

The CMB: A case study in Bayesian probability



The CMB: A Case Study

- Our underlying theories are statistical. How do we learn about cosmology from CMB observations?
 - predictions of power spectra (and higher moments): (quantum) noise
 - expand to include polarization
- Inferences in cosmology
- Measuring the spectrum, C_ℓ
 - temperature and polarization
- Measuring cosmological parameters
- Beyond the power spectrum
 - anisotropy [not small scales...]
 - sub-case study: topology
 - non-Gaussianity

} In the notes,
but probably
won't have time

Data analysis as Radical Data Compression

- Radical Compression
 - Trillions of bits of data
 - Billions of measurements at 9 frequencies
 - 50 million pixel map of whole sky
 - 2 million harmonic modes measured
 - 2500 C_ℓ variances
 - 2000σ detection of CMB anisotropy power
 - Fit with just 6 parameters
 - Baryon density, CDM density, angular scale of sound horizon, reionization optical depth, slope and amplitude of primordial $P(k)$
 - $\Omega_b h^2, \Omega_c h^2, \theta_{MC}, \tau, n_s, A_s$
 - With no significant evidence for a 7th

Parameters & C_ℓ

- What we really want:
 - $P(\text{theory} \mid \text{data})$
 - theory = the parameters of LCDM
 - or perhaps even an indication of which overall theory is correct
 - data = our CMB data and any other information (“priors”) we might consider.
 - Data compression
 - $P(\text{theory} \mid \text{raw TOI data}) \approx P(\text{theory} \mid \text{noisy CMB map})$
 $\approx P(\text{theory} \mid \text{estimated } \hat{C}_\ell)$
 - Also need error bars (and/or full covariance matrix)
 - Even then, this is only approximate
 - effect of foreground removal on maps
 - \hat{C}_ℓ dist'n depends on more than just central value & covariance

□

Bayesian methods: hierarchical models

- Timestream (d_t)
 - ⇒ Map ($T_p \sim d_p$)
 - ⇒ Spectrum ($C_l \sim d_l$)
 - ⇒ cosmology

$$P(H | DI) = \frac{P(H | I)P(D | HI)}{P(D | I)}$$

$$\text{Posterior} \propto \text{Prior} \times \text{Likelihood}$$

- without loss of information? (~Sufficient Statistics)

$$\begin{aligned} \square P(\text{Cosmology} | d_t, N_{tt'}) &= P(\text{Cosmology} | \text{Map}_{\text{pix}}, N_{\text{pp}'}) \\ &\approx P(\text{Cosmology} | D_l, N_{ll'}, x_l) \end{aligned}$$

(Bond, AJ, Knox; WMAP)

- (assume that we can calculate $P(\text{Cosmology} | D_l, N_{ll'}, x_l)$ even from non-Bayes estimators)

CMB Data Analysis: mapmaking

- Model: data = signal + noise, as a function of time

$$d_t = A_{tp} T_p + n_t \quad \langle n_t n_{t'} \rangle = N_{tt'} \quad \sim \text{stationary}$$

- **Step 1: mapmaking** (estimate T_p)

- Gaussian noise \Rightarrow Gen'l least squares

$$\bar{T}_p = (A^T N^{-1} A)^{-1} A^T N^{-1} d \quad \langle \delta T_p \delta T_{p'} \rangle = (A^T N^{-1} A)^{-1}$$

- If we stop here, uniform prior gives a Gaussian posterior for the map with this mean and variance.

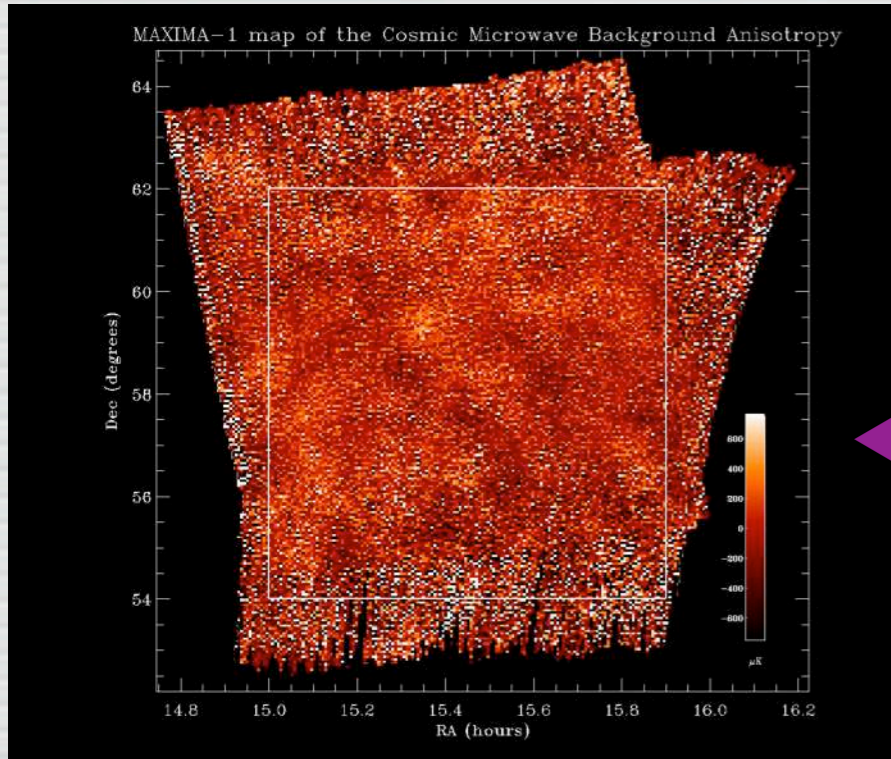
- aside: Gaussian C_ℓ prior gives Wiener filter

- But it is also a **sufficient statistic**

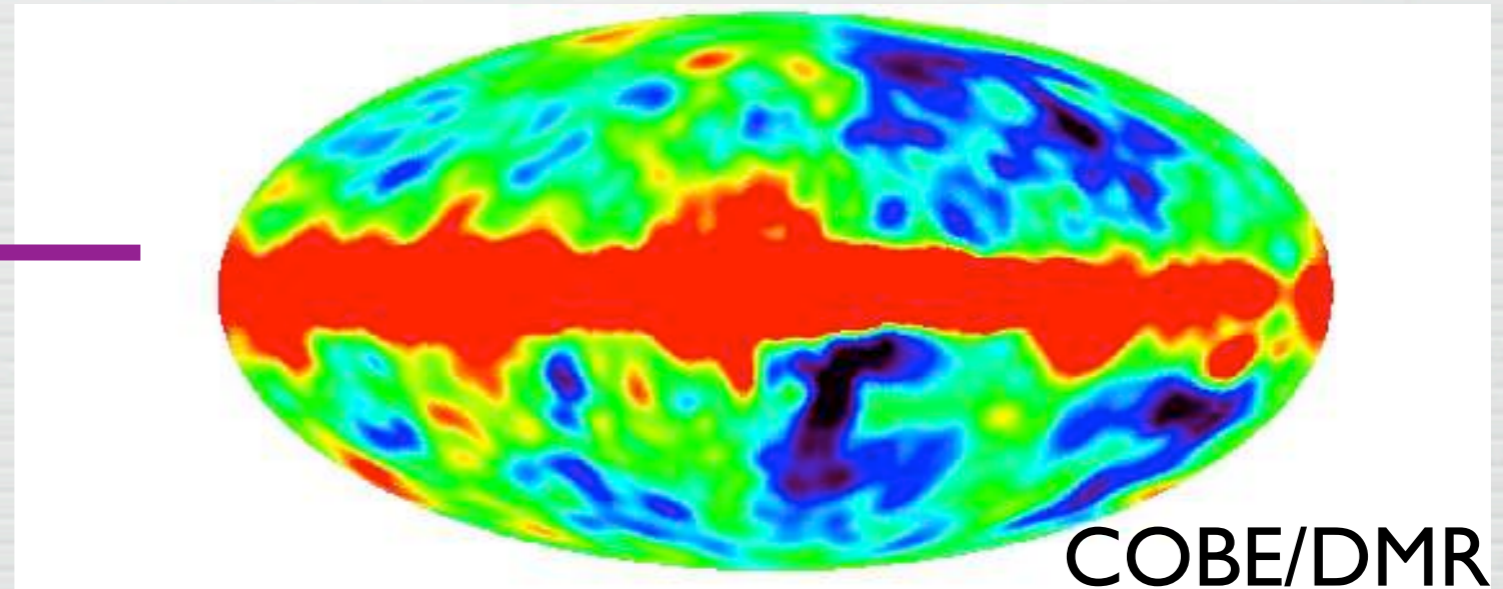
- **Algorithms:**

- Rely on simplicity/sparseness of A_{tp}
- FFT methods to apply timestream (t) operations
- Conjugate gradient least-squares soln (nb. **doesn't give corr'n matrix**)
- Further simplifications for specific cases (1/f noise, observations in rings)

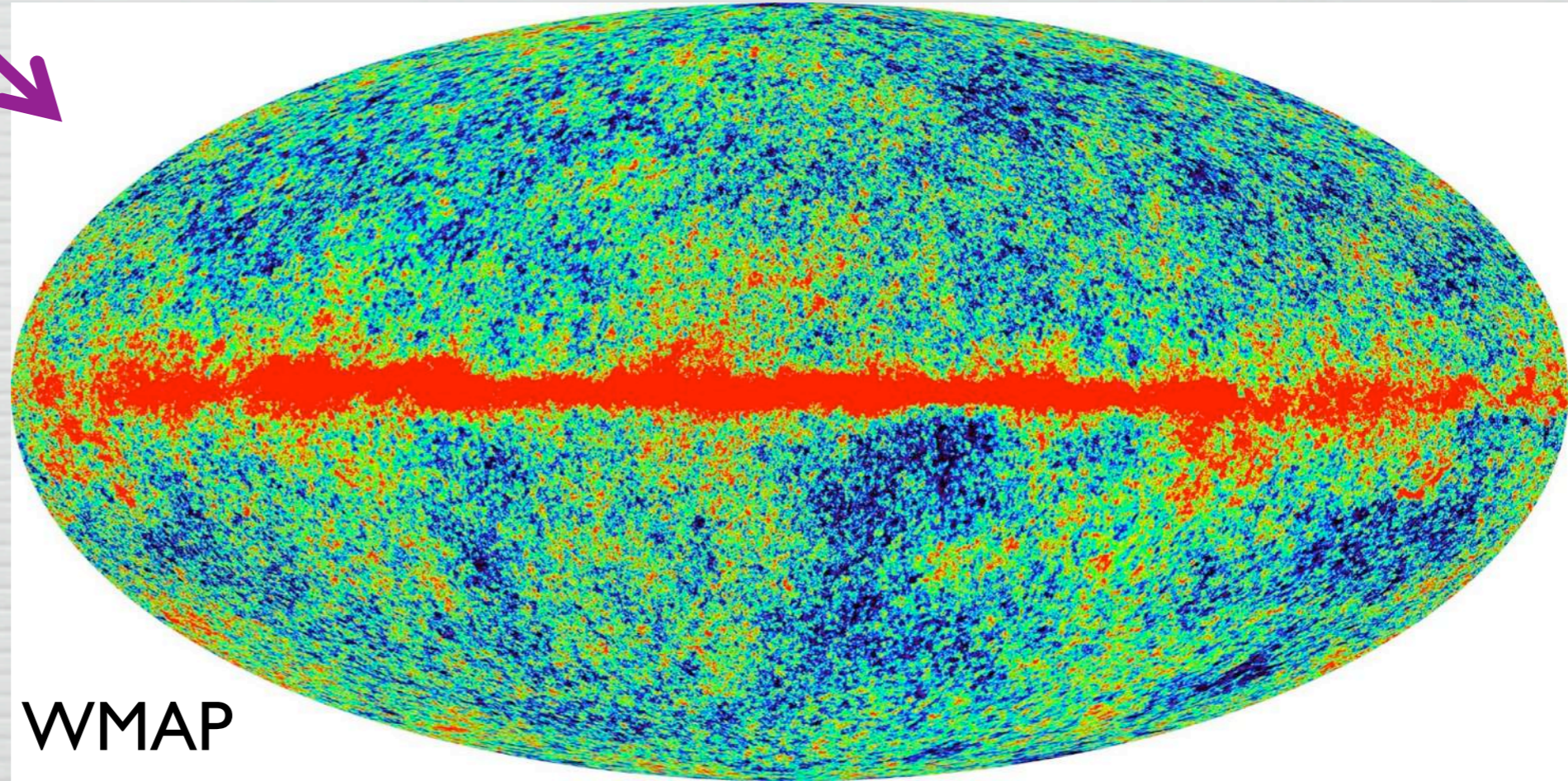
Maps of the Cosmos



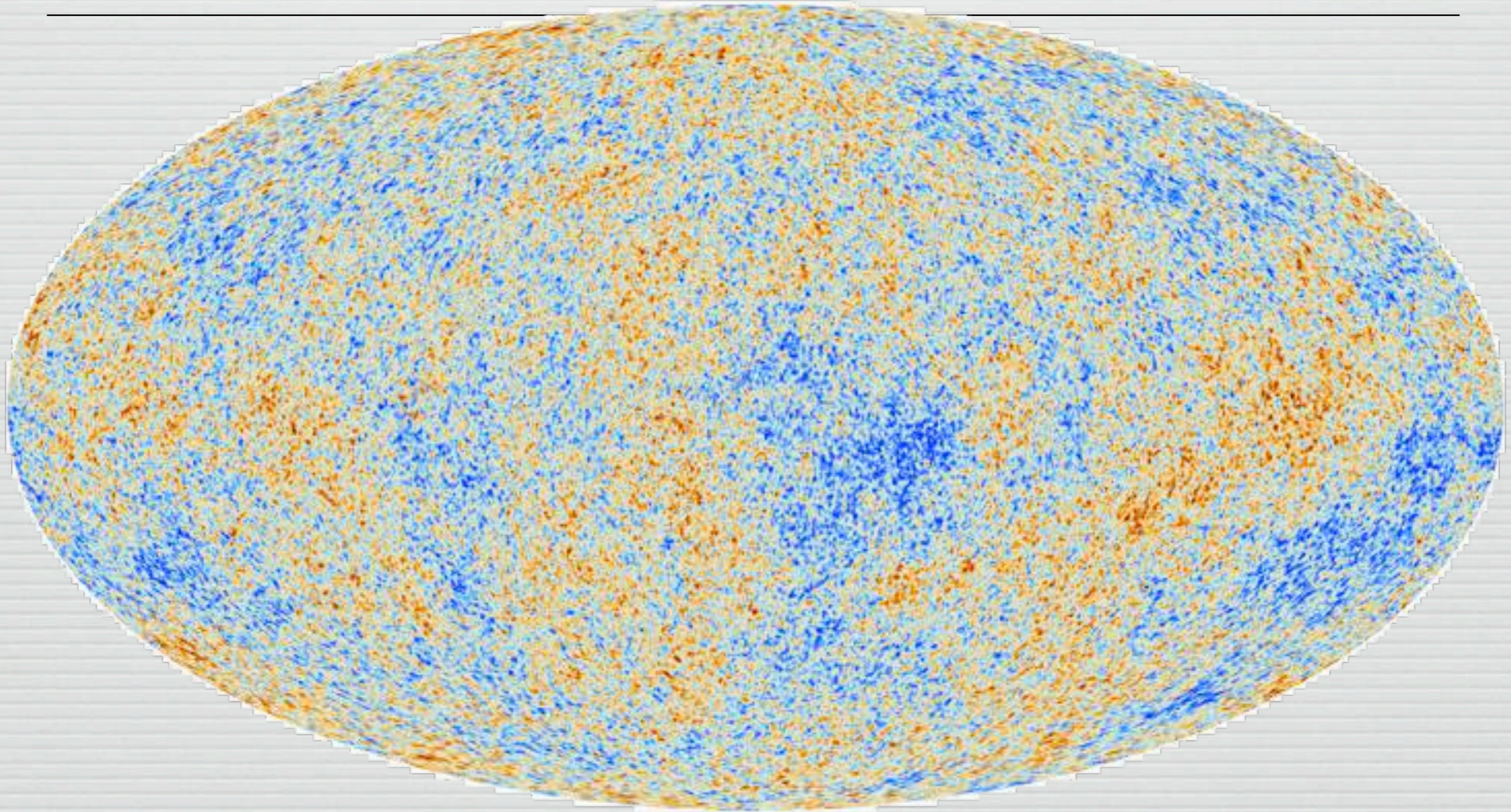
MAXIMA



*NB. pixelization on sphere non-trivial.
CMB uses "HEALPix"*



Planck



CMB Data Analysis: Spectrum estimation

- **Step 2:** Don't need to go back to the timeline to estimate the **power spectrum, C_ℓ** .
- Model the sky as a correlated, statistically isotropic Gaussian random field

$$\frac{T(\hat{x}) - \bar{T}}{\bar{T}} \equiv \frac{\Delta T}{T}(\hat{x}) = \sum_{\ell m} a_{\ell m} Y_{\ell m}(\hat{x}) \quad \langle a_{\ell m}^* a_{\ell' m'} \rangle = \delta_{\ell \ell'} \delta_{m m'} C_\ell$$

Parametric version
of cov. mat. est'n:
diag in ℓ basis

$$\langle T_p T_{p'} \rangle = S_{pp'} = \sum_{\ell} \frac{2\ell + 1}{4\pi} C_\ell B_\ell^2 P_\ell(\hat{x}_p \cdot \hat{x}_{p'})$$

spherical harmonic
wavenumber ℓ

$$P(\bar{T} | C_\ell) = \frac{1}{|2\pi(S + N)|} \exp -\frac{1}{2} \bar{T}^T (S + N)^{-1} \bar{T}$$

- complicated and expensive function of C_ℓ
 - Many practical issues in calculating this explicitly.
 - At low ℓ , use sampling (usu. Gibbs), Newton-Raphson, Copula
 - At high ℓ , approximate by a function of estimated (ML) C_ℓ and errors & some other information X_ℓ

Expected errors

- Estimating the error (variance^{1/2}) on a variance (C_ℓ)
- $\langle \delta C_\ell \delta C_\ell \rangle = \langle a_{\ell m} a_{\ell m} a_{\ell m} a_{\ell m} \rangle - \langle a_{\ell m} a_{\ell m} \rangle \langle a_{\ell m} a_{\ell m} \rangle$
 - Wick's theorem: $\langle a^4 \rangle = 3 \langle a^2 \rangle^2$
 - CMB case: Knox 95, Hobson & Magueijo 96
 - need to account for $(2\ell + 1)f_{\text{sky}}$ measurements of each ℓ

$$(\delta C_\ell)^2 \cong \frac{2}{(2\ell + 1)f_{\text{sky}}} (C_\ell + N_\ell)^2 \quad N_\ell \approx w^{-1} = (\theta_p \sigma_p)^{-2}$$

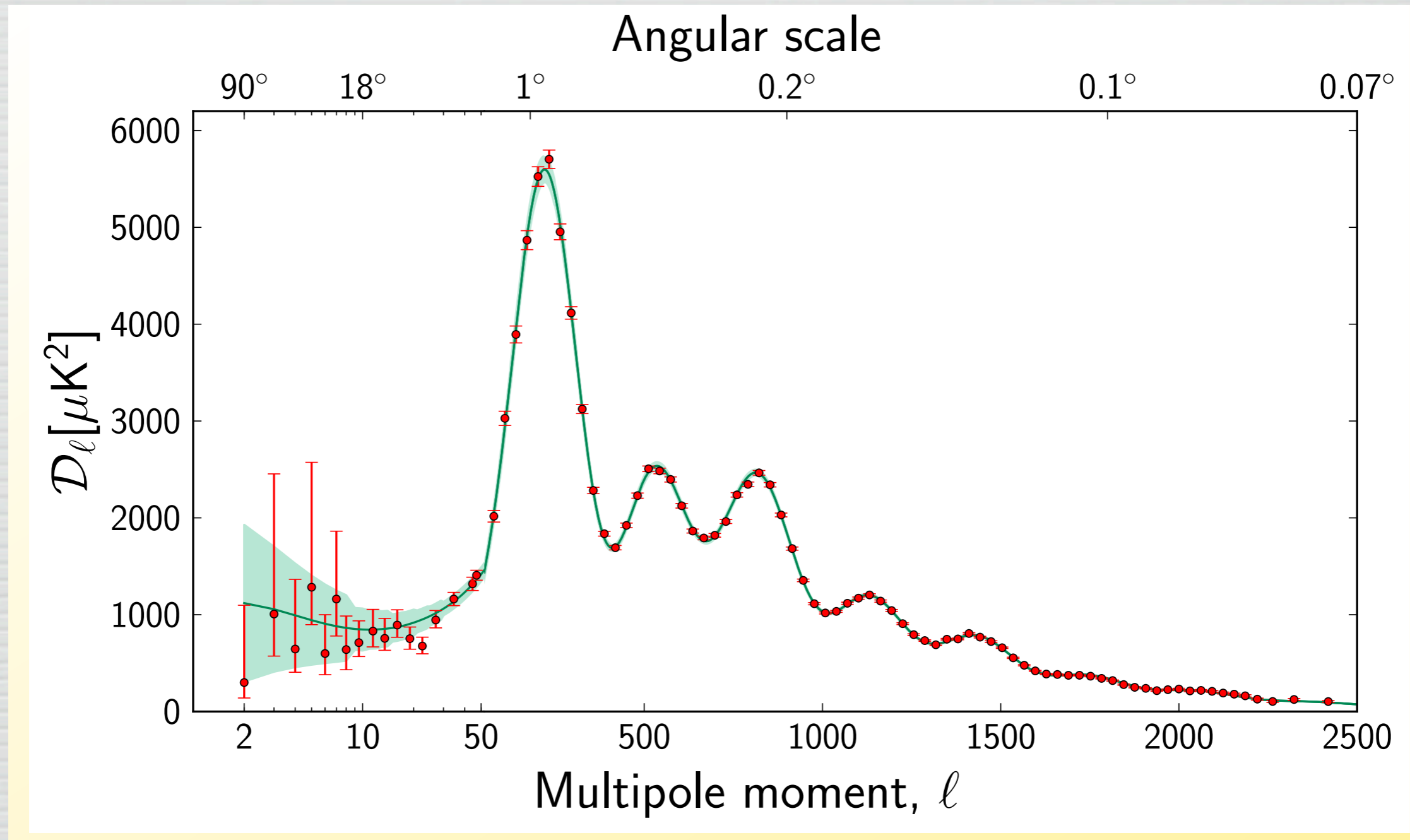
of modes

Sample
(cosmic)
Variance

Noise variance

- Bandpowers: bin in ℓ (weighted for specific C_ℓ shape) to reduce errors and decrease covariance

Planck errors



Error band: cosmic variance estimate

error bars: cosmic + noise variance

A toy model

- Consider all-sky observations with uniform white noise

$$d_p = T_p + n_p \quad \langle T_p T_{p'} \rangle = S_{pp'} = \sum_{\ell} \frac{2\ell + 1}{4\pi} C_{\ell} B_{\ell}^2 P_{\ell}(\hat{x}_p \cdot \hat{x}_{p'})$$

- Pixel-space likelihood $\langle n_p n_{p'} \rangle = N_{pp'} = \sigma^2 \delta_{pp'}$

$$P(d_p | C_{\ell}) = \frac{1}{|2\pi(S + N)|^{1/2}} \exp -\frac{1}{2} d^T (S + N)^{-1} d$$

- Work in harmonic space $d_{\ell m} \simeq \int d^2 \hat{x}_p d(\hat{x}_p) Y_{\ell m}(\hat{x}_p)$

- White noise equiv to const. noise spectrum, $N_{\ell} = N_{\infty} \sigma^2$
 $\langle n_{\ell m} n_{\ell' m'} \rangle = \delta_{\ell \ell'} \delta_{m m'} N$

- Likelihood separates

$$P(d_{\ell m} | C_{\ell}) = \prod_{\ell} \frac{1}{|2\pi(C_{\ell} + N)|^{\ell+1/2}} \exp \left(-\frac{2\ell + 1}{2} \frac{\hat{C}_{\ell}}{C_{\ell} + N} \right)$$

- with pseudo spectrum $\hat{C}_{\ell} \equiv \frac{1}{2\ell + 1} \sum_m |d_{\ell m}|^2$

Toy model

$$P(d_{\ell m}|C_{\ell}) = \prod_{\ell} \frac{1}{|2\pi(C_{\ell} + N)|^{\ell+1/2}} \exp\left(-\frac{2\ell+1}{2} \frac{\hat{C}_{\ell}}{C_{\ell} + N}\right) \quad \hat{C}_{\ell} \equiv \frac{1}{2\ell+1} \sum_m |d_{\ell m}|^2$$

