

# Uncertainty Quantification for multiscale kinetic equations with random inputs IV

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# VI. High dimensional random space

(R. Shu-J. Hu-J, Num. Math '17)

## Curse of dimension

- Boltzmann is already 6 dimension in space and velocity; random inputs add many more dimensions
- SG basis for random space:  
if polynomial of degree  $n$  is used, then the number of basis is  $\binom{n+d}{d}$

# Sparse Grids<sup>[2]</sup>

- Efficient methods to choose basis functions  $\{\Phi_k(\mathbf{z})\}$  in high dimensional random spaces
- Guo and Cheng<sup>[3]</sup> use sparse grids for a discontinuous Galerkin method for transport equations
- For sufficiently smooth function, the approximation error is  $O(K^{-(m+1)}(\log K)^{(m+2)(d-1)+1})$  where  $K$  is the number of basis, and  $m$  is the degree of polynomials.
- Partly break “the curse of dimensionality”

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[2] H.-J. Bungartz and M. Griebel, 2004

[3] W. Guo and Y. Cheng, 2016

- Restrict to the case  $I_{\mathbf{z}} = [-1, 1]^d$ , and  $\pi(\mathbf{z}) = \frac{1}{2^d}$
- $P^m(a, b)$  : the space of polynomials of degree at most  $m$  on the interval  $(a, b)$
- Start with 1-d piecewise polynomial space

$$V_N^m = \{\phi : \phi \in P^m(-1 + 2^{-N+1}j, -1 + 2^{-N+1}(j+1)), j = 0, 1, \dots, 2^N - 1\}.$$

- Define  $W_N^m$  as the orthogonal complement of  $V_{N-1}^m$  inside  $V_N^m$ . Then  $V_N^m = \bigoplus_{0 \leq j \leq N} W_j^m$
- Dimension of  $W_N^m$  is  $(m+1)2^{N-1}$

- In  $d$ -dimensional random space, define tensor grids

$$\mathbf{V}_{N,\mathbf{z}}^m = V_{N,z_1}^m \times \cdots \times V_{N,z_d}^m. \quad \mathbf{W}_{\mathbf{j},\mathbf{z}}^m = W_{j_1,z_1}^m \times \cdots \times W_{j_d,z_d}^m$$

- Then  $\mathbf{V}_{N,\mathbf{z}}^m = \bigoplus_{0 \leq |\mathbf{j}|_\infty \leq N} \mathbf{W}_{\mathbf{j},\mathbf{z}}^m$ .

When all the components of  $\mathbf{j}$  are large, the coefficients are very small. But such spaces have a lot of basis functions!

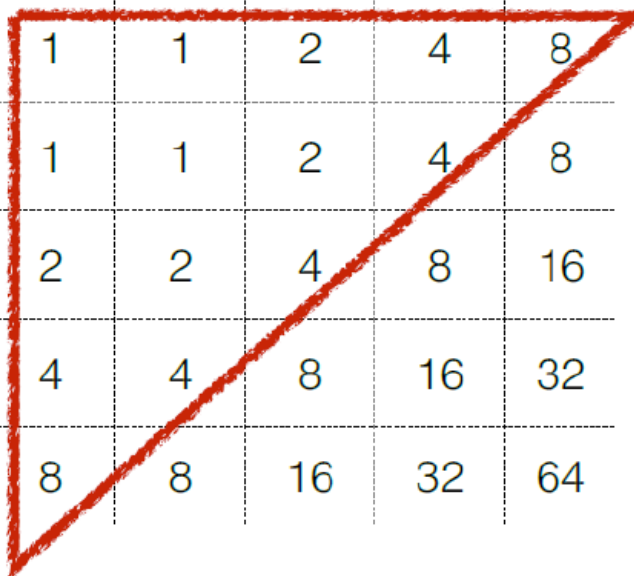
| $z_2 \backslash z_1$ | $W_0^0$ | $W_1^0$ | $W_2^0$ | $W_3^0$ | $W_4^0$ |
|----------------------|---------|---------|---------|---------|---------|
| $W_0^0$              | 1       | 1       | 2       | 4       | 8       |
| $W_1^0$              | 1       | 1       | 2       | 4       | 8       |
| $W_2^0$              | 2       | 2       | 4       | 8       | 16      |
| $W_3^0$              | 4       | 4       | 8       | 16      | 32      |
| $W_4^0$              | 8       | 8       | 16      | 32      | 64      |

- Idea: take  $\hat{\mathbf{V}}_{N,\mathbf{z}}^m = \bigoplus_{0 \leq |\mathbf{j}|_1 \leq N} \mathbf{W}_{\mathbf{j},\mathbf{z}}^m$ .
- The most expensive parts are dropped, without affecting the accuracy too much

• 256  48 !

