-t') \dot{\gamma}_{yx}(t') dt'$$

$$\tau_{ii}(t) = 0$$

$$\Psi_1^+ \equiv \frac{\tau_{xx} - \tau_{yy}}{\dot{\gamma}_o^2} = 0 \quad \Psi_2^+ \equiv \frac{\tau_{yy} - \tau_{zz}}{\dot{\gamma}_o^2} = 0$$

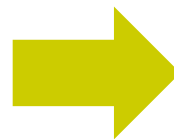
Cannot predict
normal stresses



Start-up of Steady Shear

Constitutive Model

$$\tau_{yx}(t) = \int_{-\infty}^t G(t-t') \dot{\gamma}_{yx}(t') dt'$$



$$\begin{aligned} \tau_{yx}(t) &= \int_{-\infty}^t G(t-t') \dot{\gamma}_o H(t') dt' \\ &= \dot{\gamma}_o \int_0^t G(t-t') dt' \end{aligned}$$

With change of variables

$$s = t - t'$$

$$ds = d(t - t') = -dt'$$

$$t' = 0 \Rightarrow s = t$$

$$t' = t \Rightarrow s = 0$$

Thus:

$$\tau_{yx}(t) = \dot{\gamma}_o \int_0^t G(s) ds$$

The viscosity is:

$$\eta^+ \equiv \frac{\tau_{yx}}{\dot{\gamma}_o} = \int_0^t G(s) ds$$



Cessation of Steady Shear

Kinematics

$$\underline{v}(y,t) = \dot{\zeta}(t) y \underline{e}_x$$

Unidirectional
Flow

$$\dot{\zeta}(t) = \dot{\gamma}_o H(-t)$$

$$\dot{\gamma} = \begin{pmatrix} 0 & \dot{\zeta}(t) & 0 \\ \dot{\zeta}(t) & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

Material
Properties

$$\eta^- \equiv \frac{\tau_{yx}}{\dot{\gamma}_o}$$

$$\Psi_1^- \equiv \frac{\tau_{xx} - \tau_{yy}}{\dot{\gamma}_o^2}$$

$$\Psi_2^- \equiv \frac{\tau_{yy} - \tau_{zz}}{\dot{\gamma}_o^2}$$

Stress cessation
Coefficient



Cessation of Steady Shear

$$\underline{\tau}(t) = \int_{-\infty}^t G(t-t') \dot{\underline{\gamma}}(t') dt'$$



Constitutive Model

$$\tau_{yx}(t) = \int_{-\infty}^t G(t-t') \dot{\gamma}_{yx}(t') dt'$$

$$\tau_{ii}(t) = 0$$

$$\Psi_1^- \equiv \frac{\tau_{xx} - \tau_{yy}}{\dot{\gamma}_o^2} = 0 \quad \Psi_2^- \equiv \frac{\tau_{yy} - \tau_{zz}}{\dot{\gamma}_o^2} = 0$$

Cannot predict
normal stresses



Cessation of Steady Shear

Constitutive Model

$$\tau_{yx}(t) = \int_{-\infty}^t G(t-t') \dot{\gamma}_{yx}(t') dt' \quad \longrightarrow \quad \begin{aligned} \tau_{yx}(t) &= \int_{-\infty}^t G(t-t') \dot{\gamma}_o H(-t') dt' \\ &= \dot{\gamma}_o \int_{-\infty}^0 G(t-t') dt' \end{aligned}$$

With Change of Variables

$$\begin{aligned} s &= t - t' & ds &= d(t - t') = -dt' \\ t' = -\infty &\Rightarrow s = \infty & t' = t &\Rightarrow s = 0 \end{aligned}$$