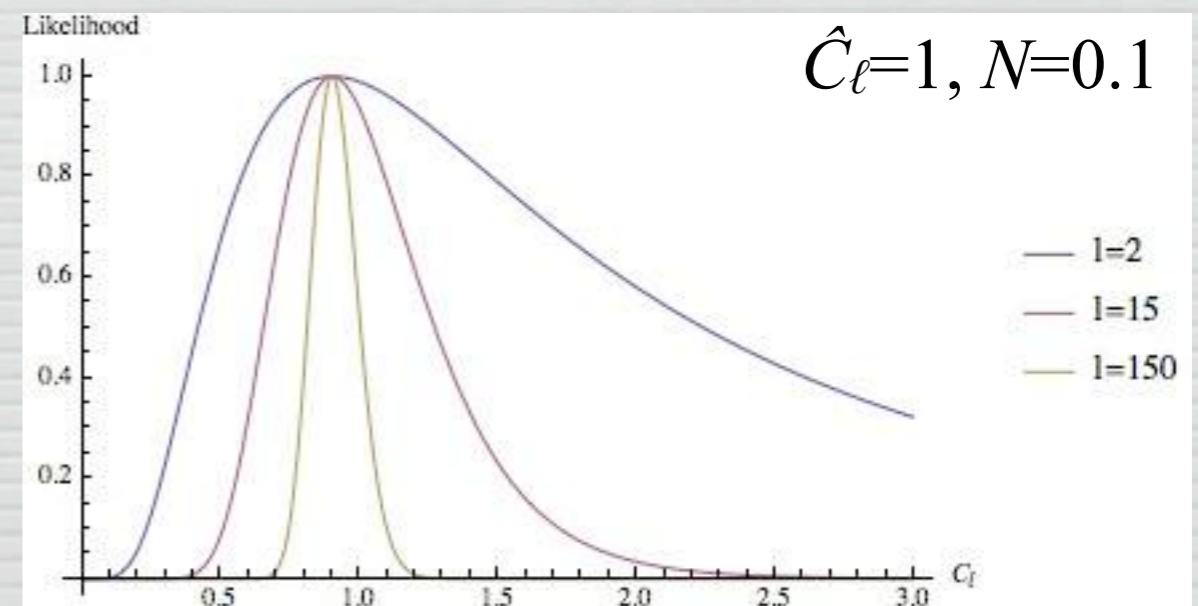
□ Likelihood (as a function of C_{ℓ}) maximized at $C_{\ell} = \hat{C}_{\ell} - N$

□ with curvature $\left. \frac{d^2 \ln P}{dC_{\ell}^2} \right|_{C_{\ell} = \hat{C}_{\ell} - N} = - \left(\frac{2\hat{C}_{\ell}}{2\ell+1} \right)^{-1}$

■ cf. Gaussian $\frac{d^2 \ln P}{dx^2} = -(\sigma^2)^{-1}$
and Fisher information $F \equiv - \left\langle \frac{d^2 \ln P}{dx^2} \right\rangle$

□ Skew positive likelihood

□ more Gaussian as $\ell \rightarrow \infty$



Bayesian methods: MADCAP/MADspec

- (quasi-)Newton-Raphson iteration to Likelihood maximum
- Algorithm driven by matrix manipulation (iterated quadratic):

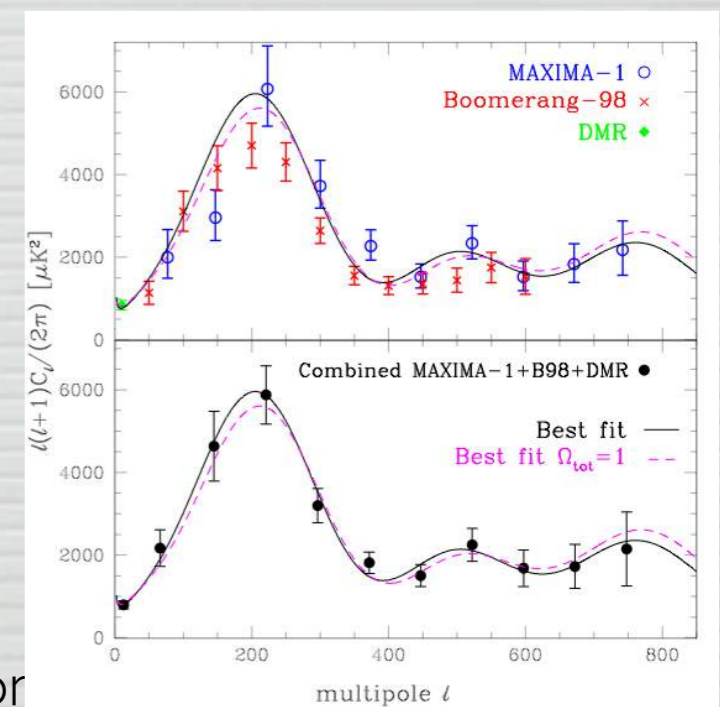
$$\delta C_\ell = \frac{1}{2} F_w^{-1} \text{Tr} \left[(dd^T - C) \left(C^{-1} \frac{\partial C}{\partial C_\ell} C^{-1} \right) \right]$$

$$F_w = \frac{1}{2} \text{Tr} \left[C^{-1} \frac{\partial C}{\partial C_\ell} C^{-1} \frac{\partial C}{\partial C_\ell} \right] \quad \text{Fisher matrix}$$

$$C = S + N$$

- Fisher = approx. Likelihood curvature
- full polarization: signal matrix $S^{xx'}_{pp'}$
- Arbitrary (precomputed) noise spectrum
- Arbitrary linear filters
 - Stompor et al; Jaffe et al; Slosar et al

- $O(N^3)$ operations naively (matrix manipulations), speedup to $\sim O(N^2)$ for spectrum estimates (potentially large prefactor)
 - Fully parallelized (MPI, SCALAPACK)
 - do calculations in the natural basis
 - no explicit need for full N_{pp} matrix in pixel basis (just noise spectrum or autocorrelation)
- e.g., MAXIMA, BOOMERANG



Borrill, Cantalupo, Stor...

Frequentist Monte Carlo methods

- MASTER: quadratic pseudo- C_l estimate (Hivon et al)

$$d_{\ell m} = \sum_p d_p w_p \Omega_p Y_{\ell m}(\hat{x}_p)$$

$$\hat{C}_\ell = \frac{1}{2\ell + 1} \sum_m |d_{\ell m}|^2 \quad \text{pseudo-}C_l$$

$$\hat{C}_\ell \approx \langle \hat{C}_\ell \rangle = \sum_{\ell'} C_\ell M_{\ell\ell'} F_\ell B_\ell^2 + N_\ell$$

(Will discuss Bayesian sampling for C_ℓ later on)

where

N is noise bias

M is mode coupling depending on sky coverage

F is experimental filter

- SPICE: transform of correlation function estimate

(Szapudi et al)

- Issues: filters, weights, noise estimation/iteration, input maps

ICIC — optimal or naïve?

Hybrid Methods: FASTER

- Key insight: MASTER covariance formalism allows calculation of diagonal part of pseudo- a_{lm} covariance — use for likelihood maximization
 - (nb. this has maximum entropy and so is conservative!)
 - *Diagonal* likelihood:

$$P(d_{lm} | C_\ell I) = \frac{1}{\left[2\pi \langle \hat{C}_\ell + N_\ell \rangle\right]^{1/2}} \exp\left[-\frac{1}{2} \frac{|d_{lm}|^2}{\langle \hat{C}_\ell + N_\ell \rangle}\right]$$

- MC evaluation of means;
- Newton-Raphson iteration towards maximum
- Easy calculation of Likelihood shape parameters

B98, CBI; Contaldi et al

(related suggestions from Delabrouille et al)

WMAP (etc.): Cross-correlations

- Take advantage of uncorrelated noise between different detectors

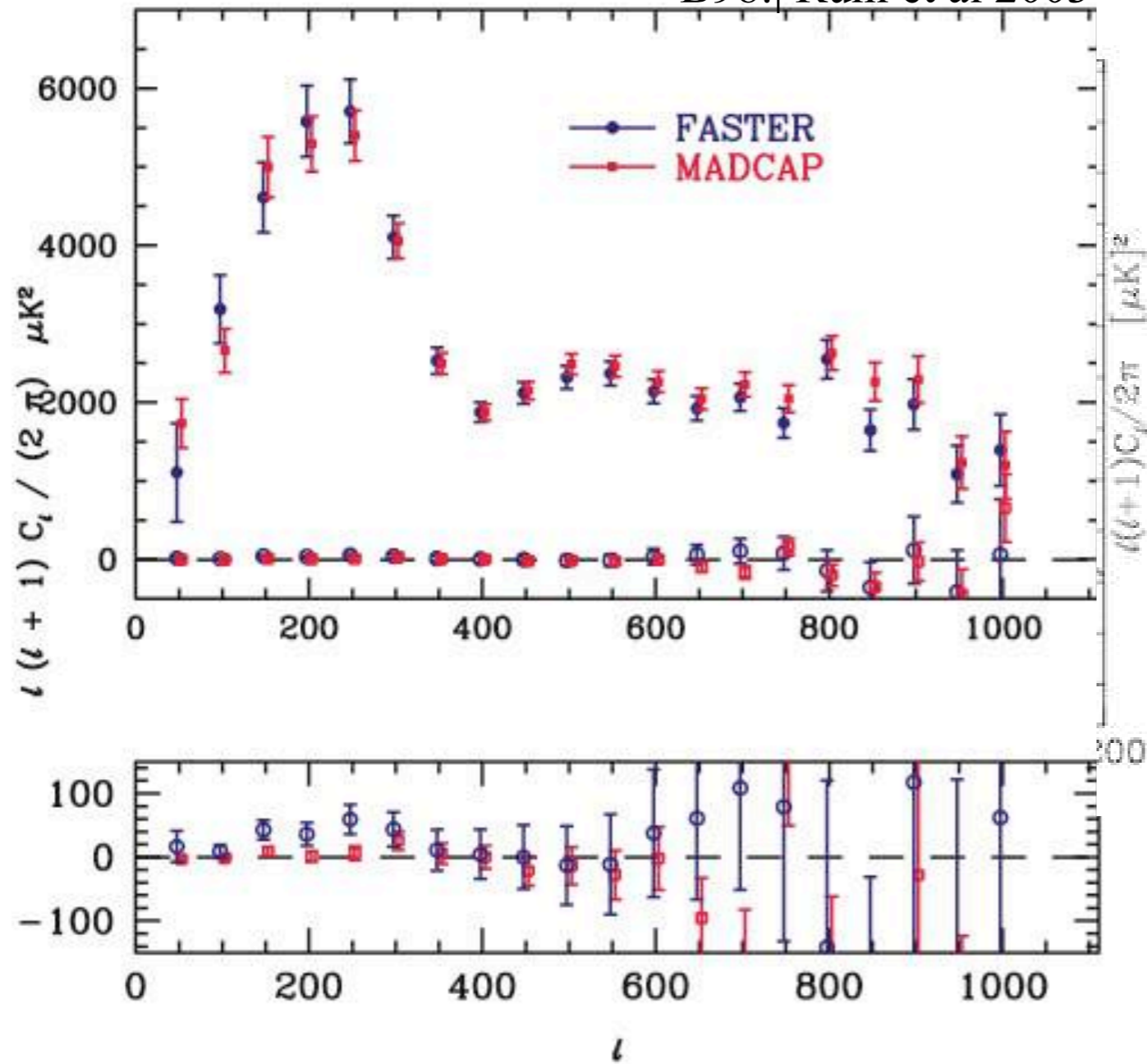
- $\langle d_p^1 d_{p'}^2 \rangle = \langle (s_p^1 + n_p^1)(s_{p'}^2 + n_{p'}^2) \rangle = S_{pp'}^{12} + \cancel{N_{pp'}^{12}} = S_{pp'}$

Monte Carlo method — without need for noise bias removal

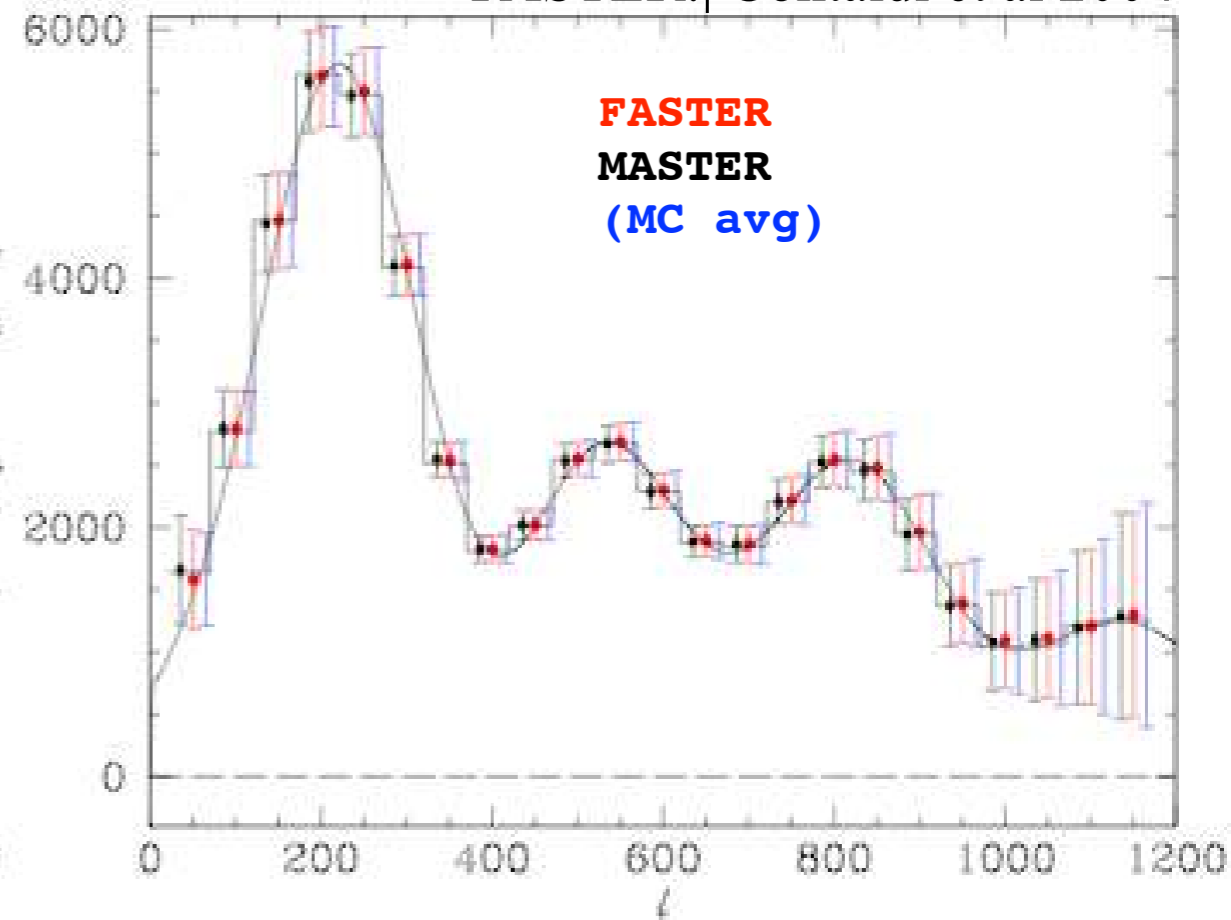
□

Comparisons

B98:| Ruhl et al 2003



FASTER:| Contaldi et al 2004



Timing and efficiency

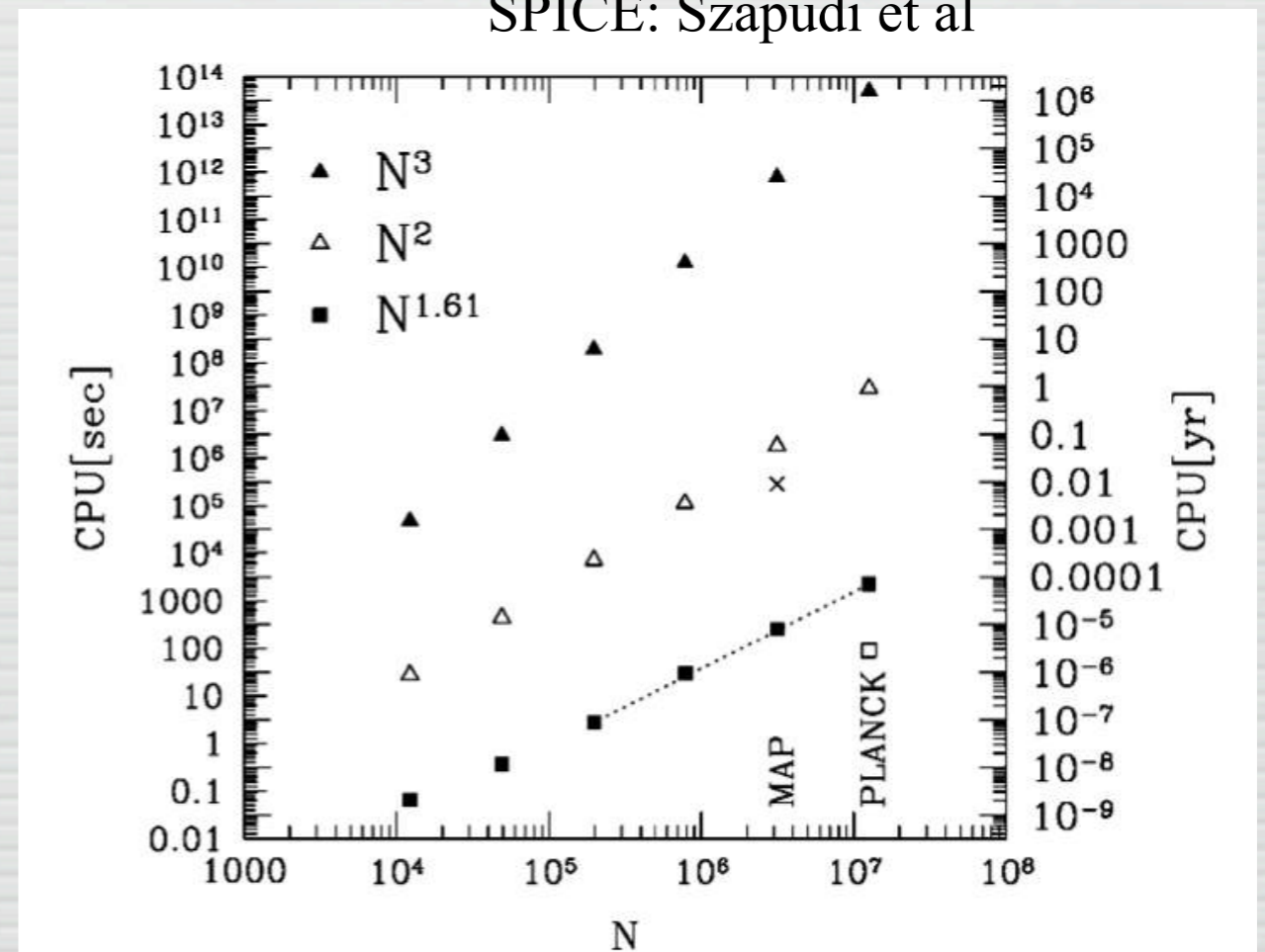
time

- optimal/bayes: N_p^3
- monte carlo: $N^{1.5}$
- prefactors: N_{MC}, N_{bin}, \dots

Space

- TOI: 50 GB/yr @200Hz
- maps: 384 Mb @ $N_{side}=2048$
- noise matrix: $N^2/2$ entries
~9 petabytes @
 $N_{side}=2048$

SPICE: Szapudi et al



resource management will become an issue even for cheapest methods

Bayesian/Frequentist Correspondence

- Why do both methods seem to work?
- frequentist mean \sim likelihood maximum
- frequentist variance \sim likelihood curvature
- Correspondence is *exact* for
 - linear gaussian models (mapmaking)
 - variance estimation with no correlations and “iid” noise — simple version of C_l problem
 - e.g., all sky, uniform noise
 - likelihood only function of d_{lm}^2
 - breaks down in realistic case of correlations, finite sky, varying noise
 - “asymptotic limit”
 - \sim high l iff noise correlations not “too strong”
- But we still want to bootstrap from point estimates to the full likelihood function

Polarization

- Formally the same problem:

- $d_p \Rightarrow (i, q, u)_p = d_{i,p} = d_q$

- $\langle d_q d_{q'} \rangle = N_{qq'} + S_{qq'}$

- low S/N, large systematics

- complicated correlations:

- $N_{qq'}$: pixel differences

- $S_{qq'} = S_{qq'}^{ij}$: linearly dependent on all of $C_l^{XX'}$ ($X=T, E, B$)

- e.g., Seljak, Zaldarriaga; Kamionkowski, Kosowsky, Stebbins; &c.

- E/B leakage (= T/E/B correlation)

- in principle, don't need extra separation step if full correlations/distributions is known

- in practice, E/B characteristics impose specific correlation structure — easier to “separate”

- Wiener filter for map from C_l .

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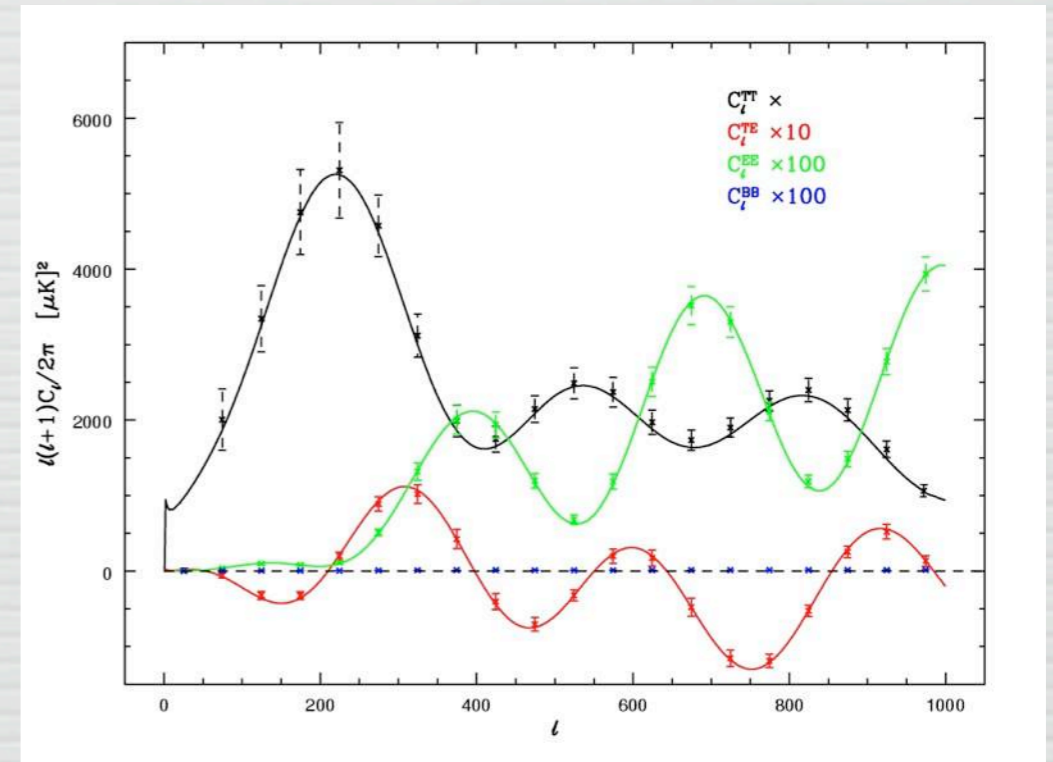
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From C_ℓ to cosmology

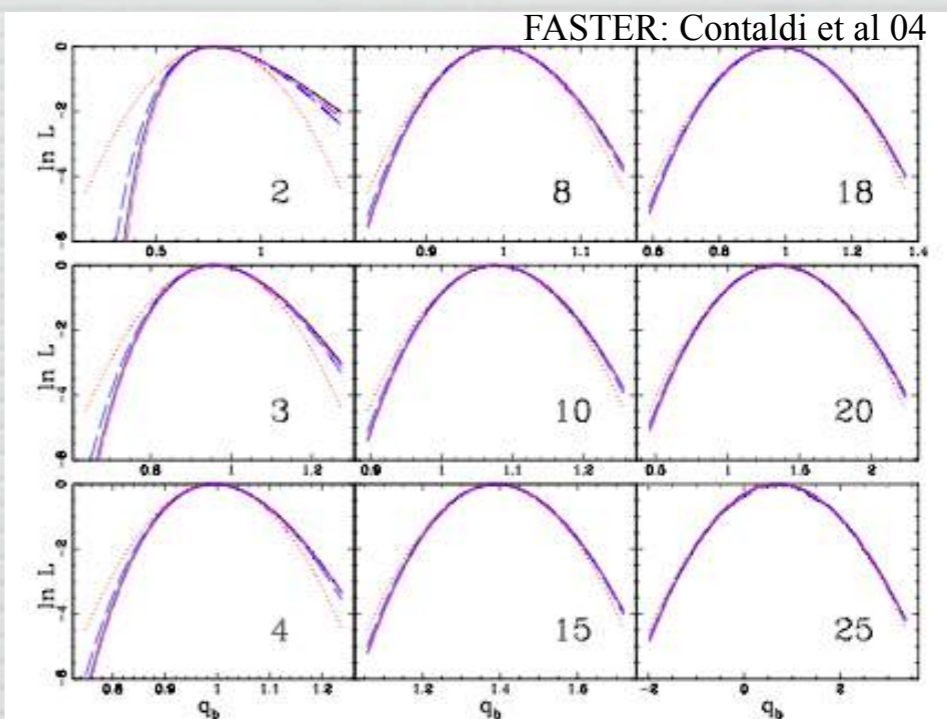
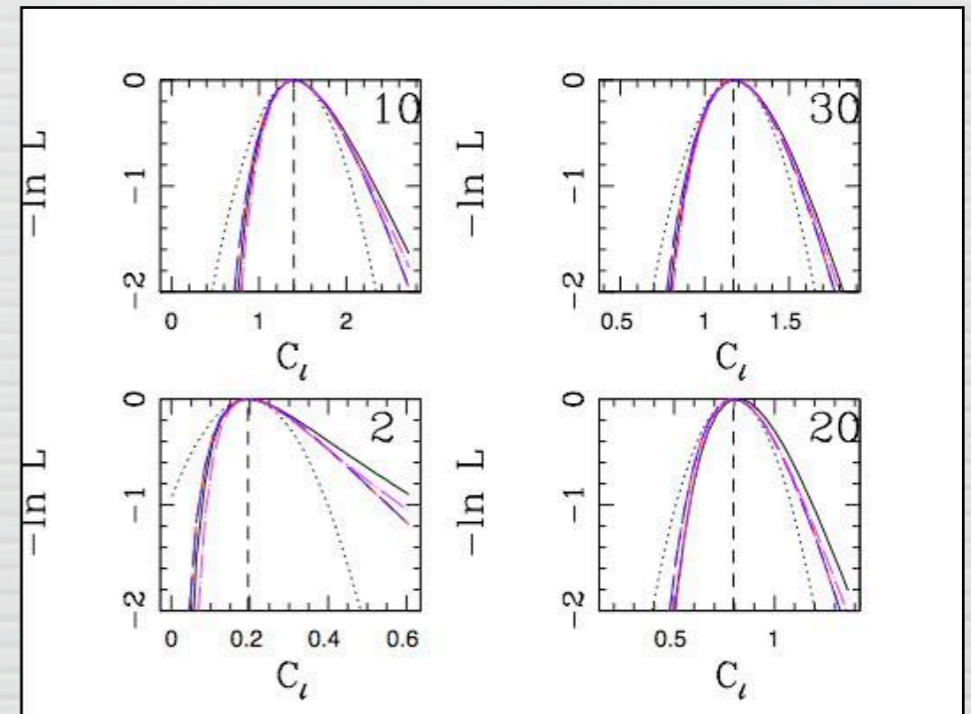
- **Step 3:** Calculate & characterize **posterior prob over some space of cosmological models** and imposed priors
- For simplest [?] theories, C_ℓ is a deterministic function of the cosmological parameters $\theta = \{H_0, n_s, \Omega_m, \Omega_{DE}, \dots\}$
 - $$\begin{aligned} P(\theta|DI) &= \int dC_\ell P(\theta|I) P(C_\ell|\theta I) P(C_\ell |DI) \\ &= P(\theta|I) P(C_\ell[\theta] | DI) \\ &= P(\theta|I) P(C_\ell[\theta] | \hat{C}_\ell, \sigma_\ell, \text{shape}, I) \end{aligned}$$