- More effective in higher dimensional random spaces

| $z_2 \backslash z_1$ | $\mathbf{W}_0^0$ | $\mathbf{W}_1^0$ | $\mathbf{W}_2^0$ | $\mathbf{W}_3^0$ | $\mathbf{W}_4^0$ |
|----------------------|------------------|------------------|------------------|------------------|------------------|
| $\mathbf{W}_0^0$     | 1                | 1                | 2                | 4                | 8                |
| $\mathbf{W}_1^0$     | 1                | 1                | 2                | 4                | 8                |
| $\mathbf{W}_2^0$     | 2                | 2                | 4                | 8                | 16               |
| $\mathbf{W}_3^0$     | 4                | 4                | 8                | 16               | 32               |
| $\mathbf{W}_4^0$     | 8                | 8                | 16               | 32               | 64               |



# Number of Basis Functions Sparse vs. Full

|         | (a) $m = 0$ |           |             | (b) $m = 1$ |           |             |
|---------|-------------|-----------|-------------|-------------|-----------|-------------|
|         | $N = 3$     | $N = 4$   | $N = 5$     | $N = 3$     | $N = 4$   | $N = 5$     |
| $d = 1$ | 8,8         | 16,16     | 32,32       | 16,16       | 32,32     | 64,64       |
| $d = 2$ | 20,64       | 48,256    | 112,1024    | 80,256      | 192,1024  | 448,4096    |
| $d = 3$ | 38,512      | 104,4096  | 272,32768   | 304,4096    | 832,32768 | 2176,262144 |
| $d = 4$ | 63,4096     | 192,65536 | 552,1048576 |             |           |             |

Table 1: Comparison of basis function:  $d$  is the dimension; in each cell, the left number (blue) is the number of basis of functions of  $\hat{V}_N^m$ ; the right number (red) is the number of basis of functions of  $V_N^m$

Sparse grid:  $O((m + 1)^d 2^N N^{d-1})$

Full grid:  $O((m + 1)^d 2^{Nd})$

# Sparsity of $S_{ijk}$

- The most expensive part is the computation of

$$Q_k(f^K, f^K) = \sum_{i,j=0}^K S_{ijk} Q(\hat{f}_i, \hat{f}_j), \quad k = 0, 1, \dots, K$$

$$\text{where } S_{ijk} = \int_{I_z} b(\mathbf{z}) \Phi_i(\mathbf{z}) \Phi_j(\mathbf{z}) \Phi_k(\mathbf{z}) \pi(\mathbf{z}) d\mathbf{z}.$$

- The computation of  $Q(\hat{f}_i, \hat{f}_j)$  is unnecessary if

$$S_{ijk} = 0, \quad \forall k$$

- This happens if  $\Phi_i$  and  $\Phi_j$  have disjoint supports



- Since  $\Phi_i$  and  $\Phi_j$  are tensor products of locally supported functions, their supports are disjoint if one of their components are disjoint.

**Theorem 4.1.** *The pairs of basis functions of  $\hat{\mathbf{V}}_N^m$  with intersecting supports have a total number at most  $O((m+1)^{2d}2^{2N}N^{d+1})$ .*