Hence:

$$\tau_{yx}(t) = \dot{\gamma}_o \int_t^{\infty} G(s) ds$$

The viscosity is

$$\eta^- \equiv \frac{\tau_{yx}}{\dot{\gamma}_o} = \int_t^{\infty} G(s) ds$$



The Linear Viscoelastic Model

Differential form of the Maxwell model

$$\tau + \frac{\eta_o}{G} \frac{\partial \tau}{\partial t} = \eta_o \dot{\gamma}$$

Integral form of the Maxwell model

$$\tau(t) = \int_{-\infty}^t \left(\frac{\eta_o}{\lambda} \right) e^{-(t-t')/\lambda} \dot{\gamma}(t') dt'$$

Generalized Maxwell model (N-Modes)

$$\tau(t) = \int_{-\infty}^t \sum_{k=1}^N \left[\left(\frac{\eta_k}{\lambda_k} \right) e^{-(t-t')/\lambda_k} \right] \dot{\gamma}(t') dt'$$

General Viscoelastic Model

$$\tau(t) = \int_{-\infty}^t G(t-t') \dot{\gamma}(t') dt'$$



Pros & Cons of GLVE Models

Pros

- The first set of constitutive relations with “memory”
- Can predict SAOS & Step Change Flows well
- Easy Calculations
- Can approximate start-up and cessation flows

Cons

- Predict Constant shear viscosity (no shear thinning, small strain rates).
- Assume that strains can be added (small strains)
- Like in generalized Newtonian models, stresses are proportional to strain rates. Hence they cannot predict Normal Stresses in shear flow.
- Their predictions are not frame-invariant!

Frame Invariance



The rotating coordinate system is related to the Cartesian one via:

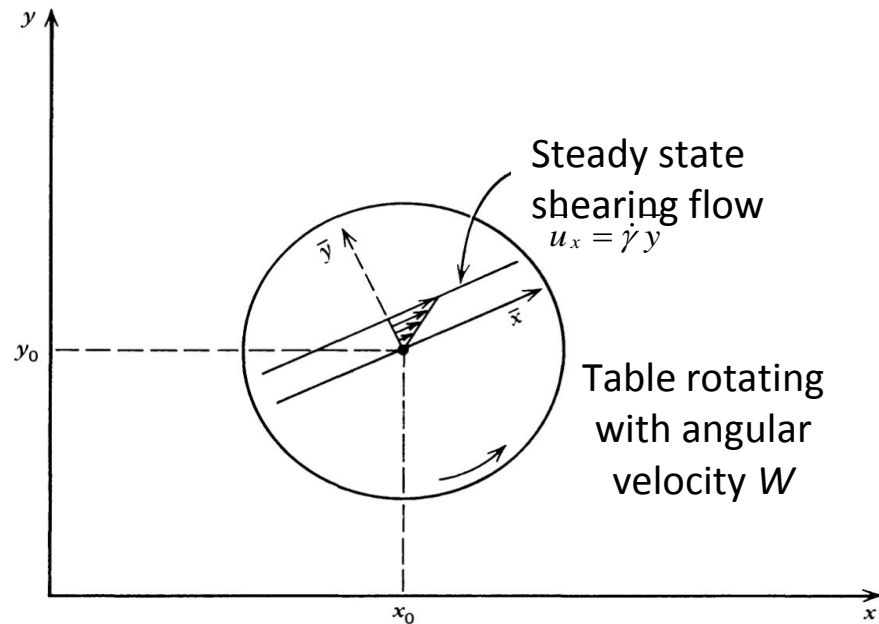
$$\begin{cases} \bar{x} = (x - x_o) \cos(Wt) + (y - y_o) \sin(Wt) \\ \bar{y} = -(x - x_o) \sin(Wt) + (y - y_o) \cos(Wt) \end{cases}$$