ML est. Variance
- So est'd C_ℓ is [approximately] a *sufficient statistic*
 - Only approximate, so not really a separate step
 - $P(\theta|d_t) = P(\theta|T_p) \approx P(\theta|C_\ell)$
 - can explore the likelihood — or finally assign meaningful priors on θ and calculate the posterior

The shape of the likelihood function

$$P(\bar{T}|C_\ell) = \frac{1}{|2\pi(S+N)|} \exp -\frac{1}{2}\bar{T}^T (S+N)^{-1}\bar{T}$$

- Complicated function of C_ℓ [through $S(C_\ell)$]
- *not* a Gaussian in C_ℓ
 - big effect at low ℓ
 - ~Offset lognormal (BJK 00)
 - Gaussian in $\ln(C_\ell + x_\ell)$
 - Other approximations better at moderate ℓ
 - e.g., Hamimeche & Lewis
 - include polarization
 - treat T, Q, U on same footing



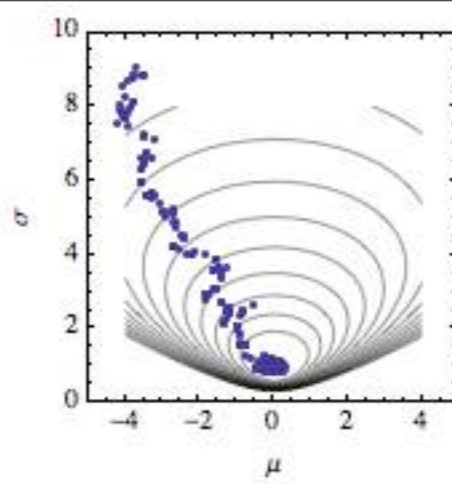
Sampling from the posterior

- Infeasible to directly explore $P(\boldsymbol{\theta}|\text{data})$ for many parameters $\boldsymbol{\theta}$
 - e.g., even the 6-parameter base LCDM model would require $\sim 100^6 = 10^{12}$ evaluations for 100 grid points in each direction...
- Instead, *generate samples* $\boldsymbol{\theta}_i$ from the distribution.
 - Easy to evaluate moments (means, variances)

$$\square \langle \boldsymbol{\theta} \rangle = \frac{1}{N} \sum_i \boldsymbol{\theta}_i \text{ or, more generally } \langle f(\boldsymbol{\theta}) \rangle = \frac{1}{N} \sum_i f(\boldsymbol{\theta}_i)$$

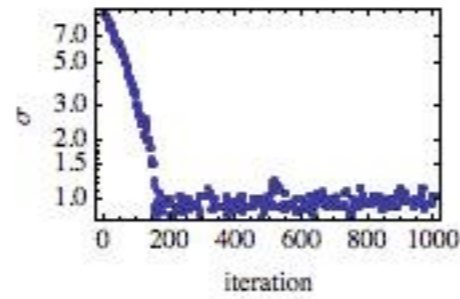
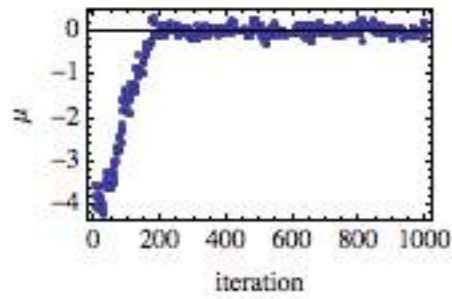
- Generate samples from posterior $P(x)$
- Most methods require being able to generate samples from some simpler distribution
- e.g., Markov Chain Monte Carlo
 - Start with proposal distribution $Q(x^*|x)$: probability of proposing point x^* if starting at point x
 - often $Q(x|y) = Q(|x-y|)$ (Metropolis)
 - Metropolis Algorithm:
 - given point $x^{(i)}$, generate x^* from $Q(x^*|x^{(i)})$
 - accept x^* as $x^{(i+1)}$ with probability $\min[1, P(x^*)/P(x^{(i)})]$;
 - otherwise $x^{(i+1)} = x^{(i)}$
 - repeat...

prop Sig[μ] = 0.2
 prop Sig[σ] = 0.2
 acceptance = 27.6%
 $\mu = 0.0208 \pm 0.0988$
 $\sigma = 0.985 \pm 0.074$

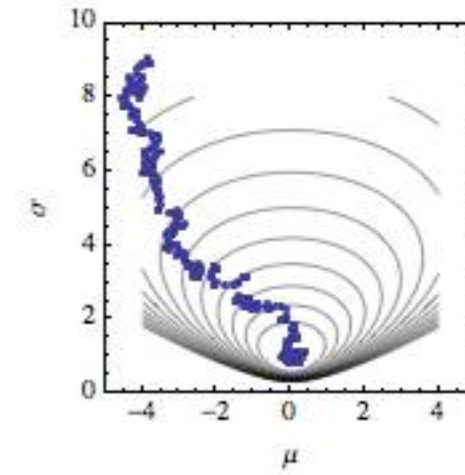


μ trace

σ trace

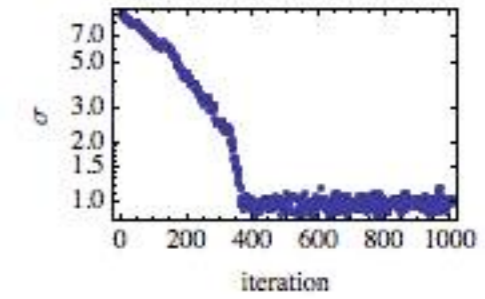
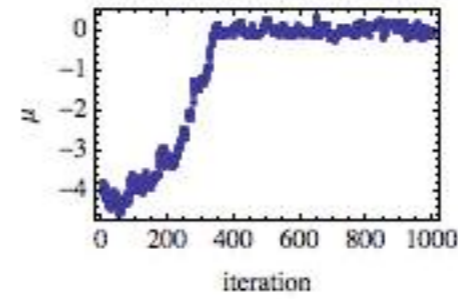


prop Sig[μ] = 0.1
 prop Sig[σ] = 0.1
 acceptance = 54.4%
 $\mu = -0.128 \pm 0.497$
 $\sigma = 1.2 \pm 0.575$

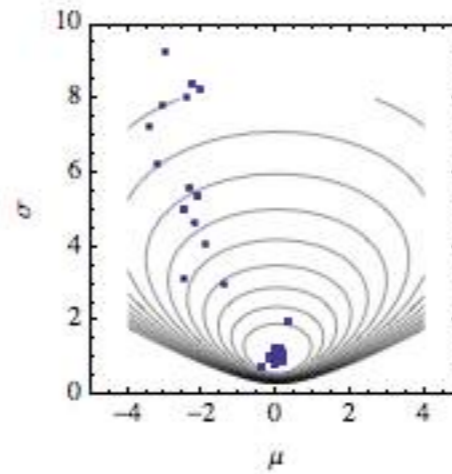


μ trace

σ trace

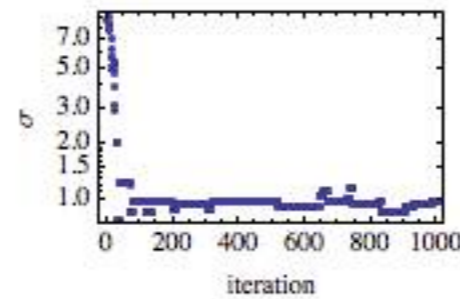
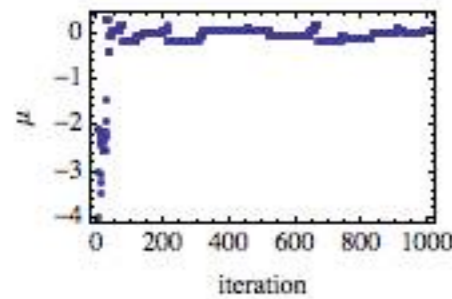


prop Sig[μ] = 0.8
 prop Sig[σ] = 0.8
 acceptance = 4.3%
 $\mu = -0.0193 \pm 0.0887$
 $\sigma = 0.974 \pm 0.0513$



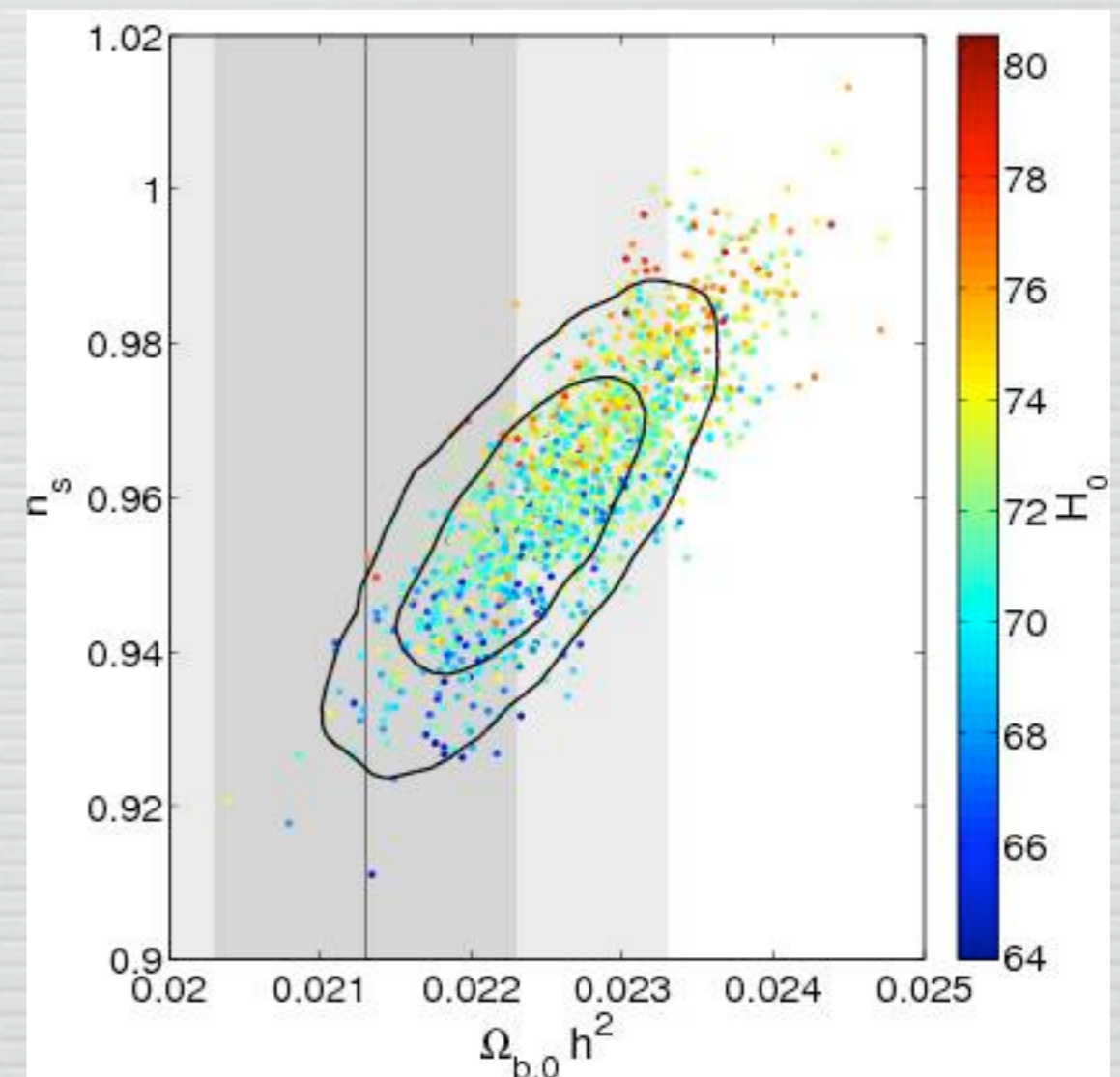
μ trace

σ trace



Monte Carlo methods for the CMB

- Markov Chain Monte Carlo: A. Lewis' CosmoMC
 - coupled with fast deterministic calculation of power spectrum as fn of cosmological parameters
 - e.g. CMBFAST, CAMB, CLASS
- Other techniques
 - e.g., Skilling's "nested sampling" which also allows fast calc'n of model likelihoods ("evidence")



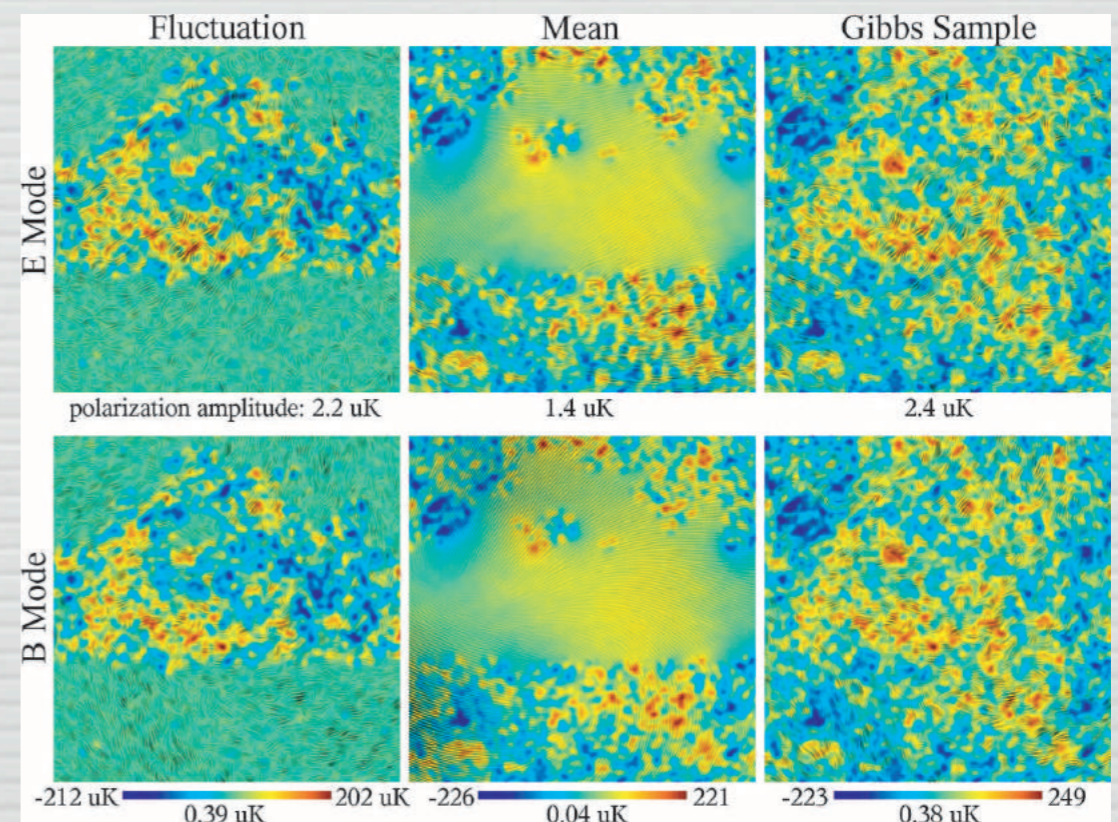
Aside: Gibbs Sampling

- Combine parametric models of foregrounds with power spectrum estimation
 - *Jewell et al; Wandelt et al; Eriksen et al; Larson et al;*
 - draw [full-sky] map realization given C_ℓ and foreground parameter (Wiener filter)
 - draw foreground realization given C_ℓ and map
 - draw C_ℓ realization given map (Wishart, Gamma dists)
- Output is sample maps and samples of C_ℓ
 - not always useful for subsequent *parameter estimation*
 - construct approx. likelihood by averaging over samples
 - Blackwell-Rao estimator

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LARSON ET AL.

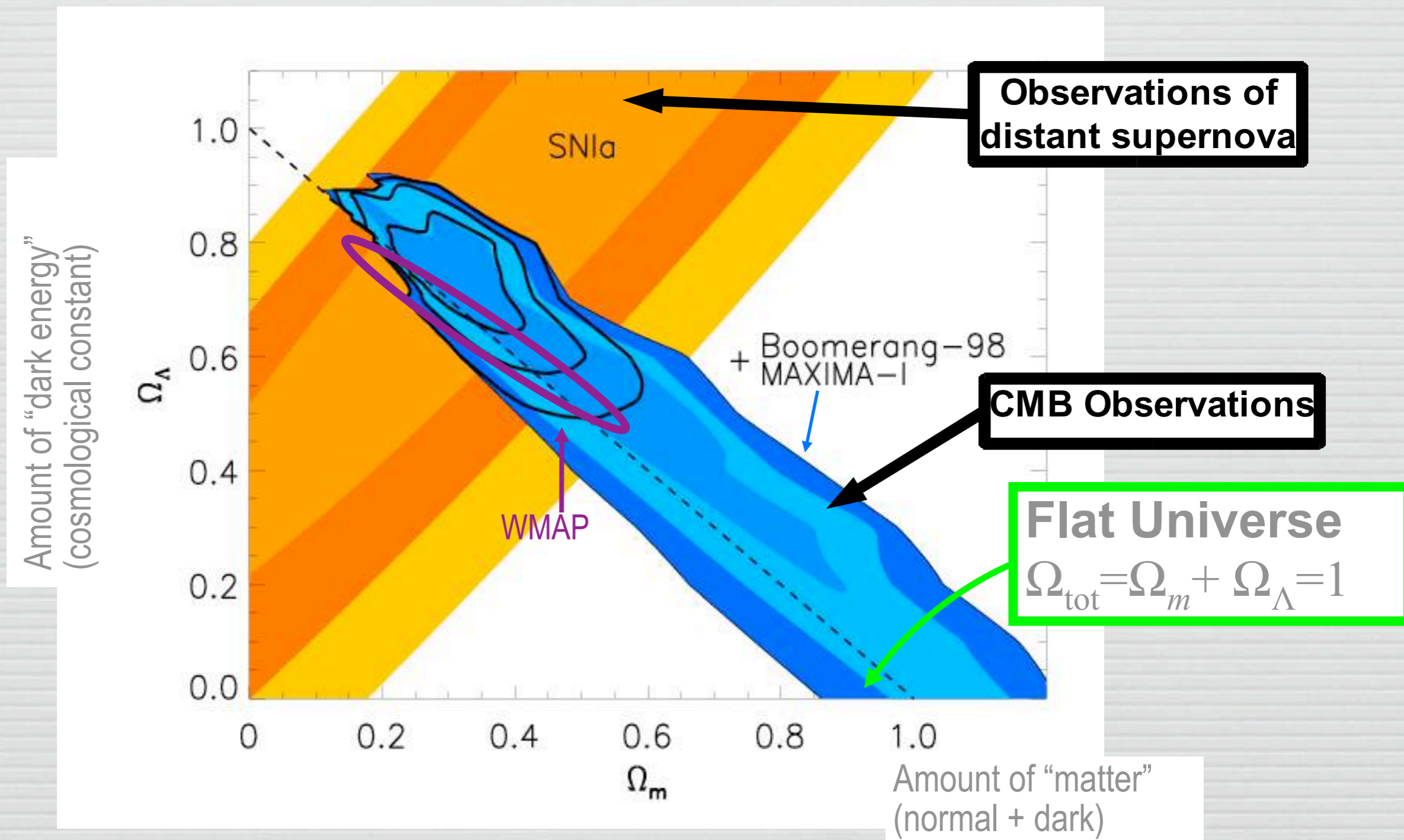
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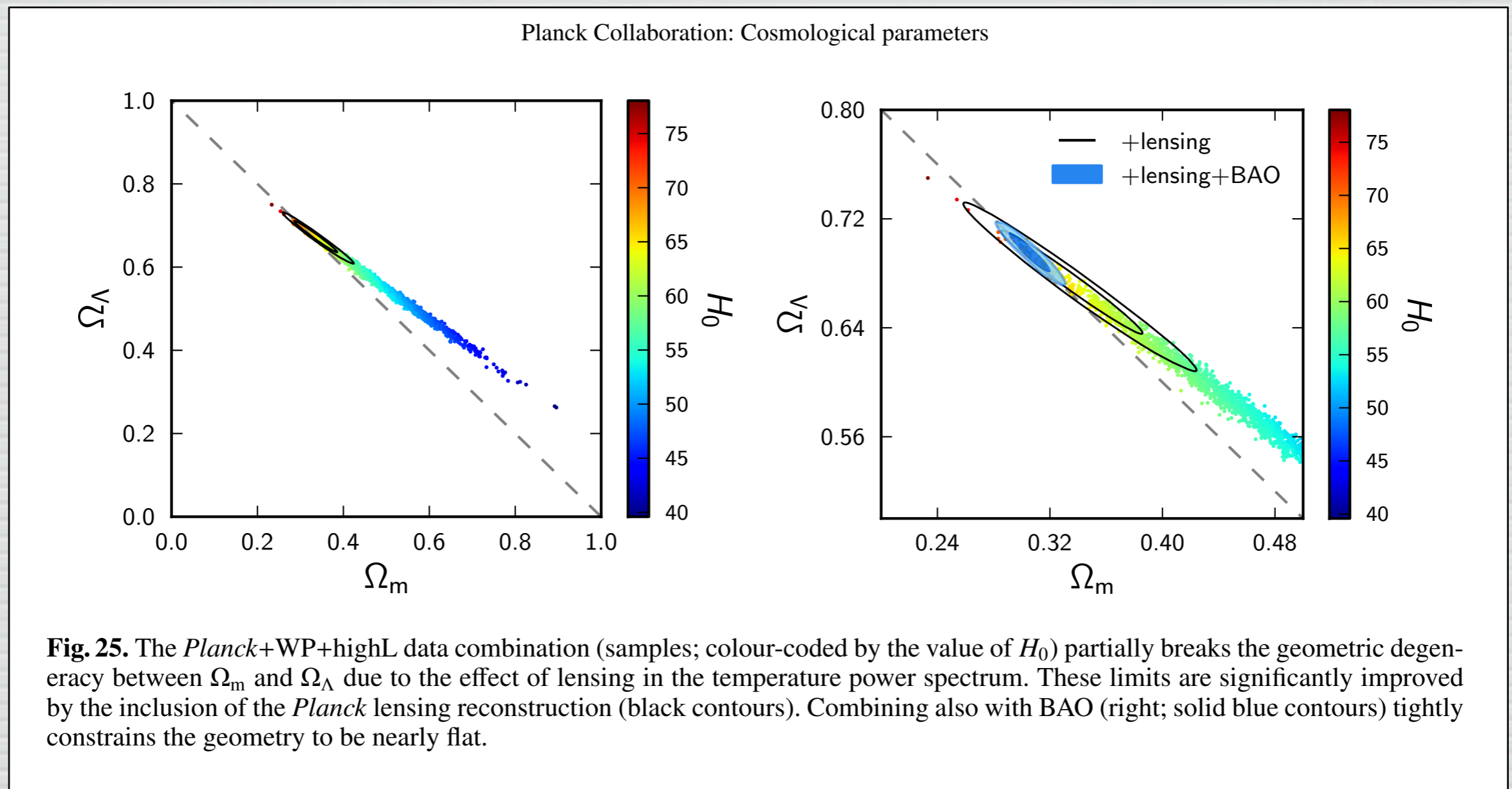
The Planck likelihood

- High ℓ
 - Start with pseudo- C_ℓ of each detector, with conservative masks
 - for cosmology, consider 100x100, 143x143, 217x217, 143x217
 - Foregrounds:
 - Use 353 GHz as a dust template
 - Explicit power spectral templates for unresolved point sources, SZ, CIB
 - Instrument:
 - relative calibration between 100, 143, 217
 - beam errors
 - Use Gaussian approximation assuming a fiducial model gives the signal covariances (Hamimeche & Lewis)
- low ℓ
 - Temperature: Planck 30-353 GHz
 - polarization: WMAP
 - needed to fix optical depth τ

Measuring the geometry of the Universe



Measuring the geometry of the Universe



Planck Params

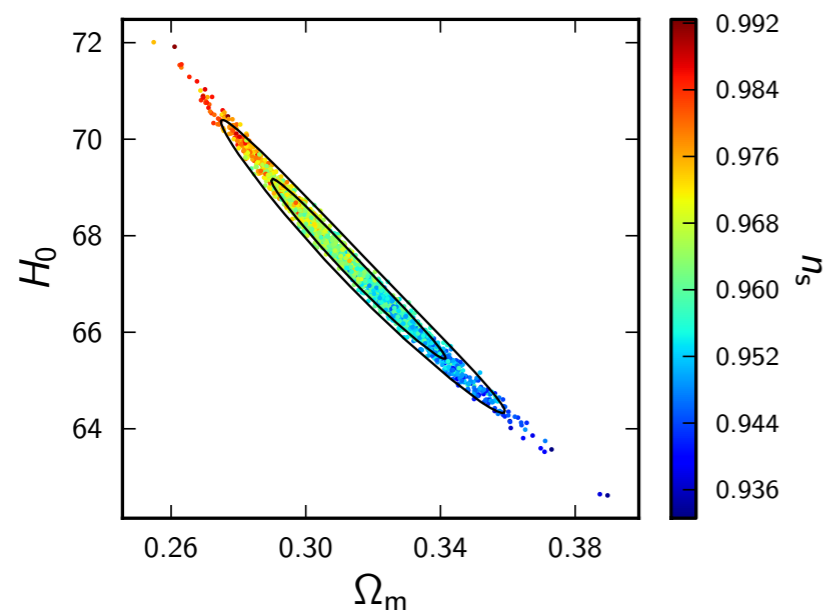


Fig. 3. Constraints in the Ω_m - H_0 plane. Points show samples from the *Planck*-only posterior, coloured by the corresponding value of the spectral index n_s . The contours (68% and 95%) show the improved constraint from *Planck*+lensing+WP. The degeneracy direction is significantly shortened by including WP, but the well-constrained direction of constant $\Omega_m h^3$ (set by the acoustic scale), is determined almost equally accurately from *Planck* alone.