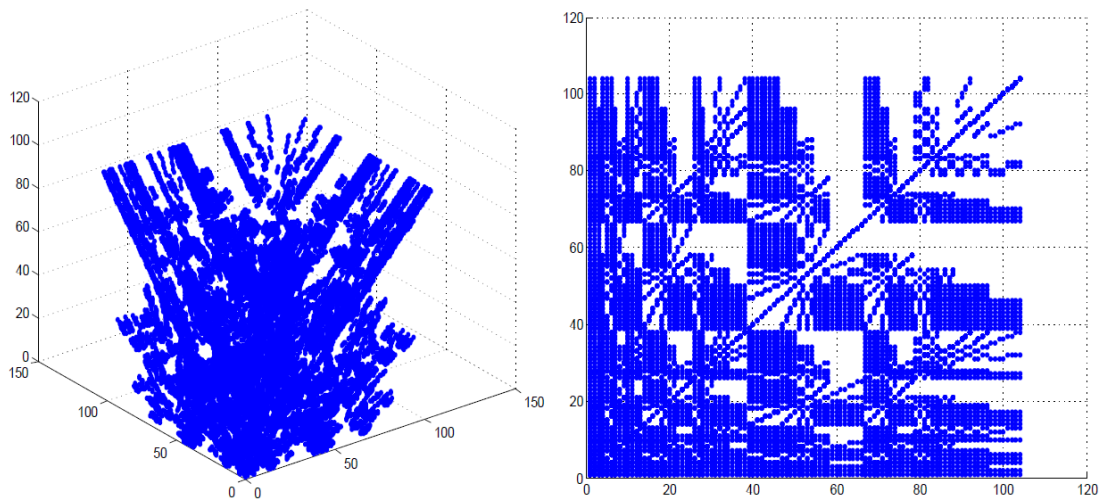


Figure 3: Demonstration of sparsity of  $S_{ijk}$ :  $m = 0, N = 4, d = 3$ .

# Regularity in the random space

- **Theorem.** *Assume that  $B$  depends on  $\mathbf{z}$  linearly,  $B$  and  $\partial_{\mathbf{z}}B$  are locally integrable and bounded in  $\mathbf{z}$ . Assume  $\sup_{\mathbf{z} \in I_{\mathbf{z}}} \|f^0\|_{L^1_{\mathbf{v}}} \leq M$ ,  $\|f^0\|_k < \infty$  for some integer  $k \geq 0$ . Then there exists a constant  $C_k > 0$ , depending only on  $B$ ,  $M$ ,  $T$ , and  $\|f^0\|_k$  such that*

$$\|f\|_k \leq C_k, \quad \text{for any } t \in [0, T].$$

- $\|f(t, \cdot, \cdot)\|_k = \sup_{\mathbf{z} \in I_{\mathbf{z}}} \left( \sum_{|\mathbf{l}|=0}^k \|\partial_{\mathbf{z}}^{\mathbf{l}} f(t, \mathbf{v}, \mathbf{z})\|_{L^2_{\mathbf{v}}}^2 \right)^{1/2}$

# Projection Error

- Number of basis functions of  $\hat{\mathbf{V}}_N^m$  is  $K = O((m+1)^d 2^N N^{d-1})$ .

- **Lemma.**<sup>[3]</sup> For any  $f \in \mathcal{H}^{m+1}(I_{\mathbf{z}})$ ,  $N \geq 1$ , we have

$$\|P_K f - f\|_{L^2(I_{\mathbf{z}})} \leq (C(m)N)^d 2^{-N(m+1)} \|f\|_{\mathcal{H}^{m+1}(I_{\mathbf{z}})}.$$

- Express the error in terms of  $K$ ,

$$\|P_K f - f\|_{L^2(I_{\mathbf{z}})} \leq C(m, d) K^{-(m+1)} (\log K)^{(m+2)(d-1)+1} \|f\|_{\mathcal{H}^{m+1}(I_{\mathbf{z}})}.$$

- The space  $\mathcal{H}^m(I_{\mathbf{z}})$  is defined by  $\|f\|_{\mathcal{H}^m(I_{\mathbf{z}})} = \max \|\partial_{z_{i_1}}^m \cdots \partial_{z_{i_r}}^m\|_{L^2(I_{\mathbf{z}})}$

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[3] W. Guo, Y. Cheng, 2016

# Accuracy estimate

**Theorem.** *Assume the random variable  $z$  and initial data  $f^0$  satisfy the assumption in the lemma for regularity, and the Galerkin approximation  $f^K$  is uniformly bounded in  $K$ , then*

$$\|f - f^K\|_{L^2_{v,z}} \leq C(t) \left\{ C(m, d) K^{-(m+1)} (\log K)^{(m+2)(d-1)+1} + \|e^K(0)\|_{L^2_{v,z}} \right\},$$

where  $e^K(0) = (P_K f - f^K)|_{t=0}$ .