Constant velocity is applied on the upper plate of a Couette device:

$$\bar{u}_x = \dot{\gamma} \bar{y} \quad \text{where} \quad \dot{\gamma} \ll 1$$

The rate of strain tensor based on the observer xyz-system is:

$$\underline{\underline{\dot{\gamma}}} = \begin{pmatrix} -\sin(2Wt) & \cos(2Wt) & 0 \\ \cos(2Wt) & \sin(2Wt) & 0 \\ 0 & 0 & 0 \end{pmatrix} \dot{\gamma} \quad \underline{\underline{\tau}} = -\int_0^\infty G(s) \underline{\underline{\dot{\gamma}}} ds = -\dot{\gamma} \int_0^\infty G(s) \begin{pmatrix} -\sin(2W(t-s)) & \cos(2W(t-s)) & 0 \\ \cos(2W(t-s)) & \sin(2W(t-s)) & 0 \\ 0 & 0 & 0 \end{pmatrix} ds$$



The integral form of the GLVM stress tensor is

Remarks and conclusions



- The stress tensor depends on the rotation velocity of the moving coordinate system!!!
- The zero-shear viscosity for $t=0$ is:

$$\tau_{xy} = -\eta_o \dot{\gamma} = -\dot{\gamma} \int_0^{\infty} G(s) \cos(2Ws) ds \Rightarrow \eta_o = \int_0^{\infty} G(s) \cos(2Ws) ds$$

Hence, it depends on the angular velocity!!!

- Also, elastic materials are analyzed under the Lagrangian framework.
Cause? The generalization of Maxwell's equation to the tensorial form.

Thus, for viscoelastic materials, which are partially elastic, we need a better mathematical description to study them in the Eulerian framework.

Solution ?



Objective time derivatives

SAOS



Kinematics $\underline{v}(y,t) = \dot{\zeta}(t) y \underline{e}_x$

$$\dot{\zeta}(t) = \dot{\gamma}_o \cos(\omega t) \quad ; \quad \gamma_o = \dot{\gamma}_o / \omega$$

Unidirectional
Flow

**Material
Properties**

$$\underline{\dot{\gamma}} = \begin{pmatrix} 0 & \dot{\zeta}(t) & 0 \\ \dot{\zeta}(t) & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

$$\frac{\tau_{yx}(\gamma_o, t)}{\dot{\gamma}_o} = G' \sin(\omega t) + G'' \cos(\omega t)$$

$$G'(\omega) = \frac{\tau_o}{\dot{\gamma}_o} \cos(\delta)$$

Storage Modulus

$$G''(\omega) = \frac{\tau_o}{\dot{\gamma}_o} \sin(\delta)$$

Loss Modulus

SAOS

GVLE Predictions



$$\underline{\tau(t)} = \int_{-\infty}^t G(t-t') \underline{\dot{\gamma}(t')} dt'$$

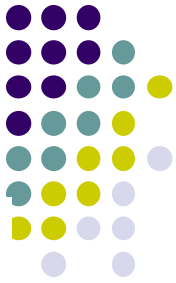
$$G'(\omega) = \omega \int_0^{\omega} G(s) \sin(\omega s) ds$$

$$G''(\omega) = \omega \int_0^{\omega} G(s) \cos(\omega s) ds$$

$$J_s^o = \lim_{\omega \rightarrow 0} \left(\frac{G'(\omega)}{(G''(\omega))^2} \right)$$