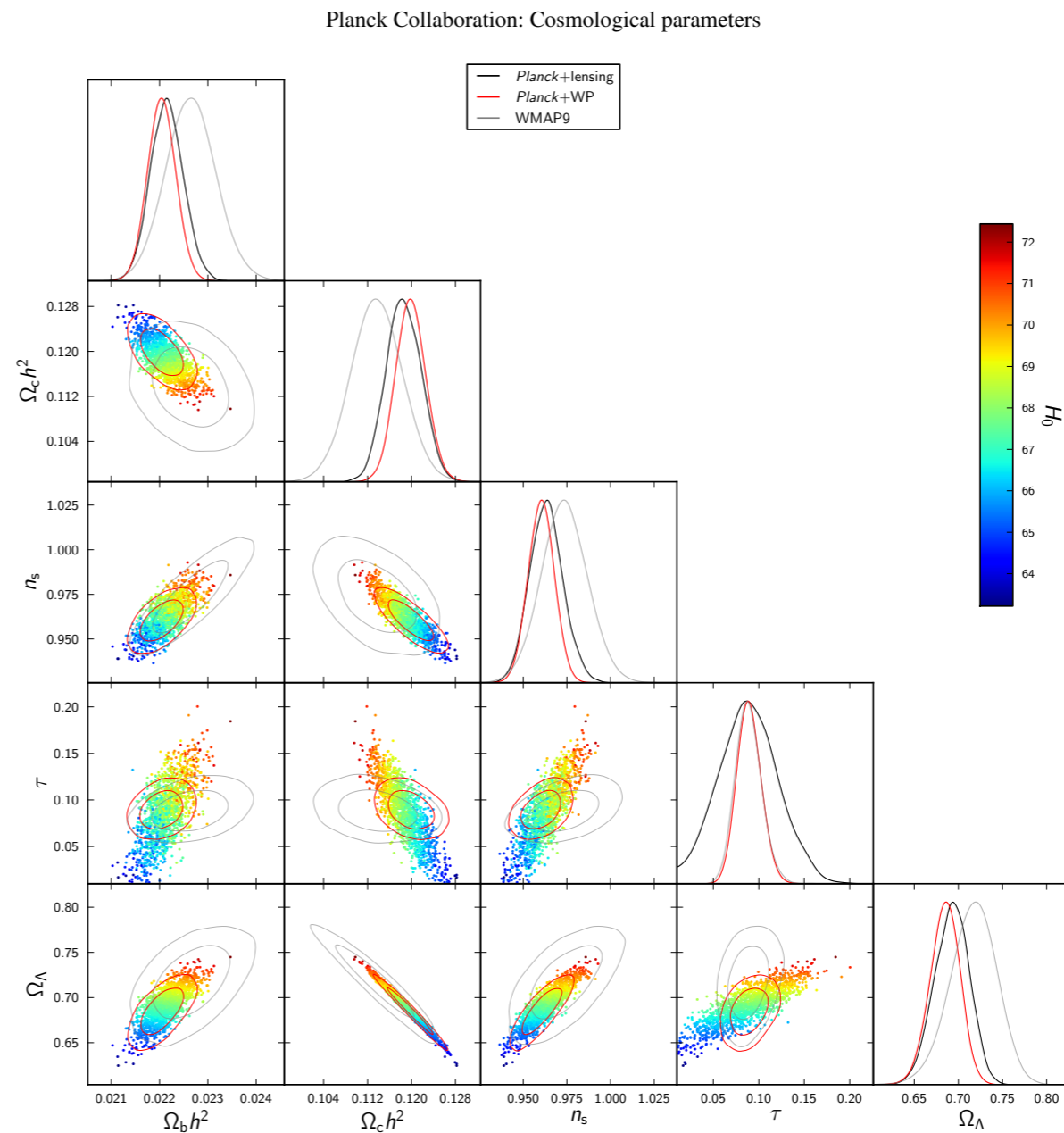


Fig. 2. Comparison of the base Λ CDM model parameters for *Planck*+lensing only (colour-coded samples), and the 68% and 95% constraint contours adding *WMAP* low- ℓ polarization (WP; red contours), compared to *WMAP*-9 (Bennett et al. 2012; grey contours).

Hierarchical Models

- So we have a **hierarchical model**
 - ask progressively more complicated questions of the data, with (approximately) no dependence on the details of previous results
 - Timelines \Rightarrow maps \Rightarrow spectra \Rightarrow parameters
- Each is a “nuisance parameter” for the next step w/ an uncontroversial prior *defining* that step
 - e.g., $\langle T_p T_p \rangle = S_{pp}(C_\ell)$ $P(C_\ell|\theta) = \delta[C_\ell - C_\ell(\theta)]$
- But in the realistic case there may be other nuisance parameters for which the priors are relevant:
 - timeline systematics, foregrounds, &c.

Testing assumptions

- We have been calculating the posterior

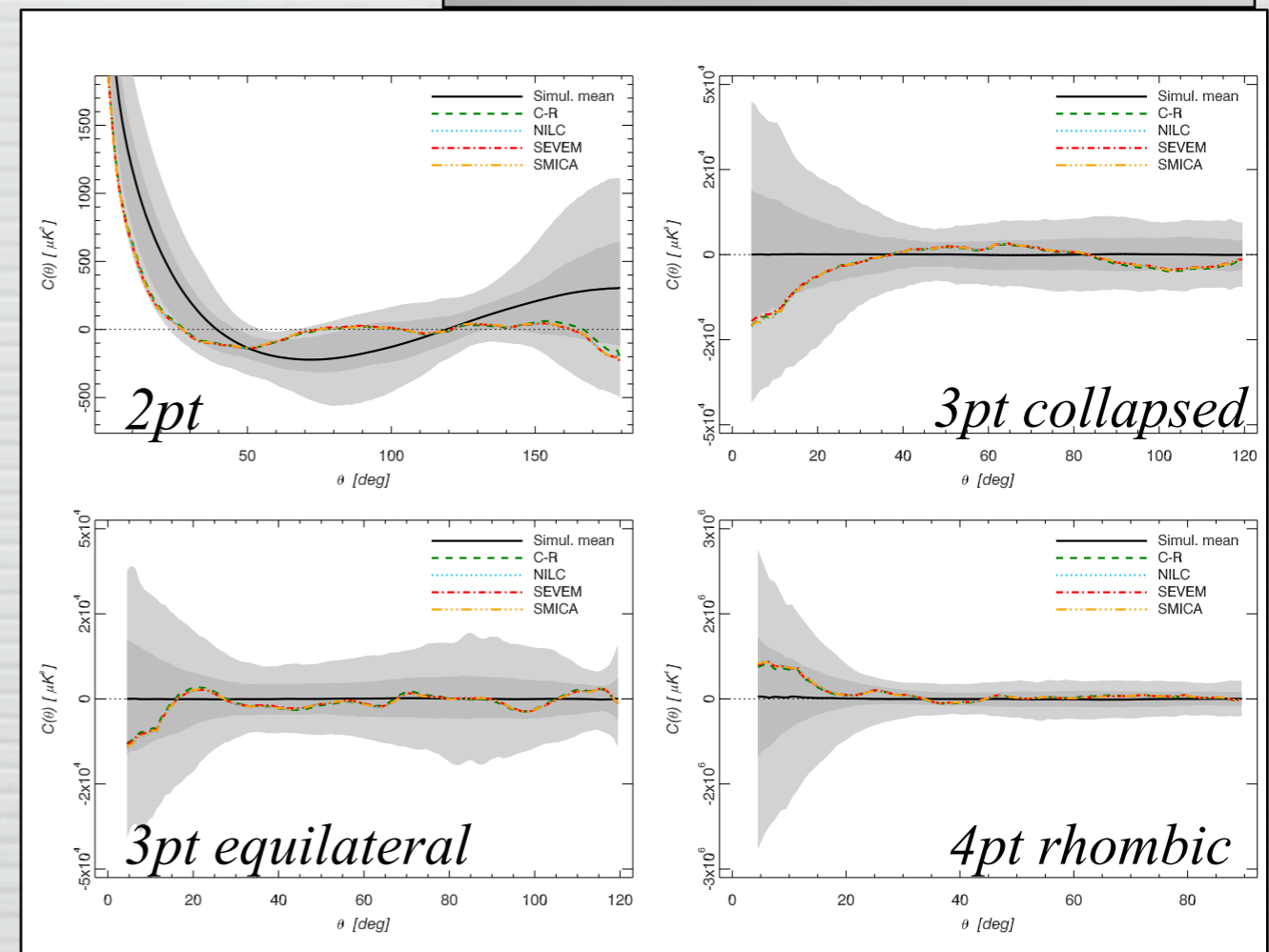
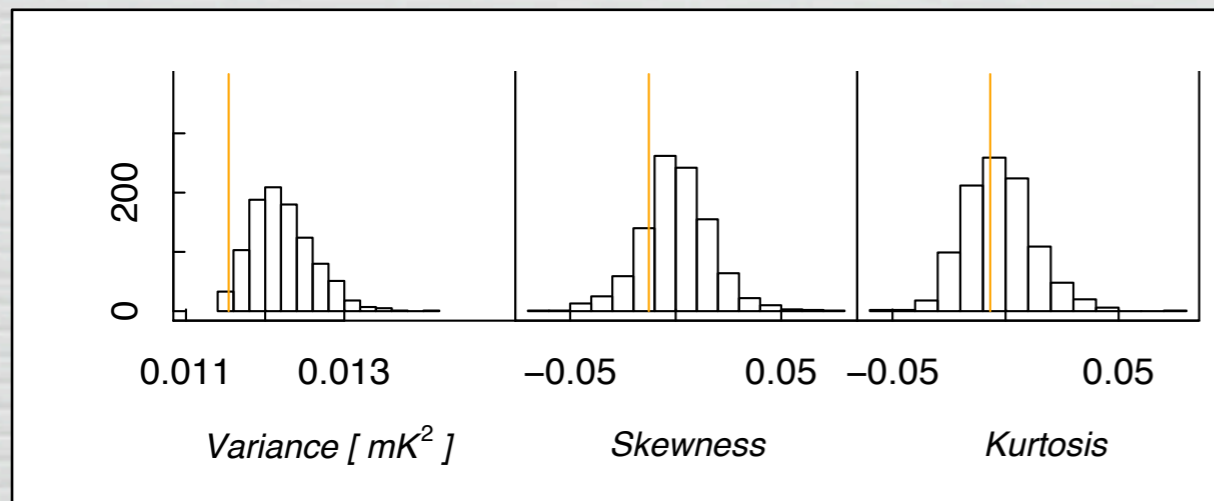
$$P(\Omega_b h^2, \Omega_c h^2, \theta_{MC}, \tau, n_s, A_s \mid \text{Planck, I})$$

- Background information “I”

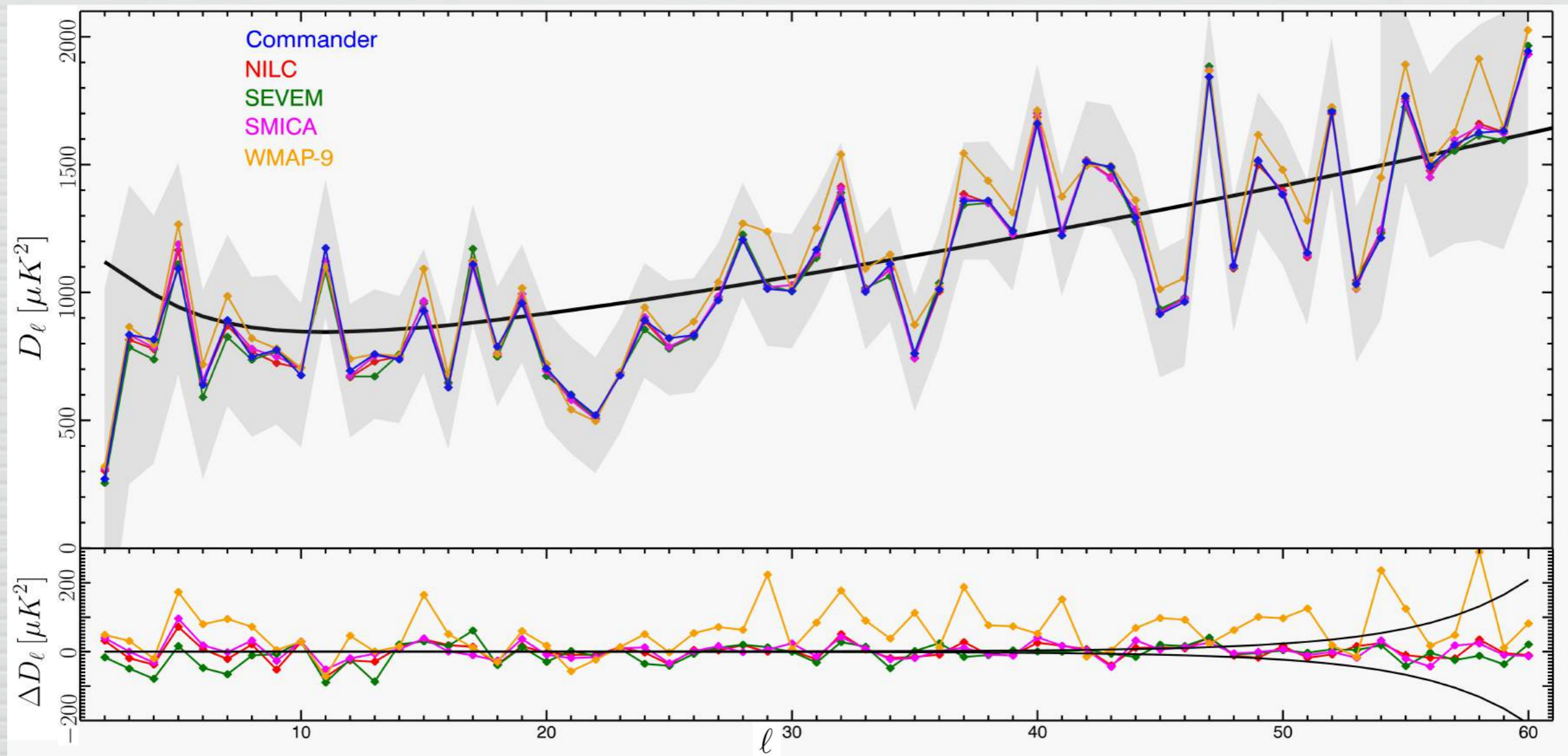
- (testable) assumptions:

- LCDM in general
- gaussianity, isotropy
- by some measures, it obeys these assumptions very well

Very difficult to test these assumptions absent a specific alternative, in a Bayesian way

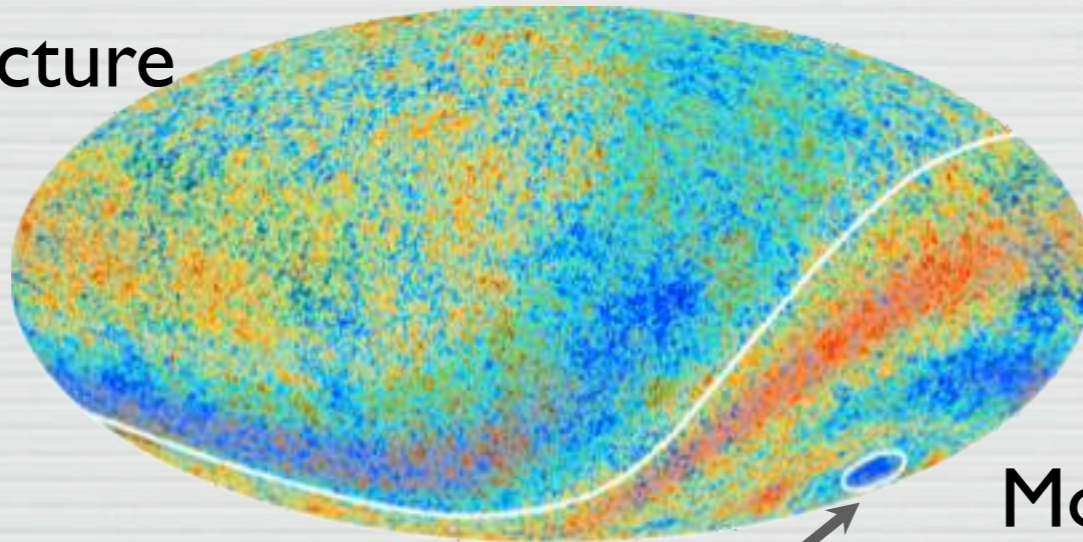


Low power on large scales



Anomalies?

Less structure

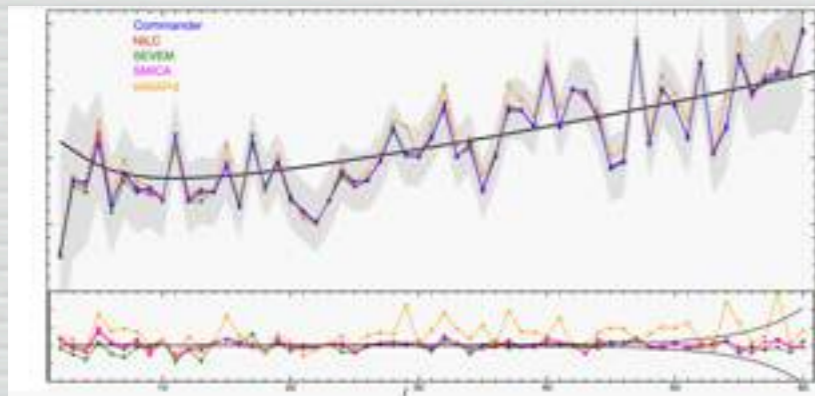
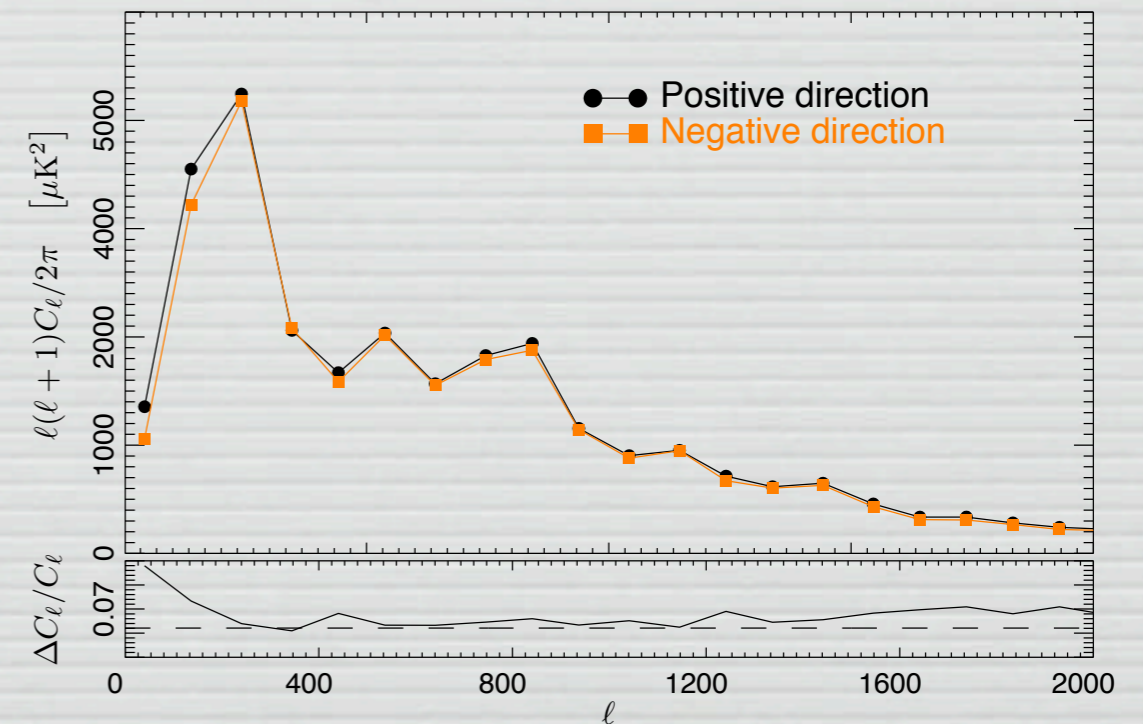


nb. there is also a *known* asymmetry from CMB dipole aberration.