# Numerical Result 1: Approximation Error

- Take function  $f(\mathbf{z})$  in random spaces with dimension 2, 3, 4

$$f(\mathbf{z}) = \frac{1}{2\pi\mathcal{K}(\mathbf{z})^2} \exp\left(-\frac{1}{2\mathcal{K}(\mathbf{z})}\right) \left(2\mathcal{K}(\mathbf{z}) - 1 + \frac{1 - \mathcal{K}(\mathbf{z})}{2\mathcal{K}(\mathbf{z})}\right),$$

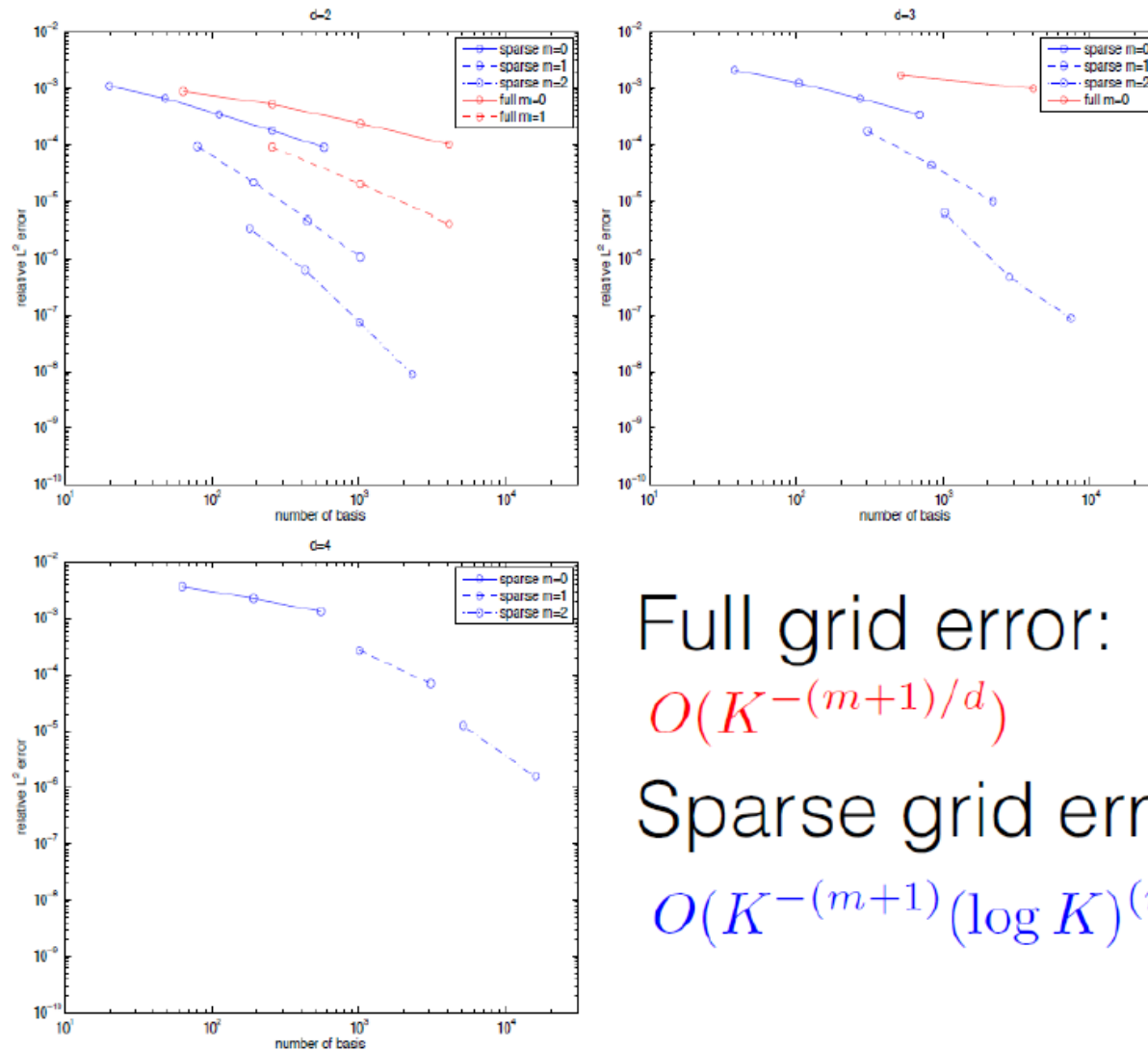
where

$$\mathcal{K}_{d=2}(\mathbf{z}) = 1 - 0.5(0.5 + 0.1 \sin(z_1) + 0.1 \sin(2z_2)),$$