Compliance in Steady Flow

SAOS



RC-3 polybutadiene $M_w = 940,000$, $M_w/M_n < 1.1$, $T_g = -99^\circ\text{C}$

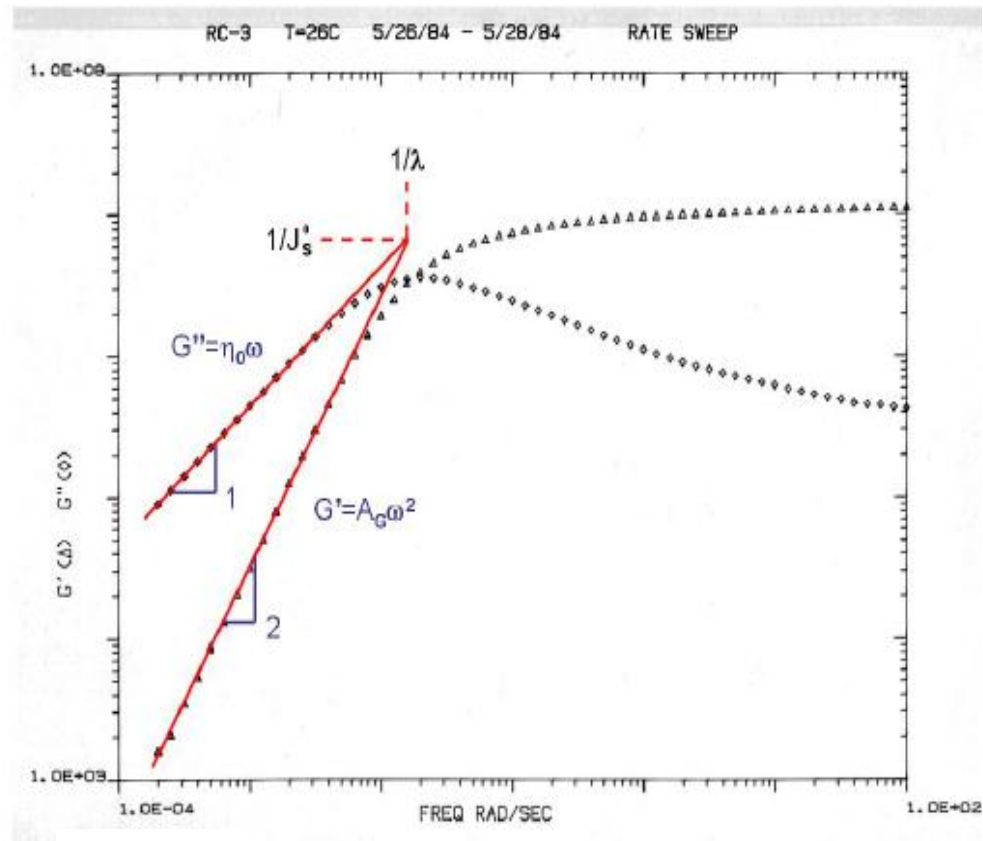
$$\eta_0 = \lim_{\omega \rightarrow 0} \left(\frac{G''(\omega)}{\omega} \right) = \lim_{\omega \rightarrow 0} (\eta'(\omega))$$

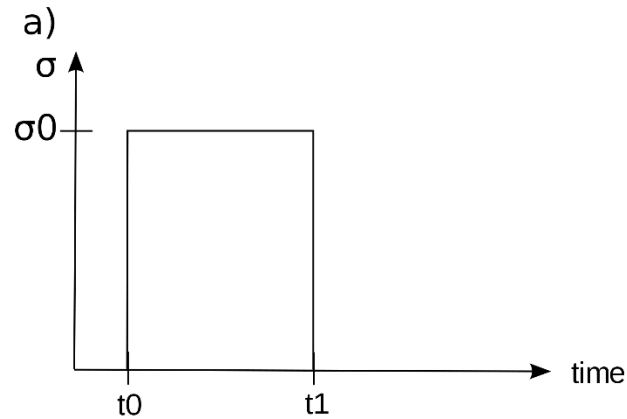
$$\eta_0 = \frac{2}{\pi} \int_{-\infty}^{\infty} \frac{G'(\omega)}{\omega} d(\ln(\omega))$$