More structure

“cold spot”

Small (but statistically significant) difference between the power in the hemispheres



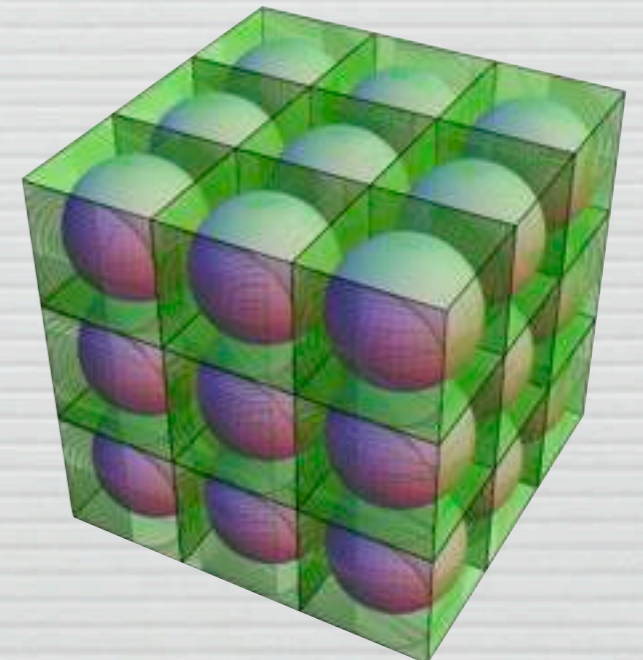
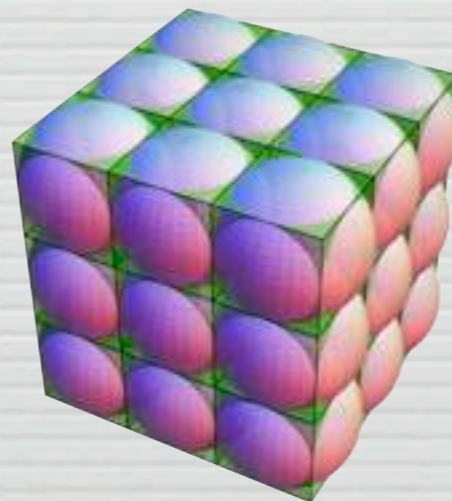
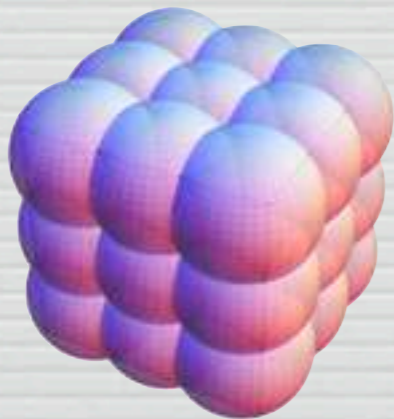
Overall low amplitude at large scales

Large-scale anisotropy

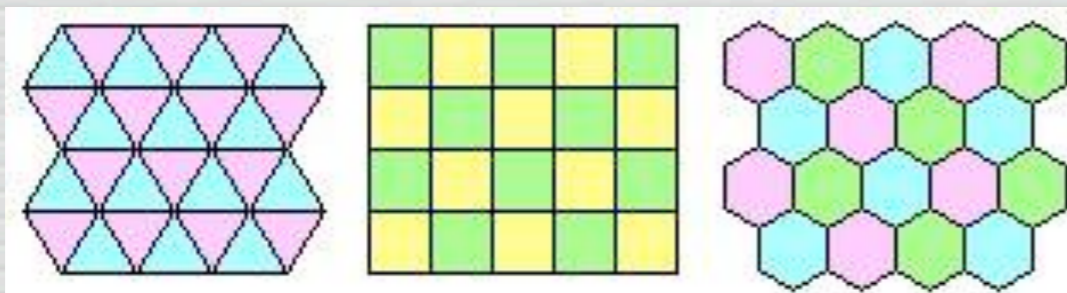
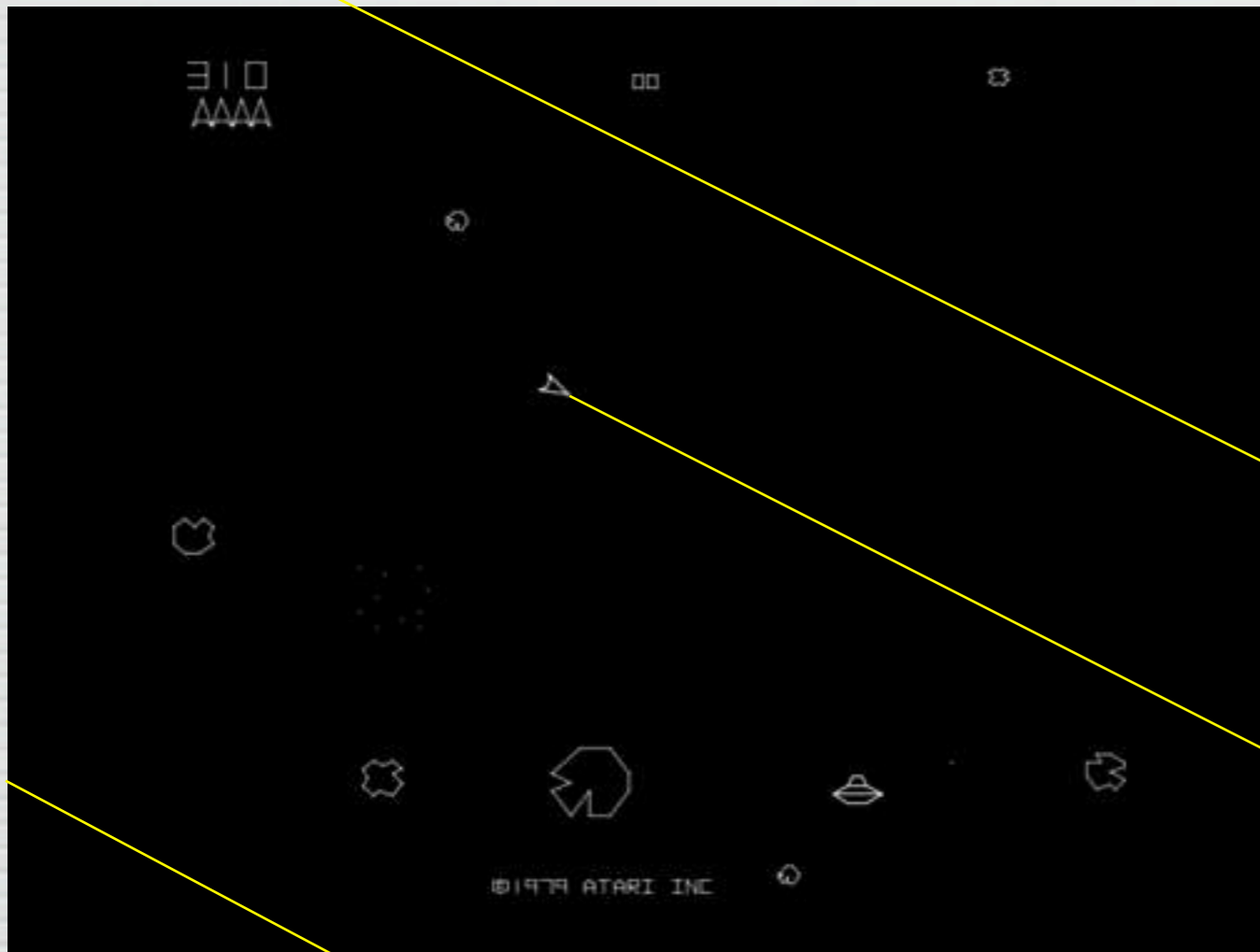
- Hemispherical differences: how can we arrange anisotropy on the scale of the horizon?
 - initial conditions: anisotropic inflation?
 - the large-scale structure of spacetime
 - change the geometry: Bianchi
 - homogeneous + anisotropic spacetimes
 - change the topology

The shape of the Universe

- General relativity determines the **curvature** of the Universe, but not its **topology** (holes and handles)
- Most theories of **quantum gravity** (and quantum cosmology) predict **topological change** on small scales and at early times.
- Does this have cosmological implications?
 - E.G., small universe \Rightarrow fewer large-scale modes available \Rightarrow low power on large scales?



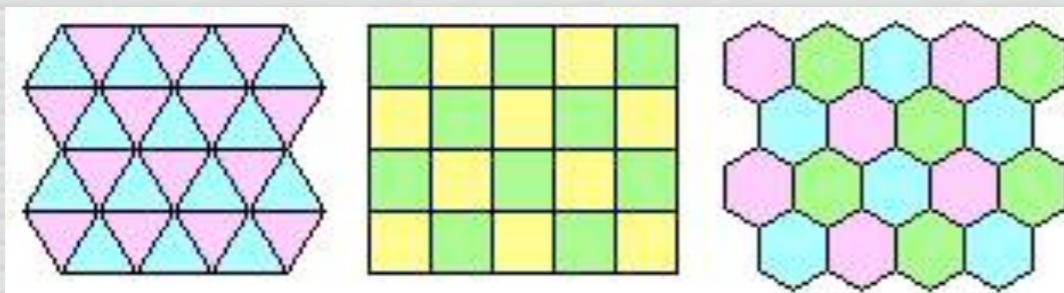
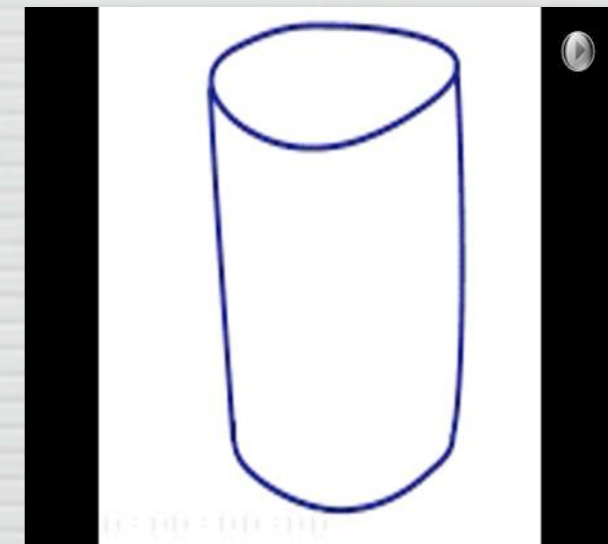
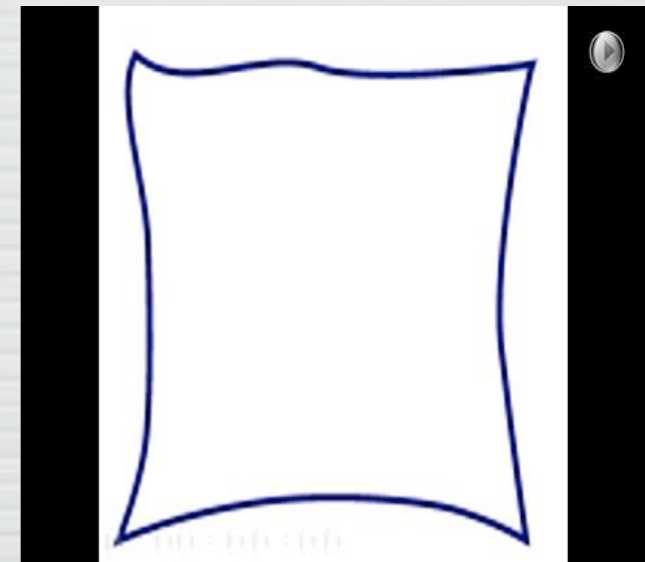
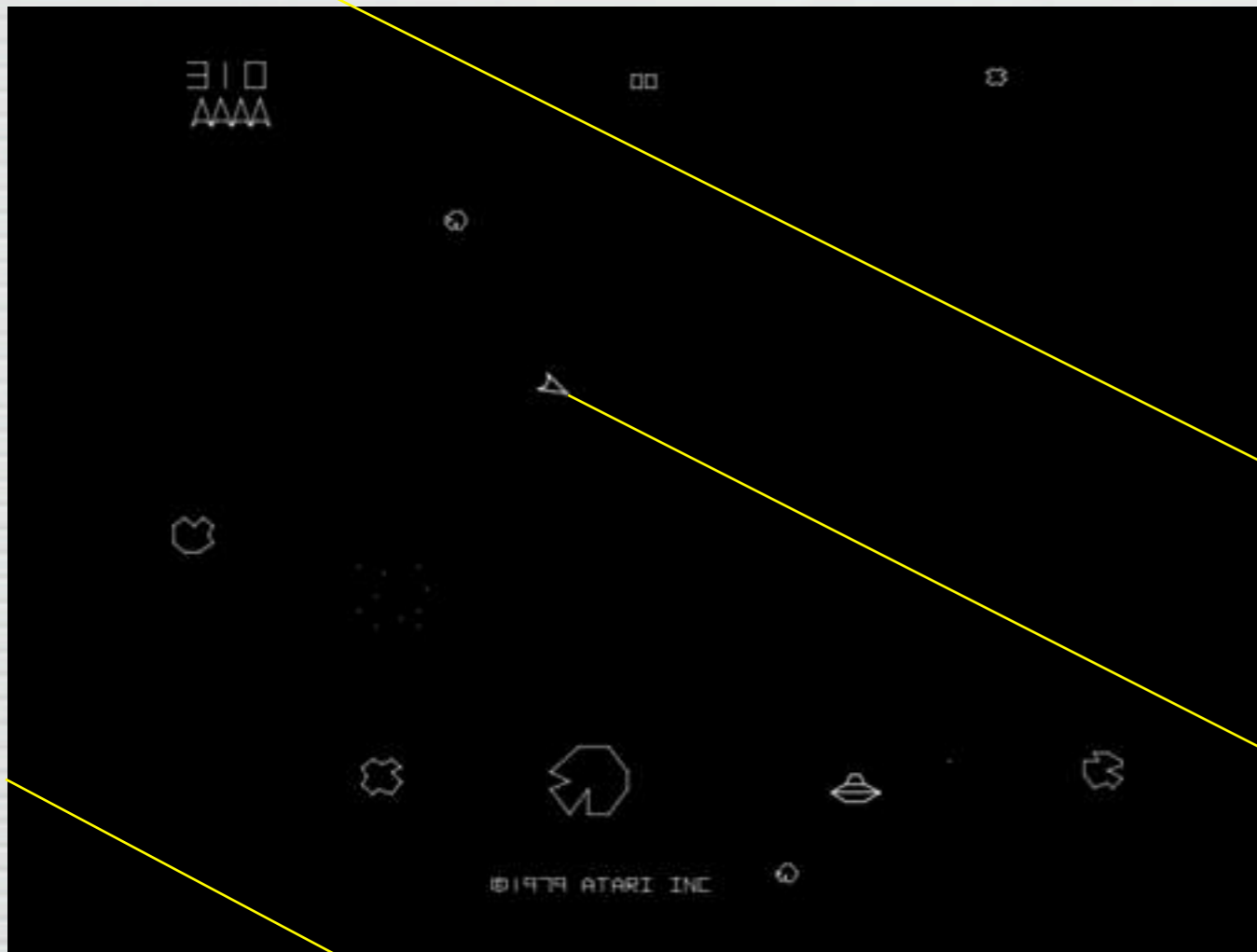
Topology in a flat “universe”



“tiling the plane”

Don't *need* to “embed” the square to have a connected topology.

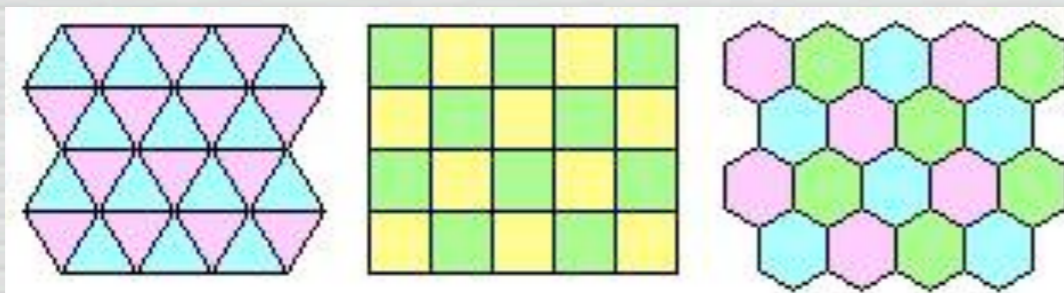
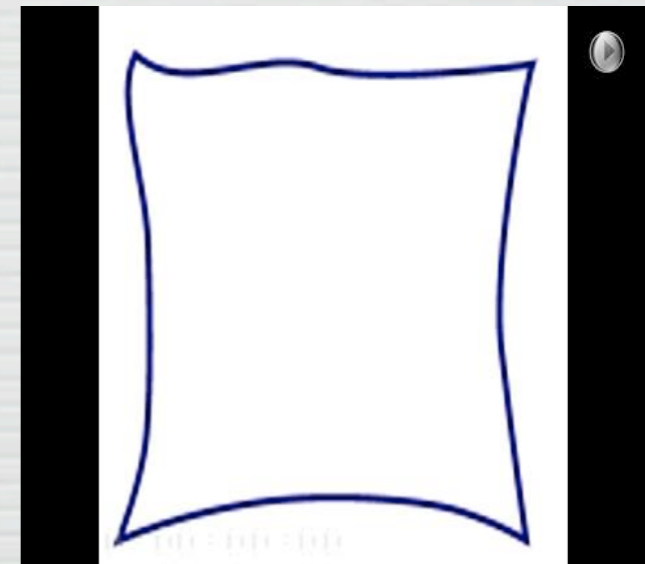
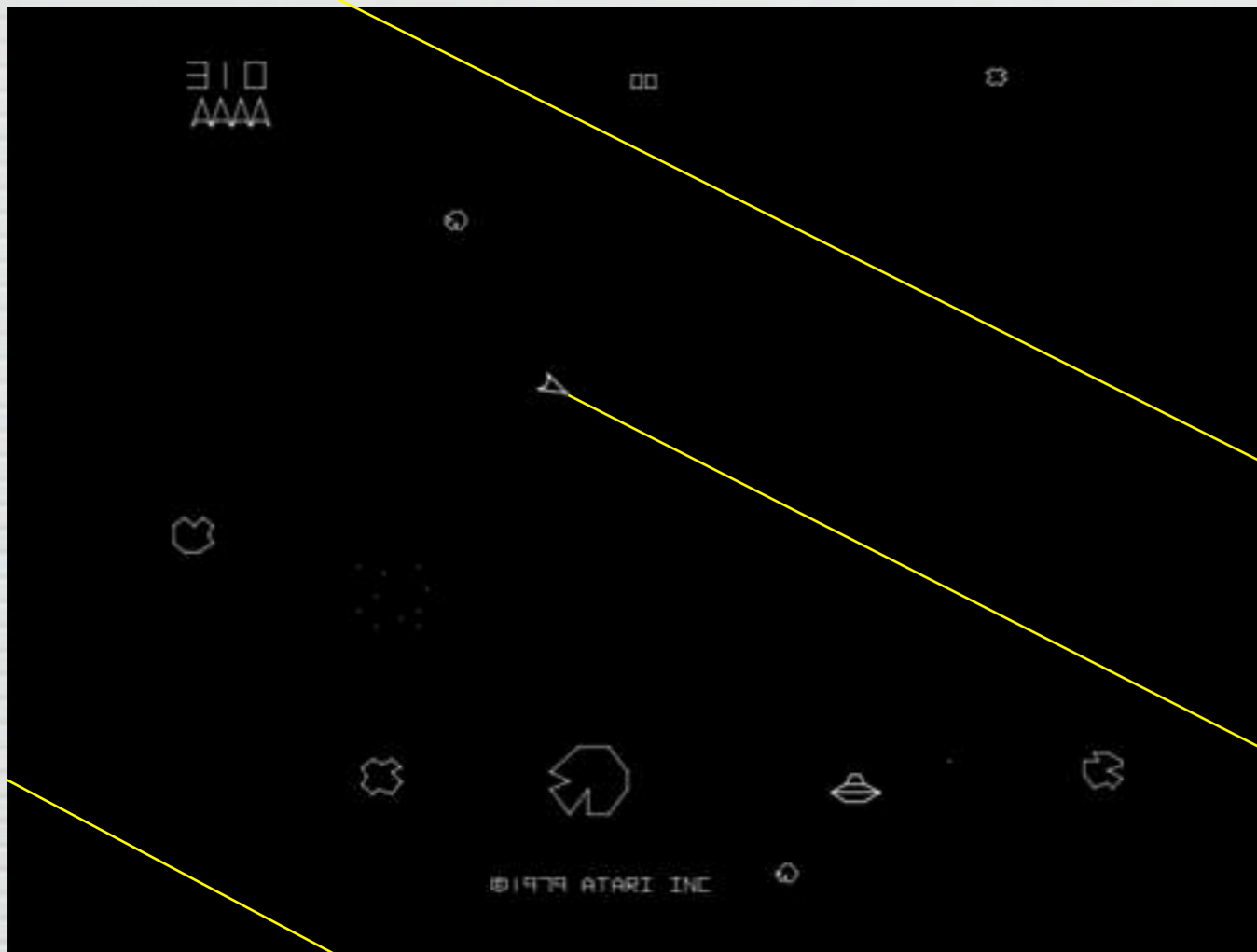
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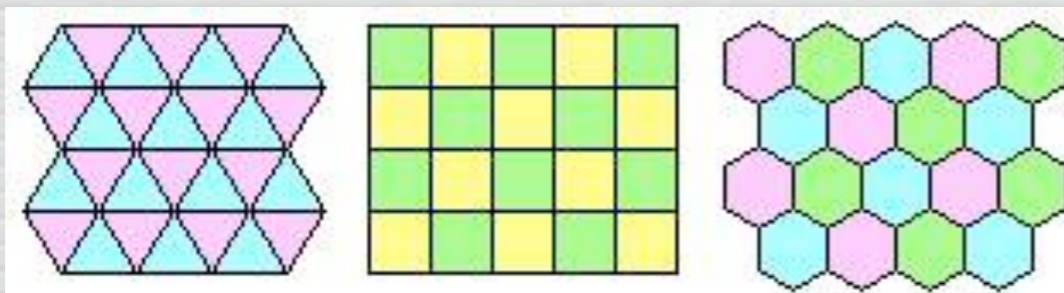
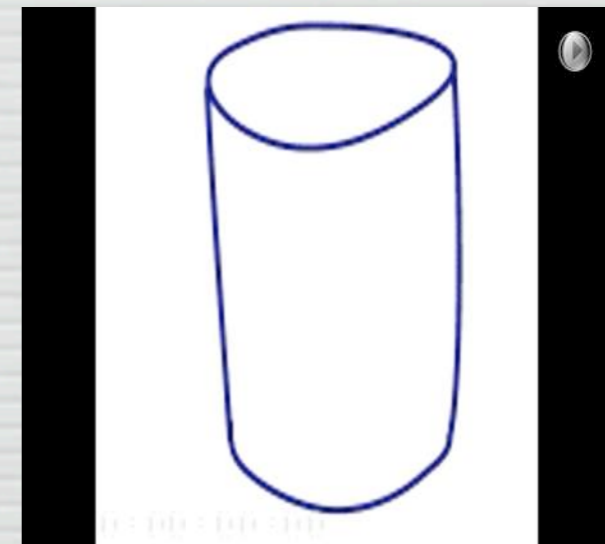
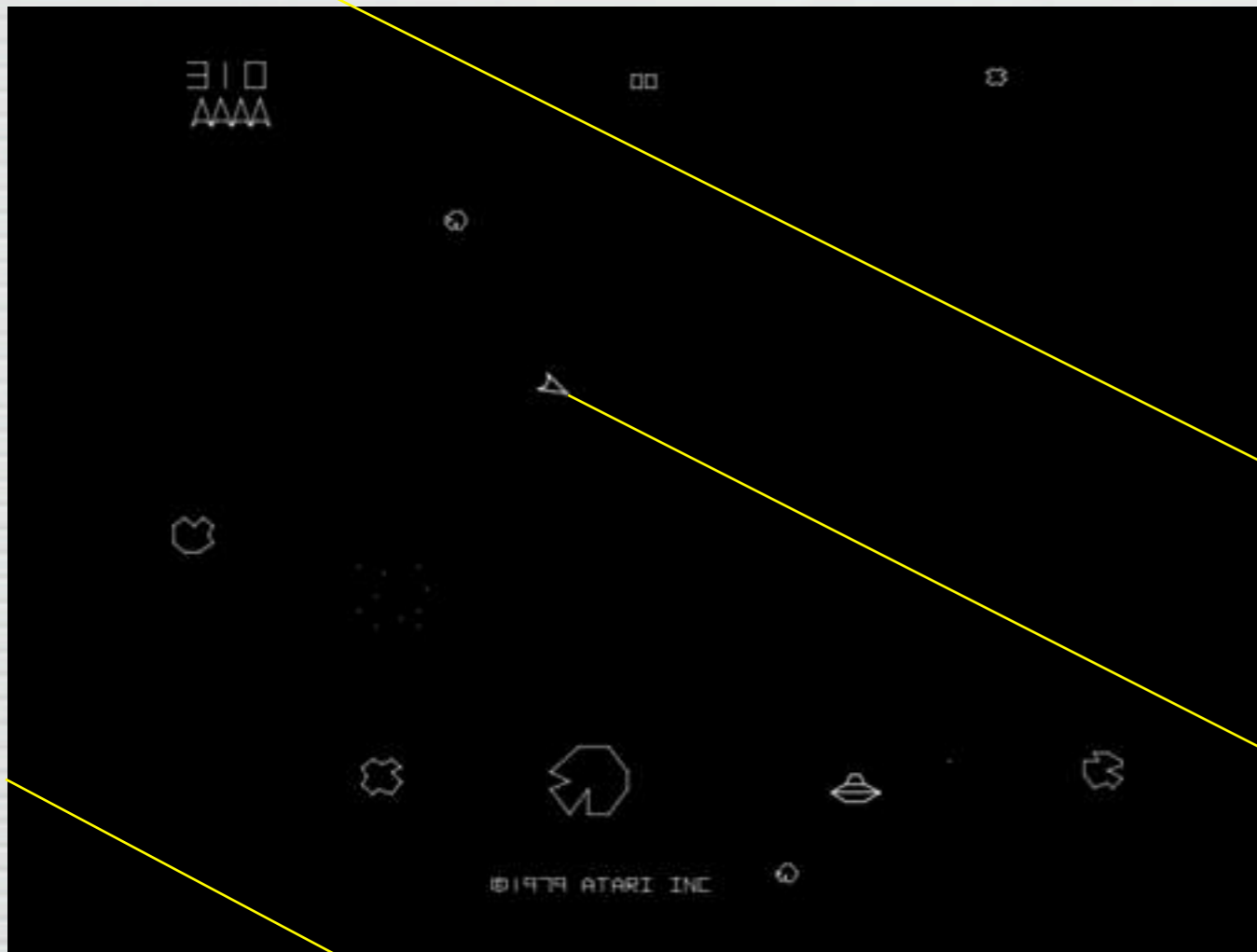
Topology in a flat “universe”



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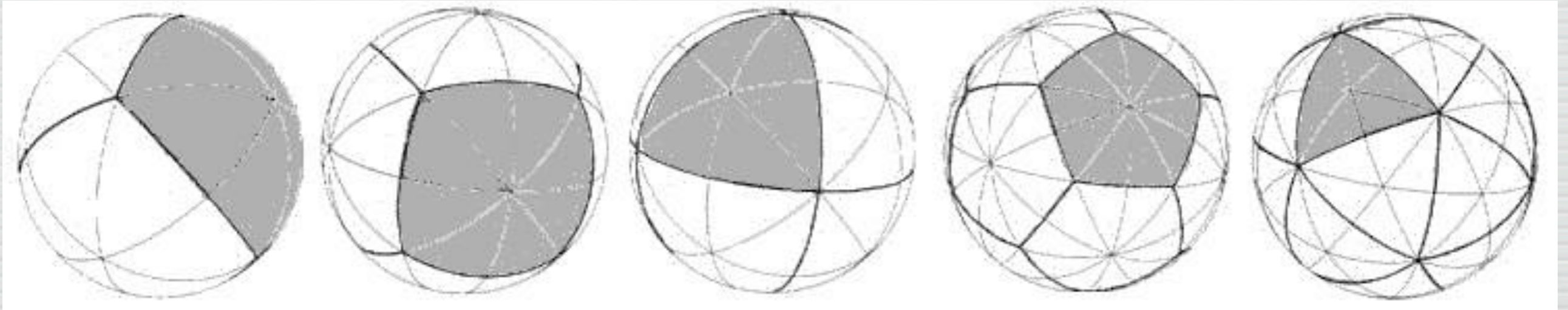
Topology in a flat “universe”



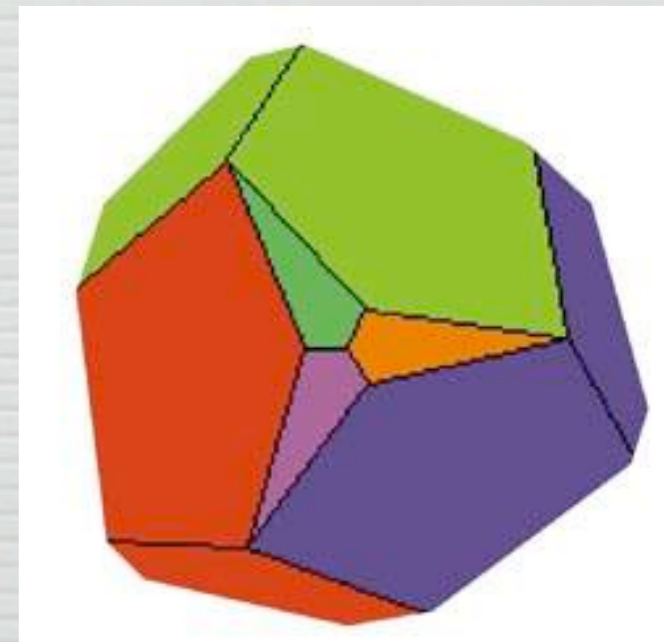
“tiling the plane”

Don't *need* to “embed” the square to have a connected topology.