$$\mathcal{K}_{d=3}(\mathbf{z}) = 1 - 0.5(0.5 + 0.1 \sin(z_1) + 0.1 \sin(2z_2) + 0.1 \cos(z_3)),$$

$$\mathcal{K}_{d=4}(\mathbf{z}) = 1 - 0.5(0.5 + 0.1 \sin(z_1) + 0.1 \sin(2z_2) + 0.1 \cos(z_3) + 0.1 \cos(2z_4)).$$

- Compare relative error  $\frac{\|f - Pf\|_{L^2}}{\|f\|_{L^2}}$



Full grid error:

$$O(K^{-(m+1)/d})$$

Sparse grid error:

$$O(K^{-(m+1)} (\log K)^{(m+2)(d-1)})$$

Figure 1: Comparison of approximation error for  $d = 2, 3, 4$ . For  $d = 4$  we do not give the result by tensor grid because the number of basis functions is too large.

# Numerical Result 2: Solve BE with uncertainty

- **6**-dimensional random space. 3 for initial data, 2 for boundary data, 1 for collision kernel. 1-d in  $\mathbf{X}$ , 2-d in  $\mathbf{V}$
- Initial data: equilibrium with

$$\rho(x, \mathbf{z}) = 1, \quad \mathbf{u}(x, \mathbf{z}) = 0, \quad T = 1 + 0.5(1 + 0.2z_2) \exp(-100(1 + 0.1z_3)(x - 0.4 - 0.01z_1)^2)$$

- Boundary data: at  $x = 0$  take Maxwell boundary with

$$T_w = 1 + 0.2z_4, \quad \alpha = 0.5 + 0.3z_5.$$

- Collision kernel:  $b(\mathbf{z}) = 1 + 0.2z_6$ .
- Take sparse grid basis with  $m = 0, N = 3$ , number of basis: 138
- Compare with stochastic collocation method at  $t = 0.04$