$$G_N^o = \frac{2}{\pi} \int_{-\infty}^{\infty} G''(\omega) d(\ln(\omega))$$

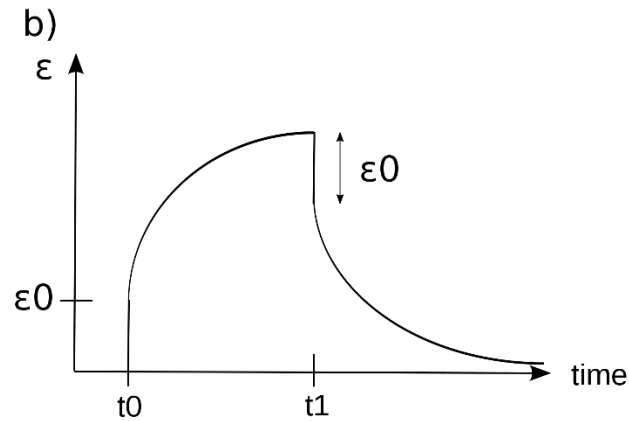
$$A_G \equiv \lim_{\omega \rightarrow 0} \left(\frac{G'(\omega)}{\omega^2} \right) = \int_0^{\infty} G(s) ds$$

$$A_G \equiv J_s^o \eta_o^2$$





End of lecture



SAOS



Proof that:

$$A_G \equiv J_s^o \eta_o^2$$

$$A_G \equiv \lim_{\omega \rightarrow 0} \left(\frac{G'(\omega)}{\omega^2} \right) = \int_0^\infty G(s) s ds$$

$$\lim_{\omega \rightarrow 0} (\sin(\omega s)) = \omega s$$

$$G'(\omega) = \omega \int_0^\infty G(s) \sin(\omega s) ds$$

$$A_G \equiv \lim_{\omega \rightarrow 0} \left(\frac{G'(\omega)}{\omega^2} \right) = \lim_{\omega \rightarrow 0} \left(\frac{\omega \int_0^\infty G(s) \sin(\omega s) ds}{\omega^2} \right) = \lim_{\omega \rightarrow 0} \left(\frac{\omega \int_0^\infty G(s) \omega s ds}{\omega^2} \right) = \int_0^\infty G(s) s ds$$

$$J_s^o = \lim_{\omega \rightarrow 0} \left(\frac{G'(\omega)}{(G''(\omega))^2} \right) = \frac{1}{\eta_o^2} \int_0^\infty G(s) s ds$$