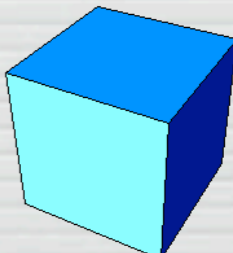
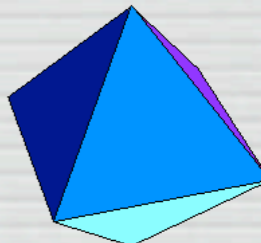
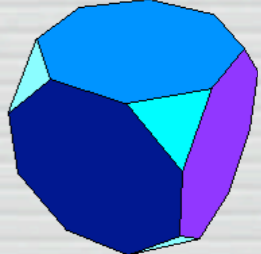
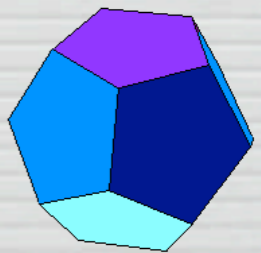
Topology + geometry



- Tile the 2-sphere with different **fundamental domains**
 - (Each of these has a 3-sphere analogy)
- **Can also tile the hyperbolic universe:**
 - (Bond, Pogosyan, etc.)

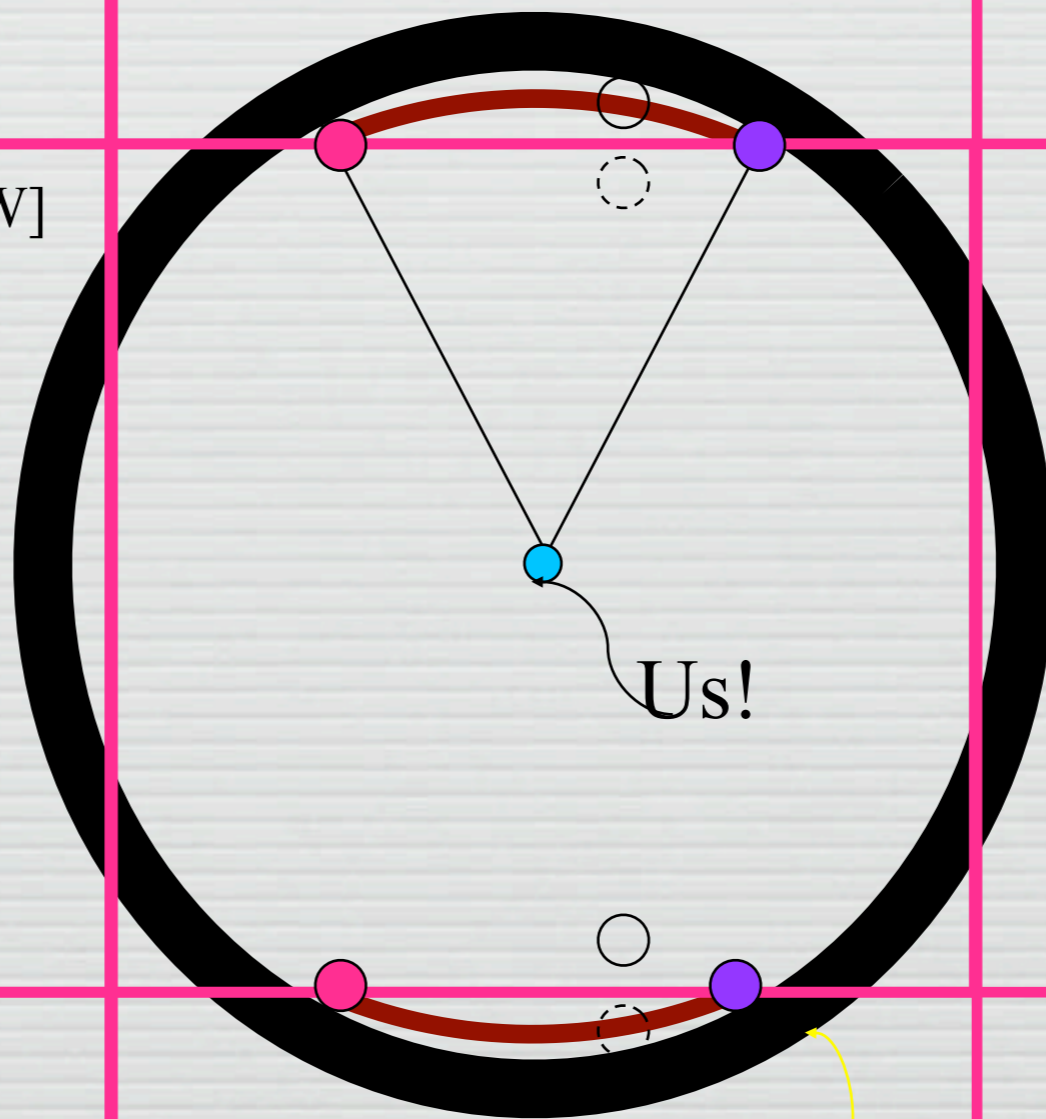


Multiply-connected Spherical Topologies

Space	Fundamental group	Order	Elements	F.P.
Quaternionic	Binary Dihedral	8	order 2 rotations about 2 perpendicular axes	
Octahedral	Binary Tetrahedral	24	symmetries of r. tetrahedron	
Truncated Cube	Binary Octahedral	48	symmetries of r. octahedron	
Poincaré	Binary Icosahedral	120	symmetries of r. icosahedron	

Measuring Topology with the CMB

- Perfect correlation [of SW]
- “circles in the sky”
- ○ finite-lag correlation



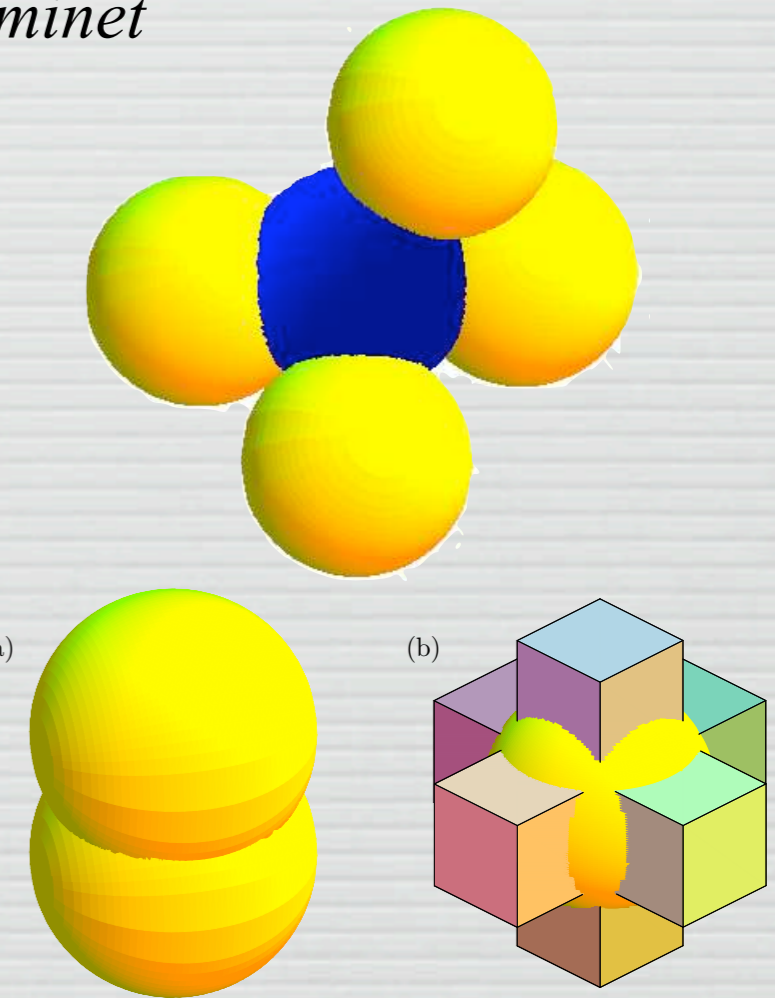
Last Scattering Surface

Topology in the CMB

- Look for repeated patterns
- **Generic** & **specific** methods
- **matching patches** (e.g., Levin et al)
 - method of images (e.g., Bond et al)
 - assumes infinitely thin LSS
 - mostly open Universes
- **Circles in the sky** (Cornish, Spergel, Starkman)^(a)
 - looks for LSS structure; ignores different views of the same point
 - nb. generic methods work as frequentist null tests but need comparison w/ specific topologies to get *statistics*
 - even Bayesians need to do exploratory statistics
 - Cornish et al '04: “fewer than 1 in 100 random skies generate a false match” [??]: limit out to 24 Gpc

Reviews:

Levin; Lachieze-Rey, Lehoucq, Luminet

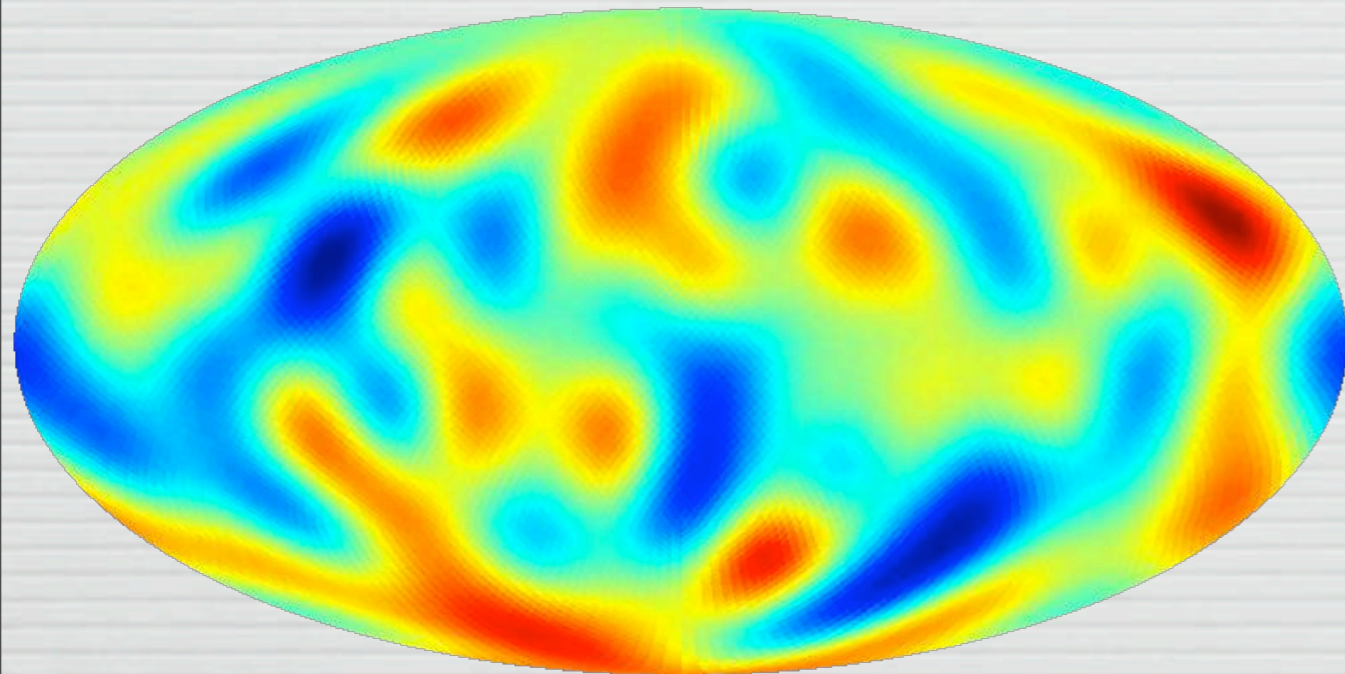


Topology: methods

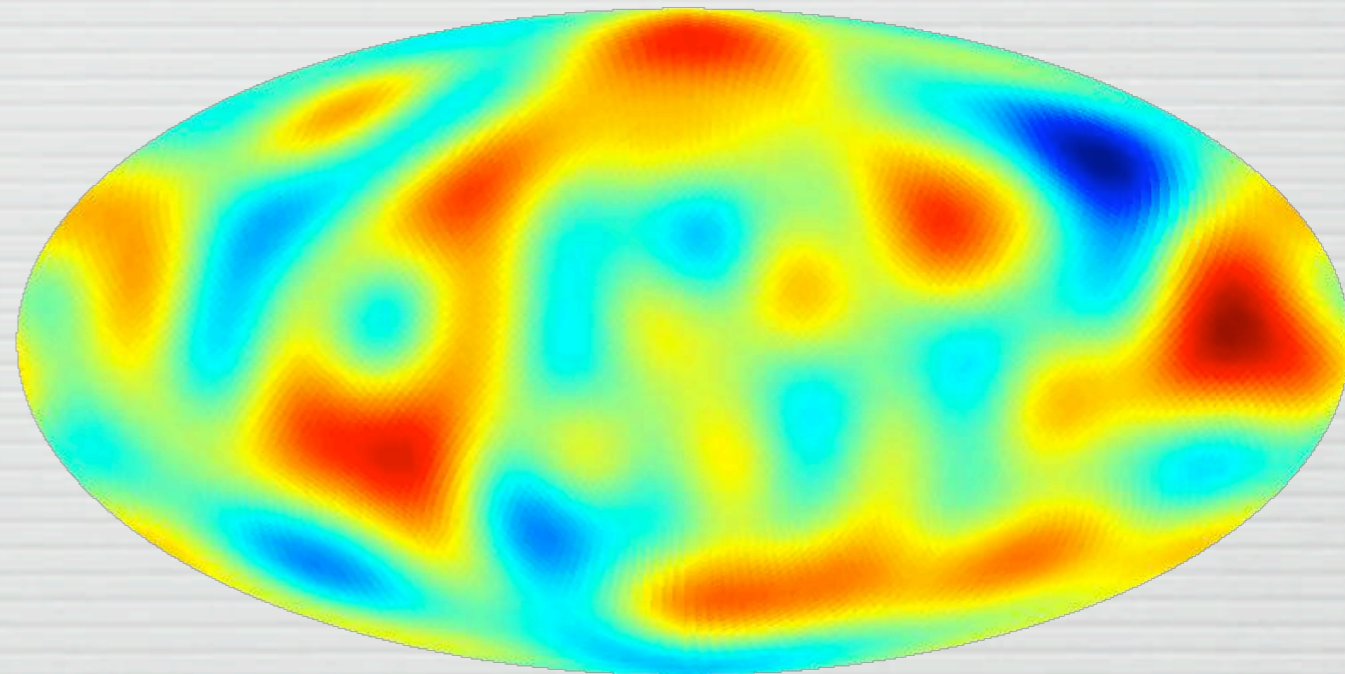
- When **topological scale** \approx **Horizon scale**, induce anisotropic correlations (and suppress power) on large scales
- Direct search for matched circles
 - sensitive to topology with parallel matched surfaces
- Explicit Likelihood
 - calculate correlation matrix for specific topologies.
 - 3d Gaussian with $\langle \delta_{\mathbf{k}} \delta_{\mathbf{k}'} \rangle = (2\pi)^3 \delta_{\mathbf{D}}(\mathbf{k} + \mathbf{k}') P(k)$ w/ k restricted to fundamental domain with boundary conditions
 - induced CMB correlations depend on topology (incl. orientation)

Simulated Maps ($\Omega_k = -0.063$)

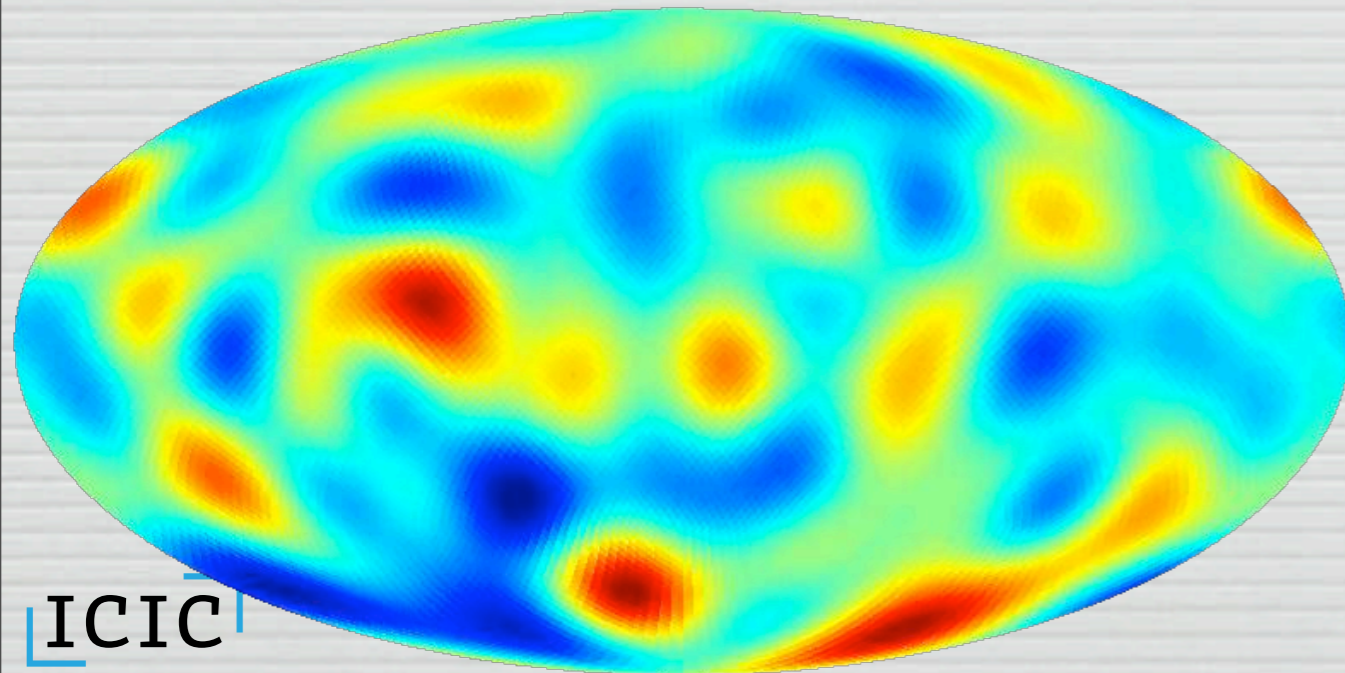
Quaternionic/bi-dehedral



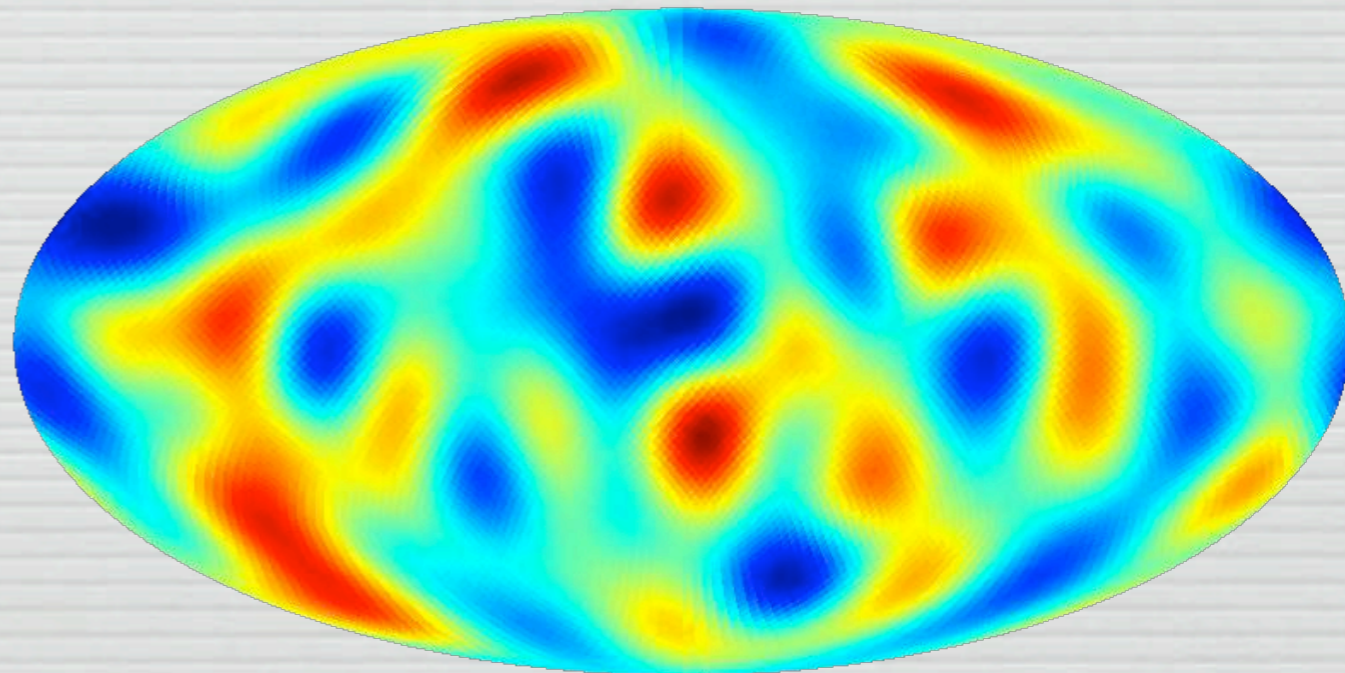
Octahedral/bi-tetrahedral



Truncated cube/bi-octahedral



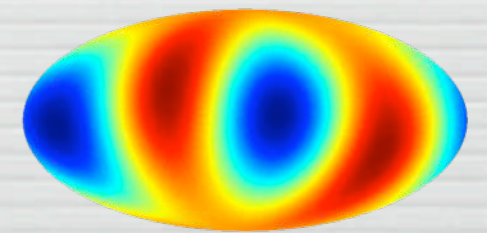
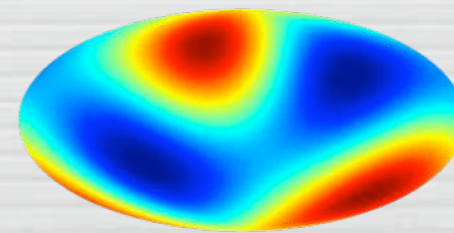
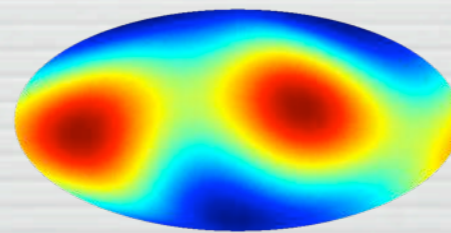
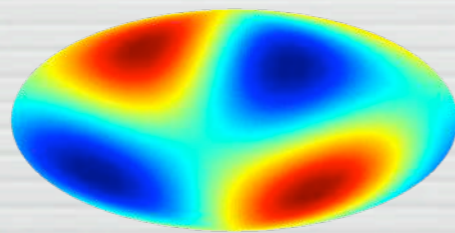
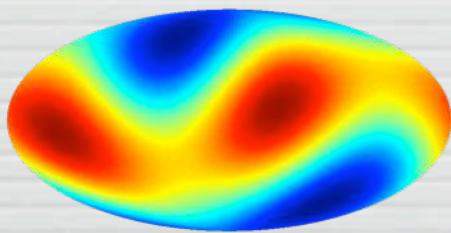
Poincaré/icosahedral



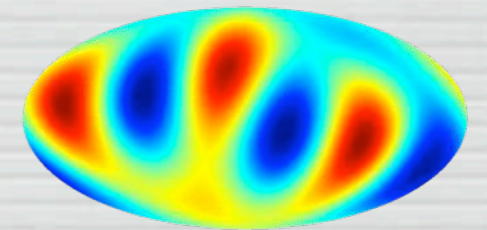
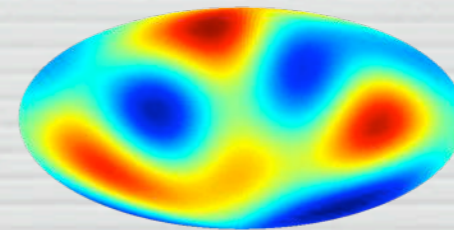
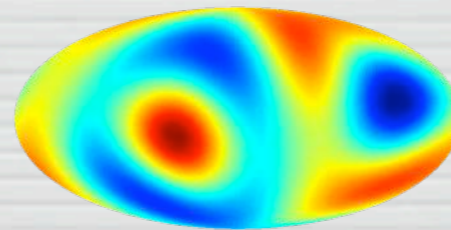
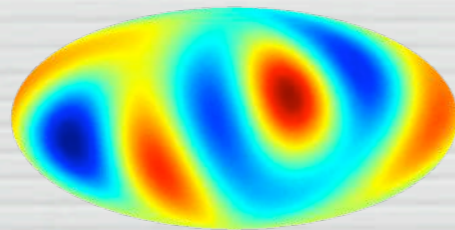
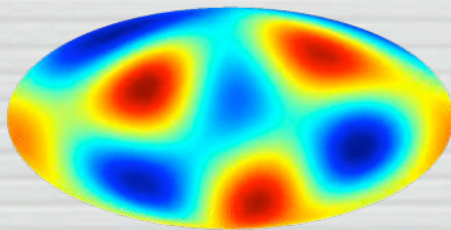
Lowest multipoles

Quaternionic Octahedral Truncated cube Poincaré WMAP

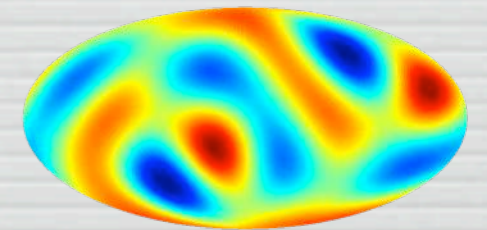
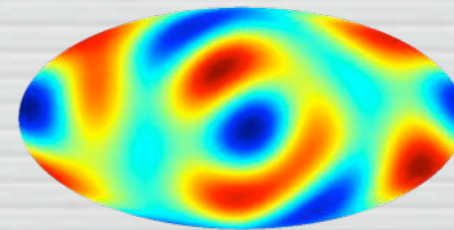
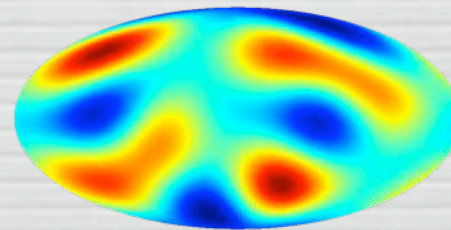
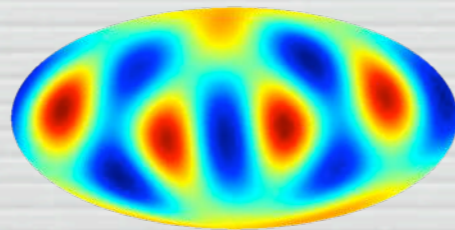
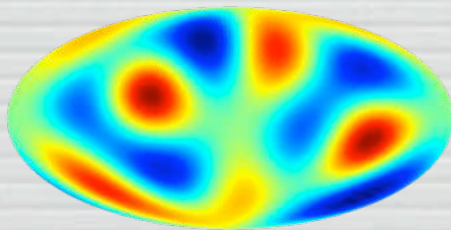
$\ell=2$



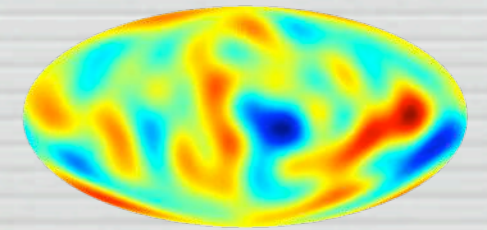
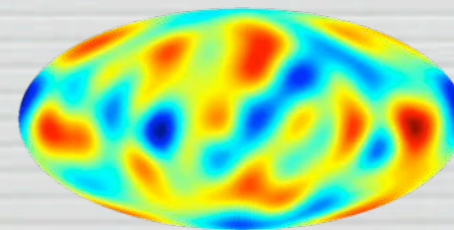
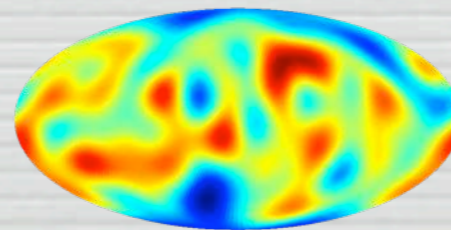
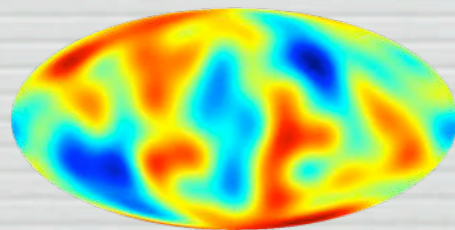
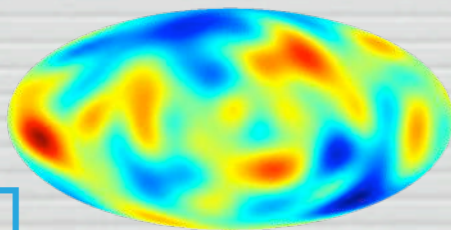
$\ell=3$



$\ell=4$



all



Bayesian topology

$$P(a|C) = \frac{1}{|2\pi C|^{1/2}} \exp\left(-\frac{1}{2}a^T C^{-1}a\right)$$

□ Full **correlation matrix**:

□ $C = \langle a_{\ell m} a_{\ell' m'} \rangle = C_{\ell\ell' mm'} = C(\text{cosmology, topology})$

□ $C_{\ell\ell'}^{mm'} \propto \int d^3k \Delta_\ell(k, \Delta\eta) \Delta_{\ell'}(k, \Delta\eta) P(k) \rightarrow$
 $\sum_{\mathbf{n}} \Delta_\ell(k_n, \Delta\eta) \Delta_{\ell'}(k_n, \Delta\eta) P(k_n) Y_{\ell m}(\hat{\mathbf{n}}) Y_{\ell' m'}^*(\hat{\mathbf{n}}),$

□ $a = a_{\ell m}$

- (Noise irrelevant on scales of interest)
- Suppressed power \Rightarrow stronger correlations

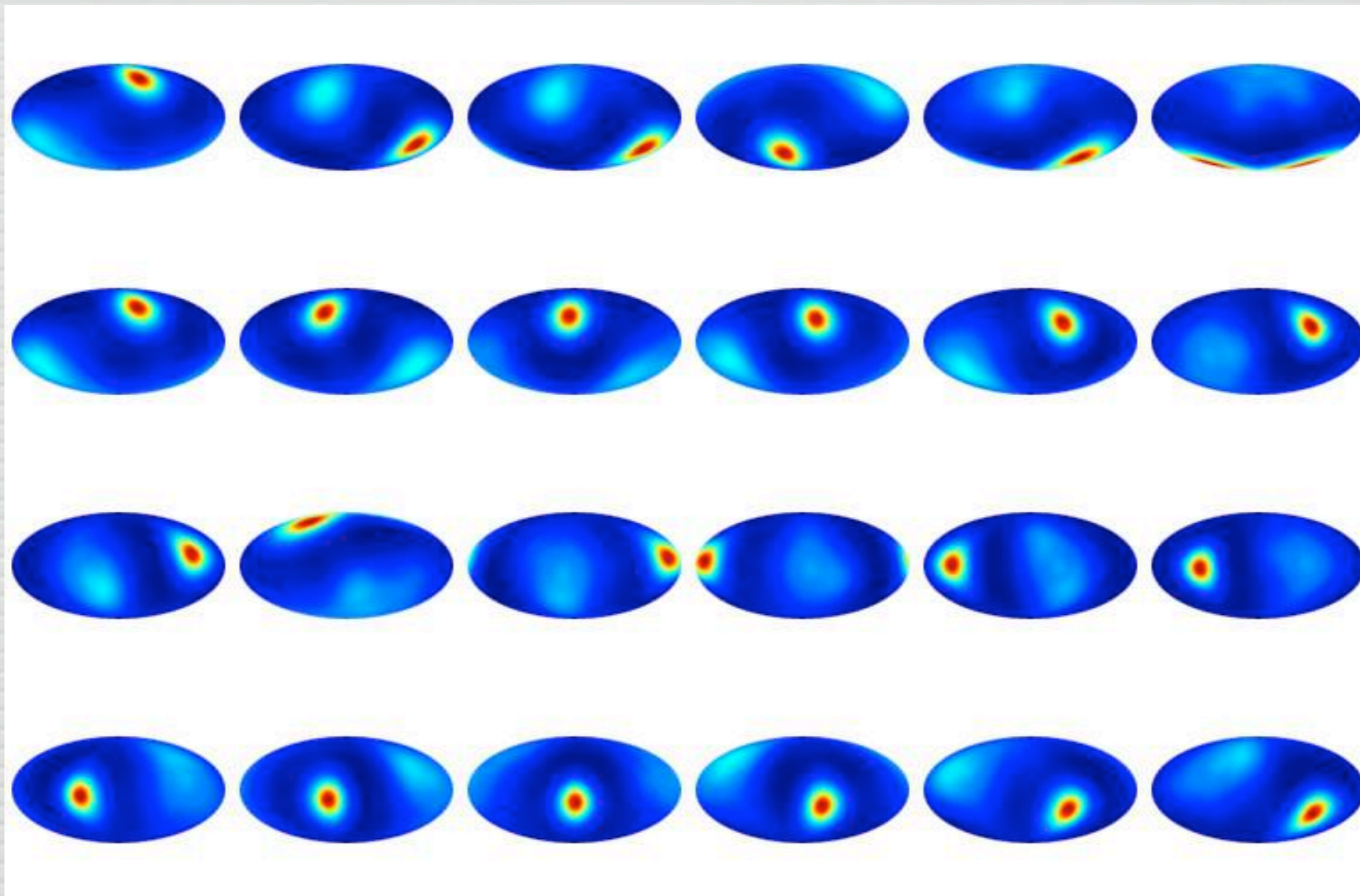
Pixel correlations

□ Octahedral: $C_{pp'} = \left\langle \frac{\Delta T}{T}(\hat{x}_p) \frac{\Delta T}{T}(\hat{x}_{p'}) \right\rangle = \sum_{\ell\ell'mm'} C_{\ell\ell'mm'} B_\ell B_{\ell'} Y_{\ell m}(\hat{x}_p) Y_{\ell' m'}(\hat{x}_{p'})$

■ $h=0.64, \Omega_k = -0.017$

~~$\rightarrow \sum_{\ell} \frac{2\ell+1}{4\pi} C_{\ell} B_{\ell}^2 P_{\ell}(\hat{x}_p \cdot \hat{x}_{p'})$~~

Rows of the correlation matrix:



Pixel correlations

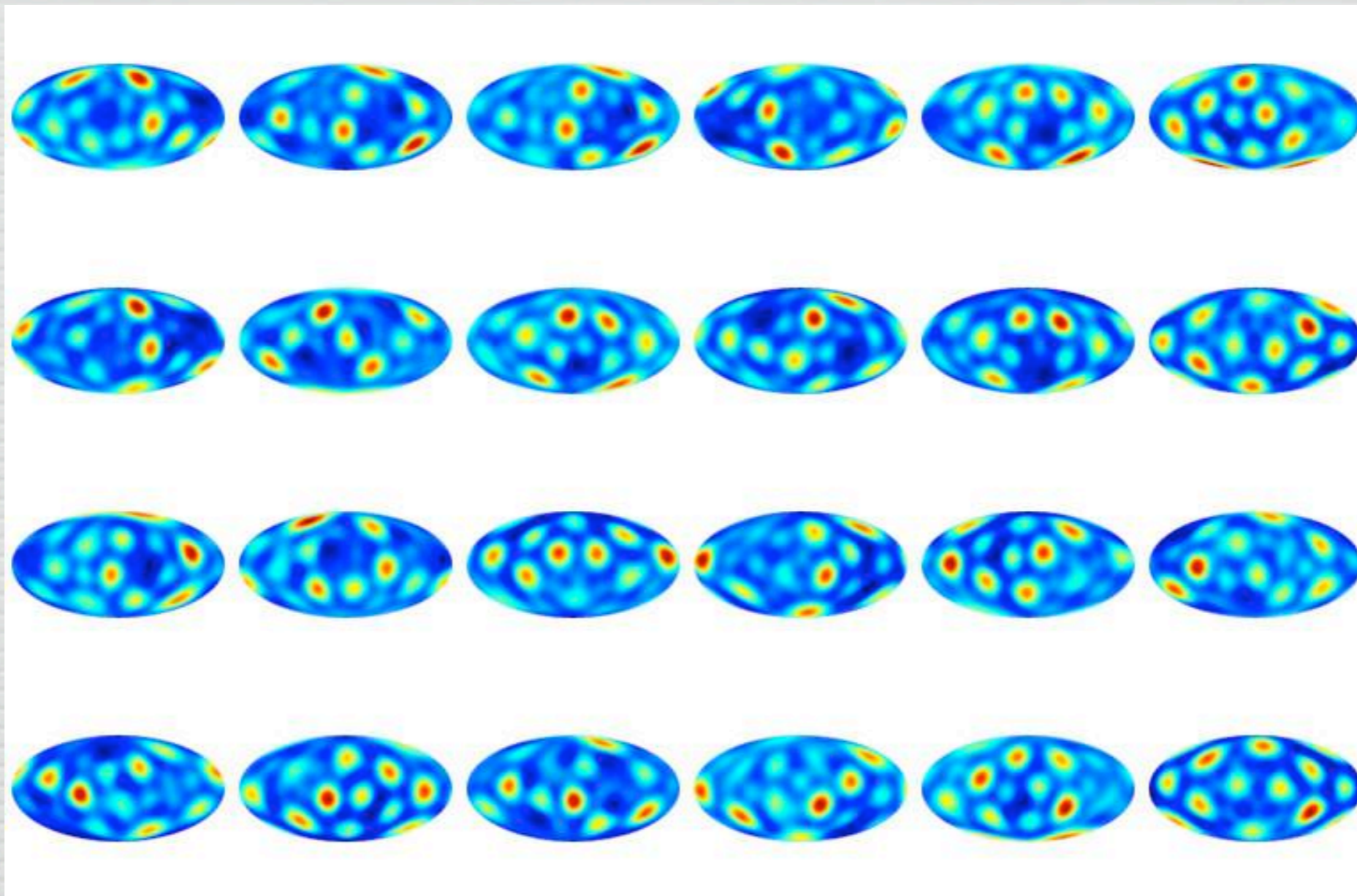
□ Poincaré:

$$C_{pp'} = \left\langle \frac{\Delta T}{T}(\hat{x}_p) \frac{\Delta T}{T}(\hat{x}_{p'}) \right\rangle = \sum_{\ell\ell'mm'} C_{\ell\ell'mm'} B_\ell B_{\ell'} Y_{\ell m}(\hat{x}_p) Y_{\ell' m'}(\hat{x}_{p'})$$

■ $h=0.52, \Omega_k = -0.063$

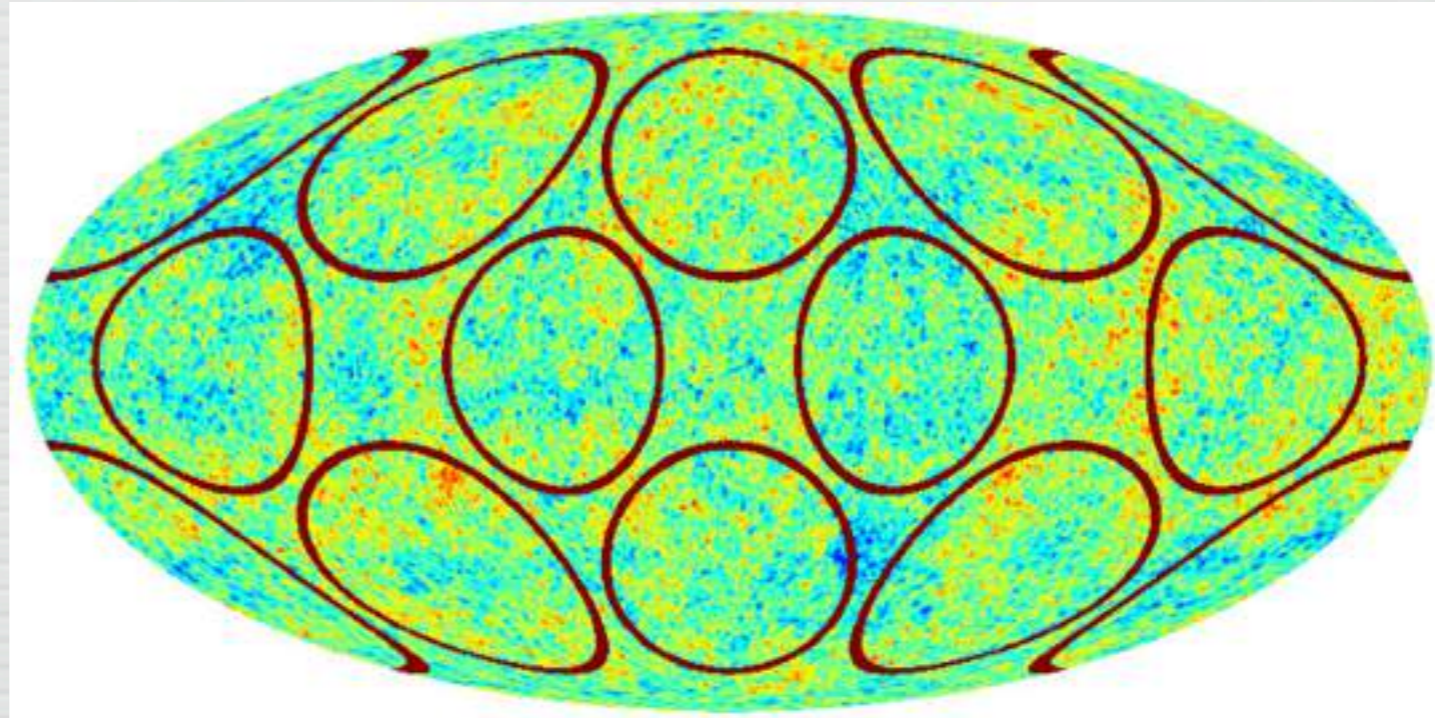
$$\rightarrow \sum_{\ell} \frac{2\ell+1}{4\pi} C_{\ell} B_{\ell}^2 P_{\ell}(\hat{x}_p \cdot \hat{x}_{p'})$$

Rows of the correlation matrix:



Topology from Planck

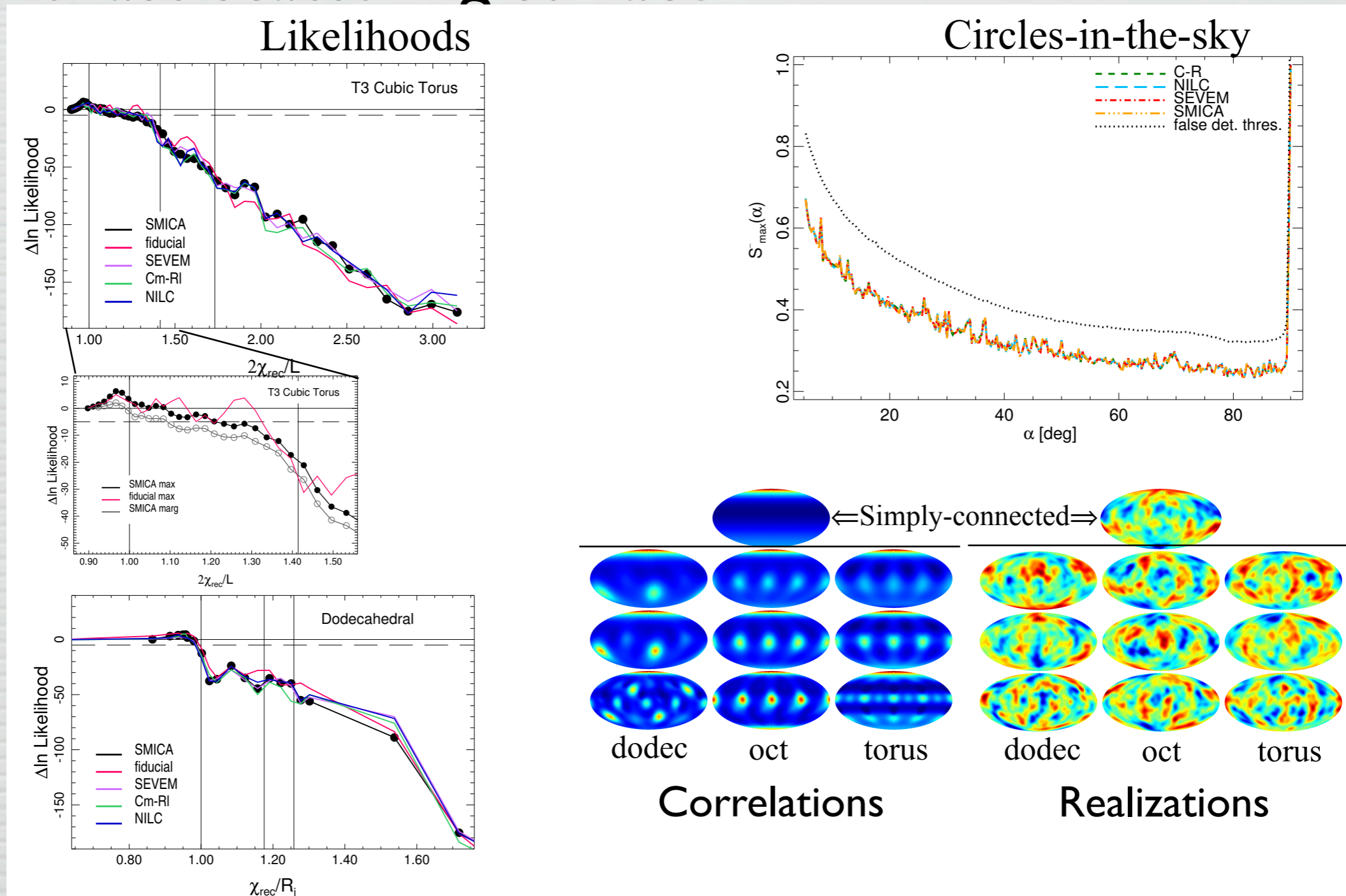
- “Matched circles” in a simulated Universe:



- Alas, not found... we can limit the size of the “fundamental cube” to be greater than the size of the surface we observe with the CMB:
 - side $L \gtrsim 26$ Gpc

Topology: results

- No strong evidence for topology on the scale of the last-scattering surface

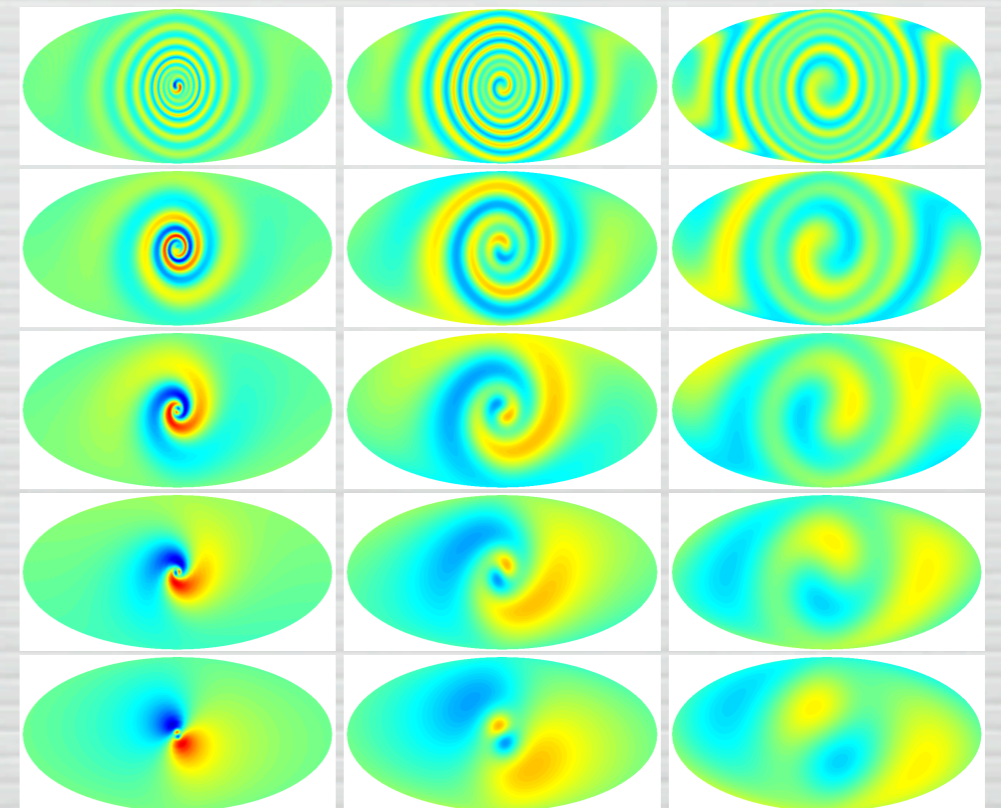


Bianchi Models

- Homogeneous, anisotropic spaces
- VII_h : global shear and rotation
 - parameter h relates vorticity ω_i to shear σ_{ij} , Ω_{tot}

$$\left(\frac{\omega}{H}\right)_0 = \frac{(1+h)^{1/2}(1+9h)^{1/2}}{6h} \frac{1-\Omega_{\text{tot}}}{\Omega_{\text{tot}}} \sqrt{\left(\frac{\sigma_{12}}{H}\right)_0^2 + \left(\frac{\sigma_{13}}{H}\right)_0^2}$$