$$A_G \equiv J_s^o \eta_o^2$$

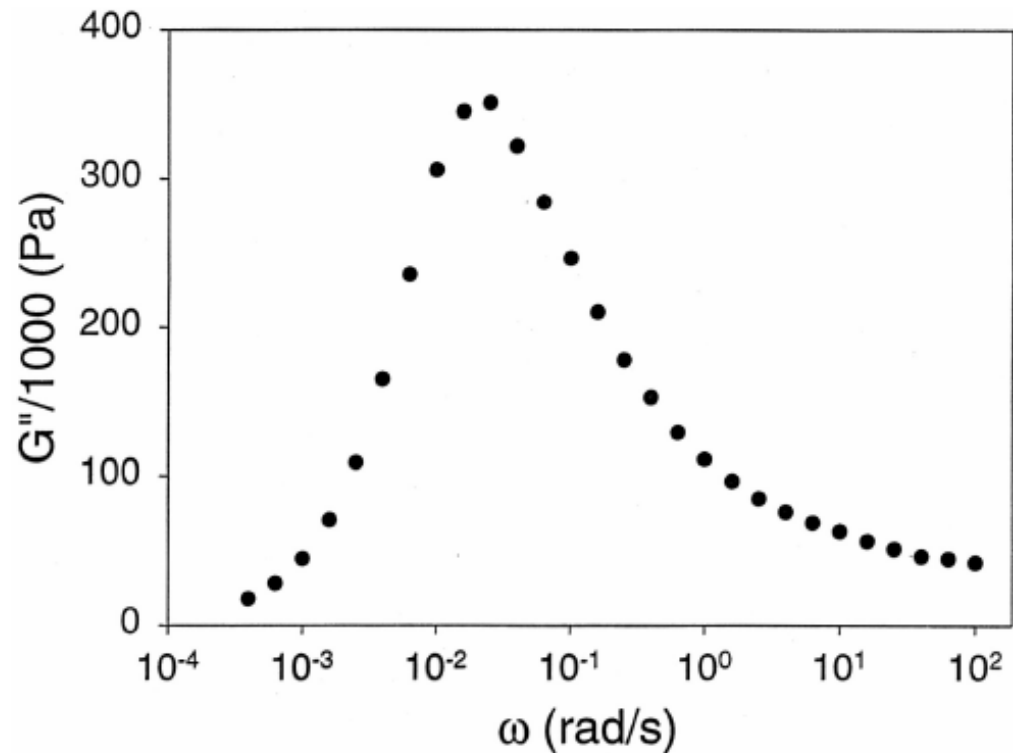
SAOS



Plateau Modulus Integration of the loss modulus

$$G_N^o = \frac{2}{\pi} \int_{-\infty}^{\infty} G''(\omega) d(\ln(\omega))$$

RC-3 polybutadiene $M_w = 940,000$, $M_w/M_n < 1.1$, $T_g = -99^\circ C$



Creep Test



Kinematics

$$\underline{v} \equiv \dot{\gamma}_{yx}(t) y \underline{e}_x$$

$$\tau_{yx}(t) = \begin{cases} 0, & t < 0 \\ \tau_o, & t \geq 0 \end{cases} = \tau_o H(t)$$

Material Properties

$$J(t, \tau_o) \equiv \frac{\gamma_{yx}(0, t)}{\tau_o}$$

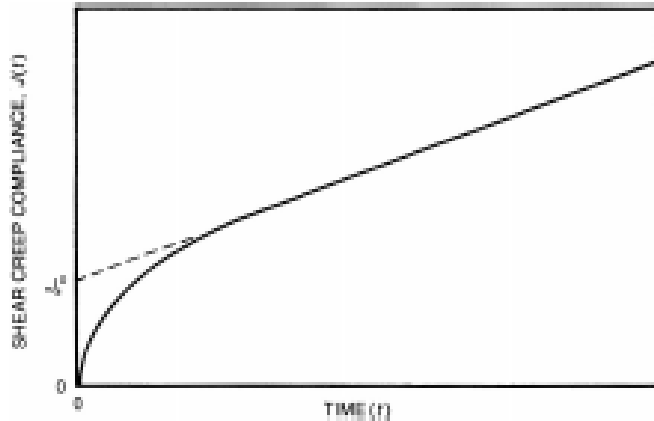
$$J_r(t', \tau_o) \equiv \frac{\gamma_r(t')}{\tau_o}$$

Shear
Compliance

Recoverable
Compliance

In linear viscoelasticity J is independent of τ_o
(cm^2/dyne)

Creep Test



$$J(t, \tau_o) = J_s^o + \frac{t}{\eta_o}$$

Compliance in steady state gives a modulus of the final stored elastic energy

Boltzmann superposition results

$$J_s^o = \frac{1}{\eta_o^2} \int_0^\infty G(s) s ds = \frac{\int_0^\infty G(s) s ds}{\left[\int_0^\infty G(s) ds \right]^2}$$

$$\eta_o = \int_0^\infty G(s) ds$$

$$J_s^o = \frac{1}{\eta_o^2} \int_{-\infty}^\infty G(s) s^2 d(\ln(s))$$

Relaxation Modulus

Comparison with Experiments
for the determination of the relaxation time



Maxwell Model

$$G(t) = G_o \exp(-t / \lambda)$$

$$\frac{tG(t)}{[tG(t)]_{\max}}$$

The function $tG(t)$
reaches its max value when $t = \lambda$

$tG(t)$ for polybutylene of high molecular weight $M_w=940,000$ and zero dispersity in the length of macromolecular chains. The continuous line depicts the predictions of the Maxwell model.