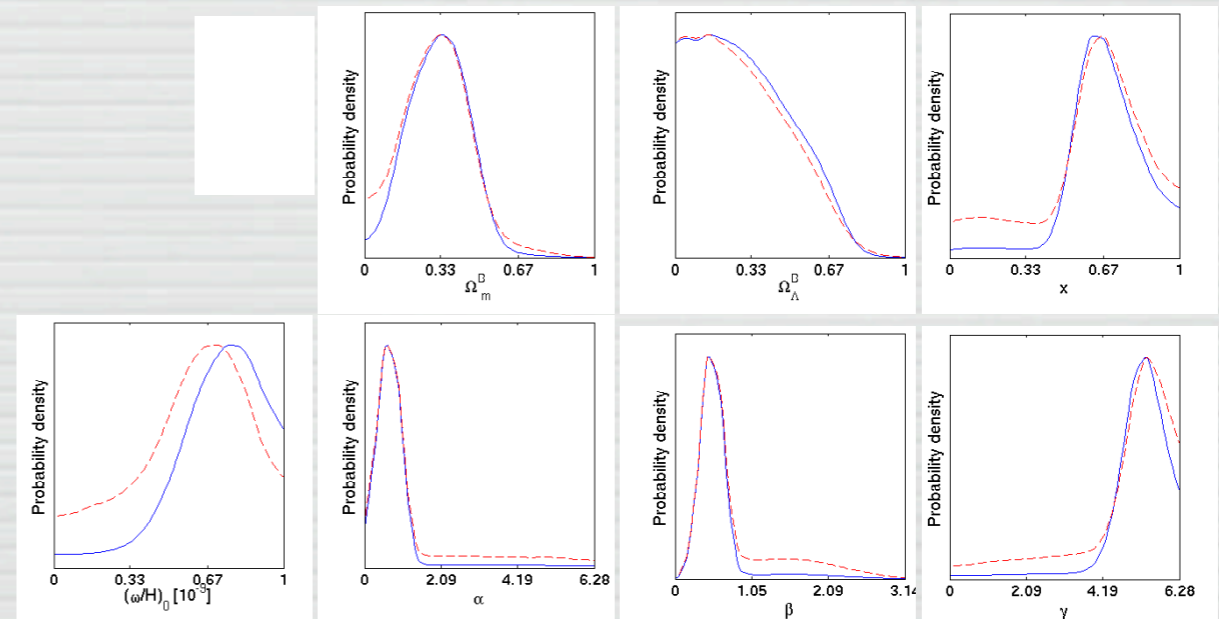
- Focusing induces specific pattern of temperature anisotropy on large scales
- Full likelihood calculation (Gaussian added to deterministic template)
 - consistent cosmology very low likelihood



Bianchi Models

Flat-decoupled

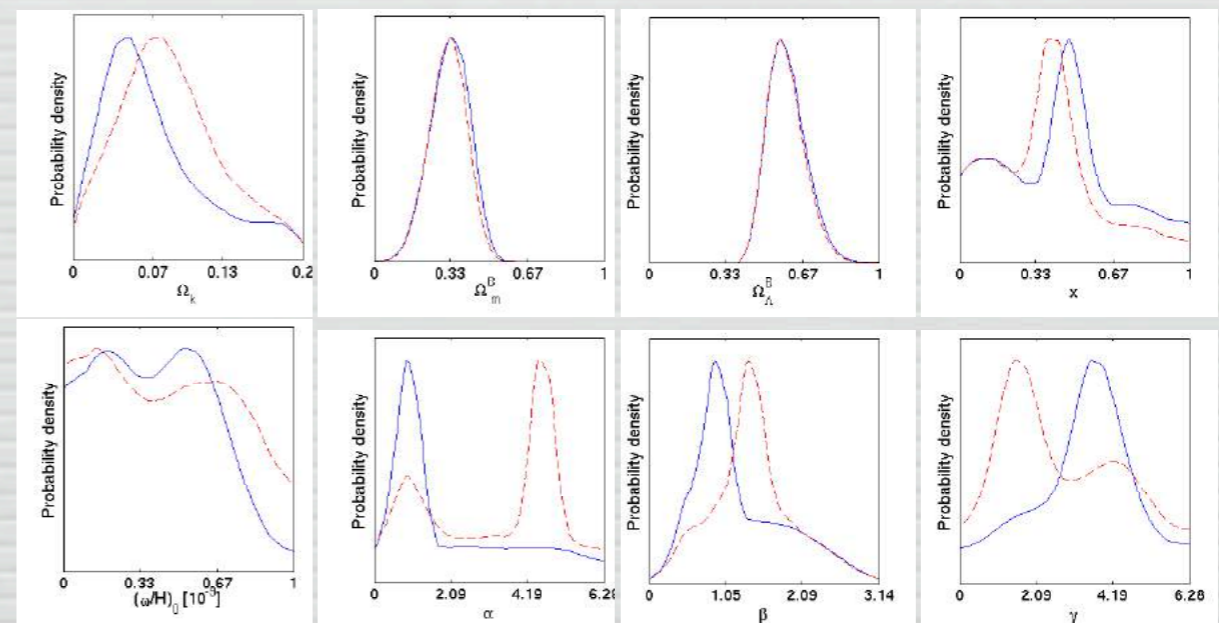
Bianchi Parameter	SMICA		SEVEM	
	MAP	Mean	MAP	Mean
Ω_m^B	0.38	0.32 ± 0.12	0.35	0.31 ± 0.15
Ω_Λ^B	0.20	0.31 ± 0.20	0.22	0.30 ± 0.20
x	0.63	0.67 ± 0.16	0.66	0.62 ± 0.23
$(\omega/H)_0$	8.8×10^{-10}	$(7.1 \pm 1.9) \times 10^{-10}$	9.4×10^{-10}	$(5.9 \pm 2.4) \times 10^{-10}$
α	38.8°	$51.3^\circ \pm 47.9^\circ$	40.5°	$77.4^\circ \pm 80.3^\circ$
β	28.2°	$33.7^\circ \pm 19.7^\circ$	28.4°	$45.6^\circ \pm 32.7^\circ$
γ	309.2°	$292.2^\circ \pm 51.9^\circ$	317.0°	$271.5^\circ \pm 80.7^\circ$



(a) Flat-decoupled-Bianchi model.

Open-coupled

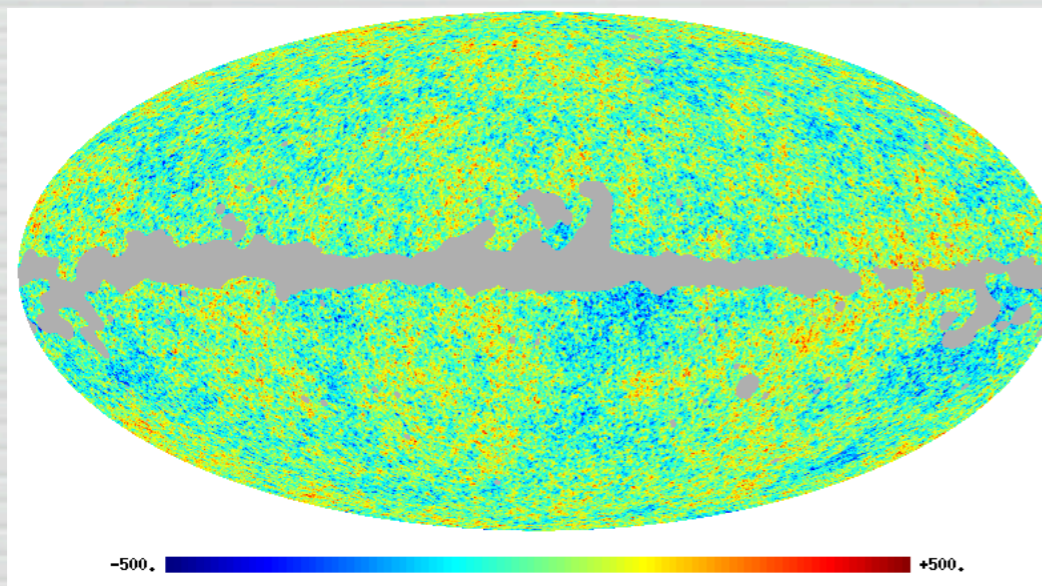
Bianchi Parameter	SMICA		SEVEM	
	MAP	Mean	MAP	Mean
Ω_k	0.05	0.07 ± 0.05	0.09	0.08 ± 0.04
Ω_m^B	0.41	0.33 ± 0.07	0.41	0.32 ± 0.07
Ω_Λ^B	0.55	0.60 ± 0.07	0.50	0.59 ± 0.07
x	0.46	0.44 ± 0.24	0.38	0.39 ± 0.22
$(\omega/H)_0$	5.9×10^{-10}	$(4.0 \pm 2.4) \times 10^{-10}$	9.3×10^{-10}	$(4.5 \pm 2.8) \times 10^{-10}$
α	57.4°	$122.5^\circ \pm 96.0^\circ$	264.1°	$188.6^\circ \pm 98.7^\circ$
β	54.1°	$70.8^\circ \pm 35.5^\circ$	79.6°	$81.1^\circ \pm 31.7^\circ$
γ	202.6°	$193.5^\circ \pm 77.4^\circ$	90.6°	$160.4^\circ \pm 91.1^\circ$



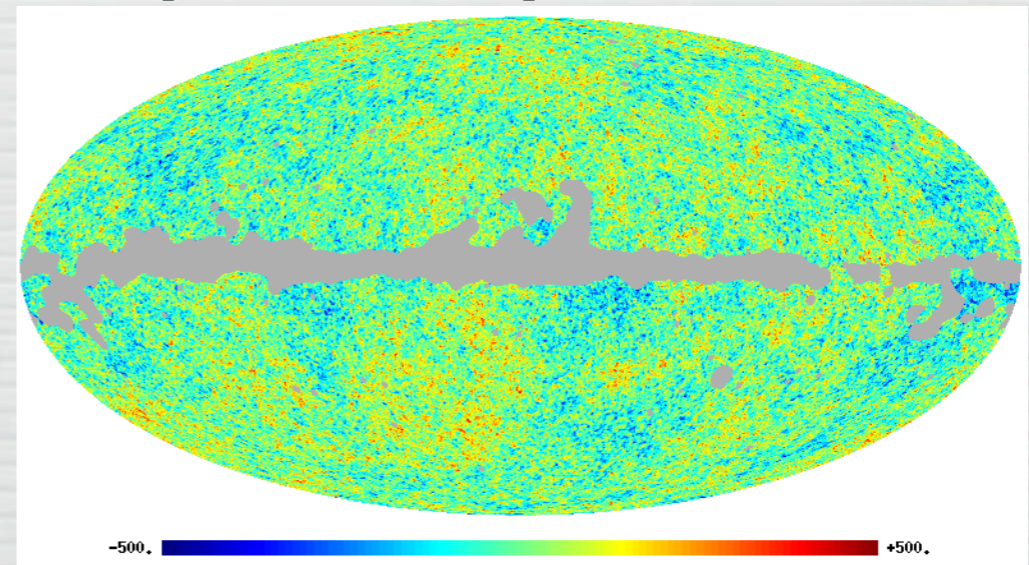
(b) Open-coupled-Bianchi model.

Flat-coupled: $\omega_0/H_0 < 8.1 \times 10^{-10}$ (95%)

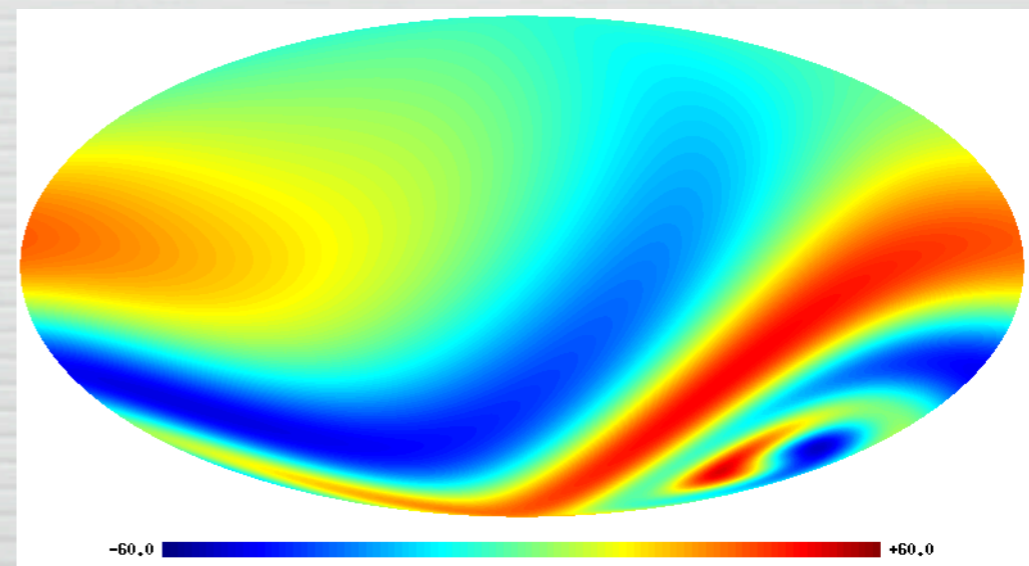
- The Bianchi VII_h uncoupled “model” accounts for much of the hemispherical asymmetry



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Non-gaussianity

- Another way to go beyond (and check) the simple assumptions
- In general, can't write down "the" distribution for a parameter with some specific set of higher-order moments. (cf. yesterday's discussion of Gaussian as MaxEnt)
- Use frequentist estimators...
- In the absence of a specific model, want to determine phenomenological parameters describing departure from an isotropic multivariate gaussian distribution.
 - e.g., moments — but not unique (there is no distribution that has mean, variance, skewness, but no higher moments)
 - for (suitably defined) small non-gaussianity, third-order moments should dominate
 - full determination of 3-pt function is computationally infeasible (and we lack sufficient S/N)
 - parameterize non-gaussianity

non-Gaussianity: f_{NL}

- Heuristically $\phi = \phi_G + f_{\text{NL}}(\phi_G^2 - \langle \phi_G^2 \rangle)$
for a Gaussian ϕ_G (e.g., multi-field inflation)

- This is the (spatially) local model for non-Gaussianity
- Induces specific 3-d correlations

$$\begin{aligned}\langle \phi\phi\phi \rangle &\sim 3f_{\text{NL}} (\langle \phi_G\phi_G\phi_G\phi_G \rangle - \langle \phi_G\phi_G \rangle \langle \phi_G\phi_G \rangle) + O(f_{\text{NL}}^2) \\ &\sim 6f_{\text{NL}} \langle \phi_G\phi_G \rangle \langle \phi_G\phi_G \rangle + O(f_{\text{NL}}^2)\end{aligned}$$

and hence 2-d correlations in the CMB

- Corresponds to Fourier bispectrum $B(k_1, k_2, k_3)$ which peaks in squeezed case $k_1 \ll k_2 \approx k_3$

- modulate small-scale structure by large-scale modes
 - cf. galaxy bias

- More generally, consider other shapes (e.g., equilateral) motivated by specific theories

Estimating non-Gaussianity

$$\langle a_{\ell_1 m_1} a_{\ell_2 m_2} a_{\ell_2 m_2} \rangle = \mathcal{G}_{m_1 m_2 m_3}^{\ell_1 \ell_2 \ell_3} b_{\ell_1 \ell_2 \ell_3} = \mathcal{G}_{m_1 m_2 m_3}^{\ell_1 \ell_2 \ell_3} h_{\ell_1 \ell_2 \ell_3}^{-2} B_{\ell_1 \ell_2 \ell_3}$$

- Expect to be able to estimate the third moment by taking some weights average over cubic products of data
- (cf. quadratic estimators of power spectra)
 - “optimal” (min-var) weights computationally infeasible (Heavens 1998) — average over *all* triples of data
 - ignoring off-diagonal covariance gives somewhat more tractable case (Creminelli et al. 2006).
 - further simplify for “separable” shapes (Komatsu et al.=KSW) and linear combinations thereof (Fergusson & Shellard)
 - generalize to $S_\ell = \text{skew-}C_\ell$, retains shape information in one ℓ direction (Heavens & Munshi)

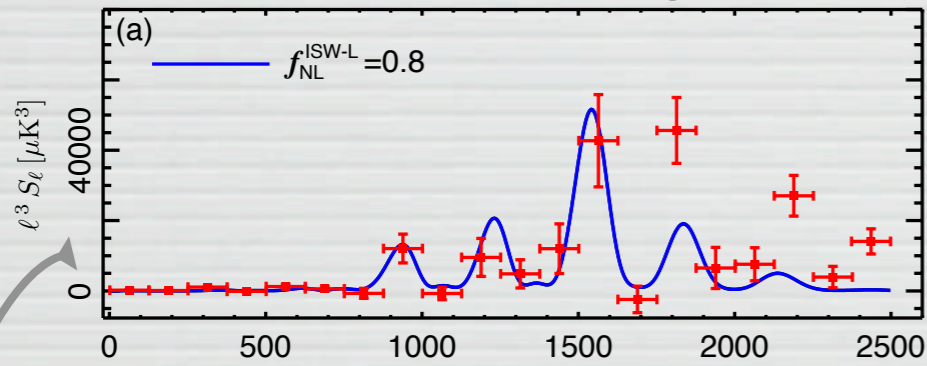
Non-Gaussianity from Planck

- Planck detects (non-Primordial) non-Gaussianity...

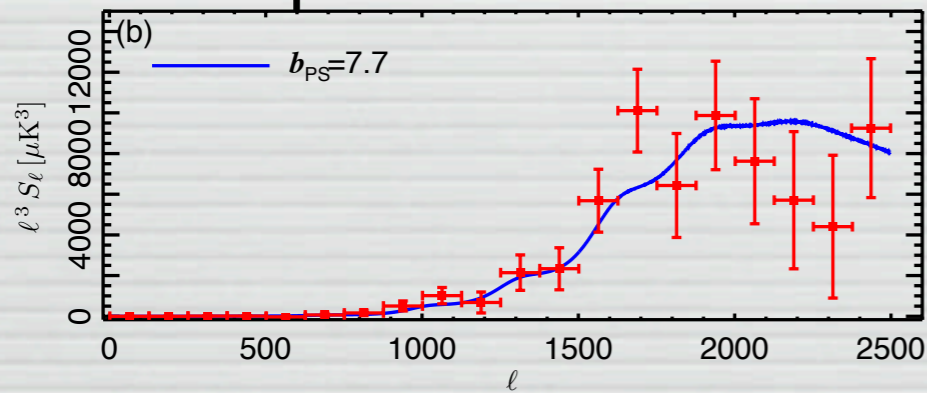
	Independent				ISW-lensing subtracted		
	KSW	Binned	Modal		KSW	Binned	Modal
SMICA							
Local	9.8 ± 5.8	9.2 ± 5.9	8.3 ± 5.9	2.7 ± 5.8	2.2 ± 5.9	1.6 ± 6.0
Equilateral	-37 ± 75	-20 ± 73	-20 ± 77	-42 ± 75	-25 ± 73	-20 ± 77
Orthogonal	-46 ± 39	-39 ± 41	-36 ± 41	-25 ± 39	-17 ± 41	-14 ± 42
NILC							
Local	11.6 ± 5.8	10.5 ± 5.8	9.4 ± 5.9	4.5 ± 5.8	3.6 ± 5.8	2.7 ± 6.0
Equilateral	-41 ± 76	-31 ± 73	-20 ± 76	-48 ± 76	-38 ± 73	-20 ± 78
Orthogonal	-74 ± 40	-62 ± 41	-60 ± 40	-53 ± 40	-41 ± 41	-37 ± 43
SEVEM							
Local	10.5 ± 5.9	10.1 ± 6.2	9.4 ± 6.0	3.4 ± 5.9	3.2 ± 6.2	2.6 ± 6.0
Equilateral	-32 ± 76	-21 ± 73	-13 ± 77	-36 ± 76	-25 ± 73	-13 ± 78
Orthogonal	-34 ± 40	-30 ± 42	-24 ± 42	-14 ± 40	-9 ± 42	-2 ± 42
C-R							
Local	12.4 ± 6.0	11.3 ± 5.9	10.9 ± 5.9	6.4 ± 6.0	5.5 ± 5.9	5.1 ± 5.9
Equilateral	-60 ± 79	-52 ± 74	-33 ± 78	-62 ± 79	-55 ± 74	-32 ± 78
Orthogonal	-76 ± 42	-60 ± 42	-63 ± 42	-57 ± 42	-41 ± 42	-42 ± 42

Non-Gaussianity from Planck

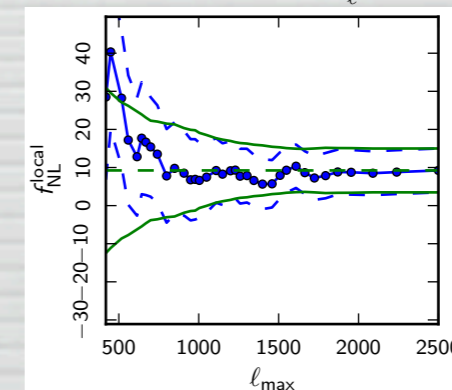
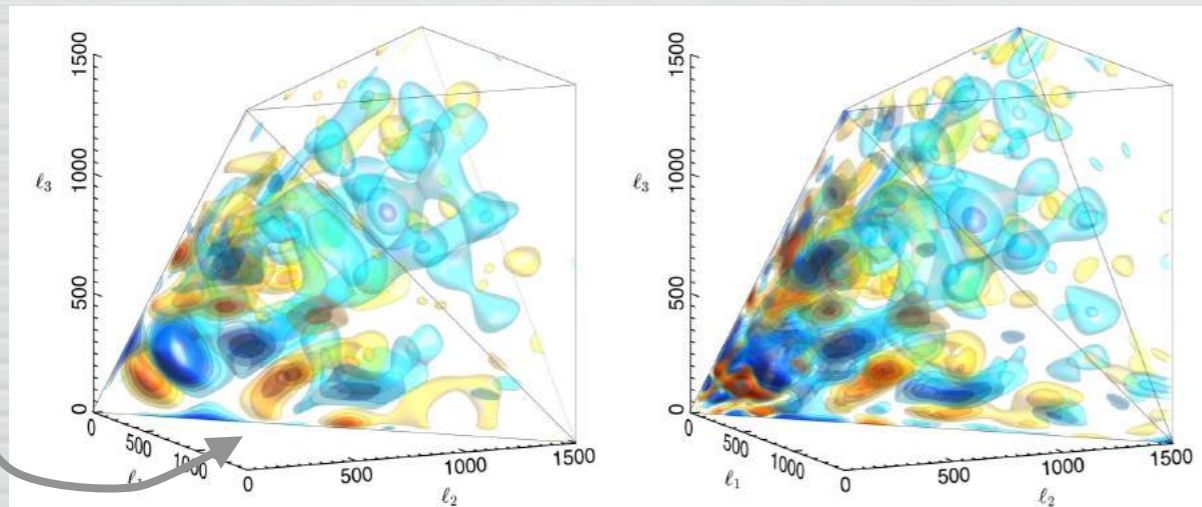
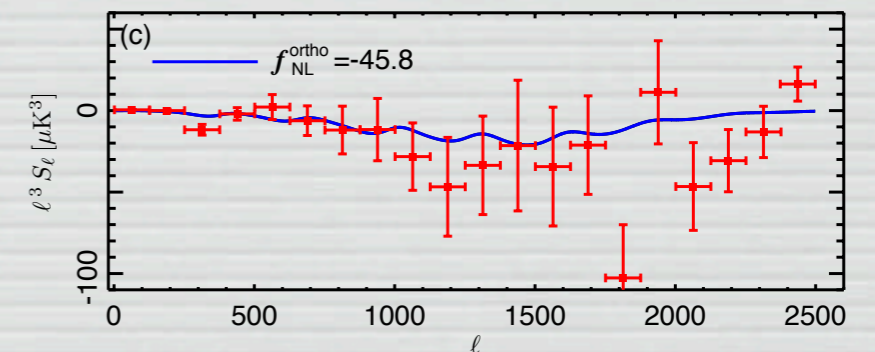
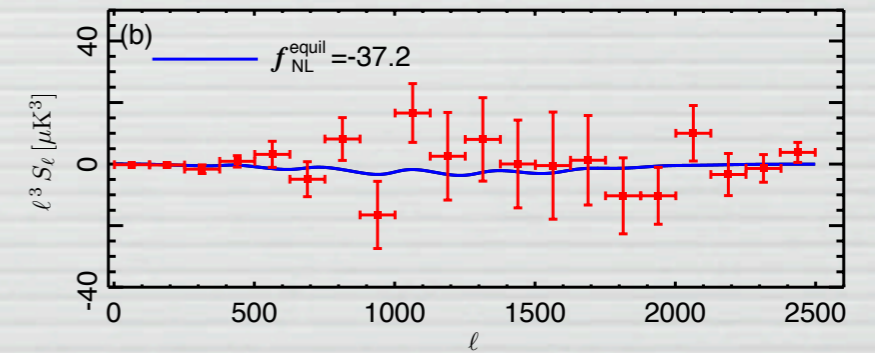
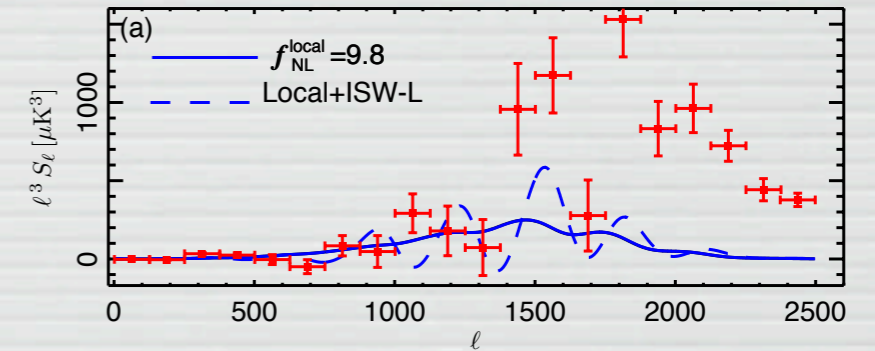
We see ISW lensing...



... and point sources



... but nothing primordial



The CMB: A Case Study

- Hierarchical Bayesian formalism
 - raw-data \Rightarrow maps \Rightarrow spectra \Rightarrow parameters
 - radical data compression
 - need to keep track of likelihood function details
- Checking assumptions
 - “anomalies”?
 - No obvious solution by changing the large-scale structure of spacetime (topology, Bianchi)
 - non-Gaussianity
 - lensing, point sources, correlations detected in Planck
 - no evidence yet for primordial non-Gaussianity