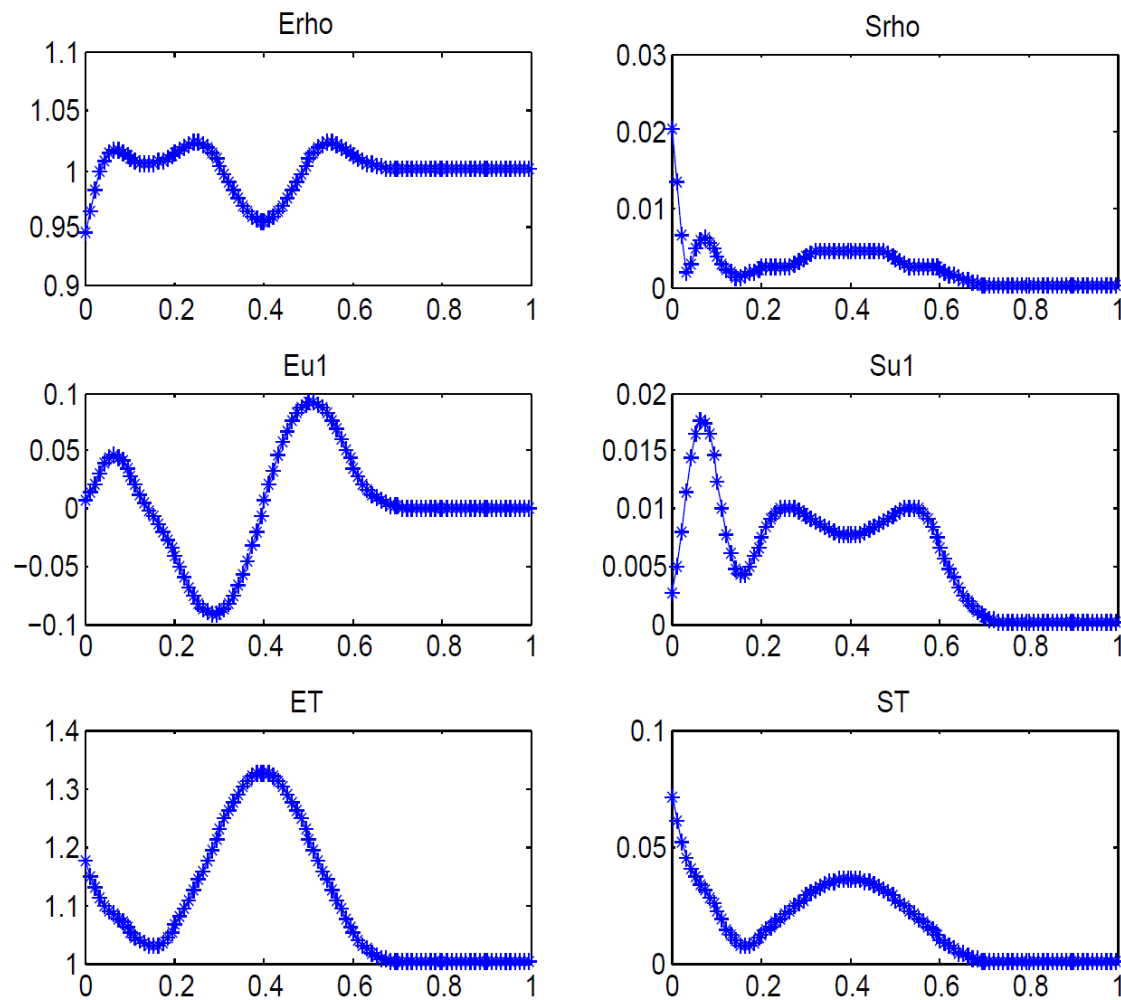


Figure 7: The Boltzmann equation with randomness on initial data, boundary data, and collision kernel ( $d = 6$ ).  $N_x = 100$ ,  $t = 0.04$ . Curve: collocation with  $M_z = 4$ ; asterisks: Galerkin with  $m = 0, N = 3$ . Left column: mean of density, first component of bulk velocity, and temperature. Right column: standard deviation of density, first component of bulk velocity, and temperature.



## High dimensional random space (J-Zuazua-Y. Zhu)

- Consider random parametric linear Vlasov-Fokker-Planck equation

$$\epsilon \partial_t f + v \partial_x f - \partial_x \phi \partial_v f = \frac{1}{\epsilon} \mathcal{F} f, \quad x, v \in \Omega = (0, l) \times \mathbb{R}$$

$$\mathcal{F} f = \partial_v \left( M \partial_v \left( \frac{f}{M} \right) \right) \quad M(v) = \frac{1}{\sqrt{2\pi}} e^{-\frac{|v|^2}{2}}$$

$$E(x, \mathbf{z}) = \partial_x \phi(x, \mathbf{z}) = \bar{E}(x) + \sum_{j \geq 1} z_j E_j(x),$$
$$\mathbf{z} \in U = [-1, 1]^\infty$$

# Best N-approximation

We seek approximate solution  $h_\Lambda$  in a finite dimensional space,

$$\mathbb{P}_\Lambda = \{h_\Lambda : h_\Lambda = \sum_{\nu \in \Lambda} h_\nu(t, x, v) L_\nu(\mathbf{z})\}, \quad (3.1)$$

where  $\Lambda$  is an index set with infinite dimensional vectors  $\nu$ . Here  $L_\nu(\mathbf{z})$  form the normalized Legendre polynomial basis such that,

$$L_\nu = \prod_{j \geq 1} L_{\nu_j}(z_j), \quad \int_{-1}^1 L_k(z_j) L_l(z_j) \frac{dz_j}{2} = \delta_{kl}, \quad (3.2)$$

so  $L_\nu$  is also an orthogonal basis in  $L^2(U, d\rho)$ .

the projection of the solution  $h$  onto  $\mathbb{P}_\Lambda$ ,

$$P_\Lambda h = \sum_{\nu \in \Lambda} \left( \int_U h L_\nu d\rho \right) L_\nu := \sum_{\nu \in \Lambda} h_\nu L_\nu = \operatorname{argmin}_{h_\Lambda \in \mathbb{P}_\Lambda} \|h - h_\Lambda\|_{L^2(U, V, d\rho)}.$$

The best N approximation is a form of nonlinear approximation that searches for  $\nu \in \Lambda$  according to the largest  $N$  coefficients  $\|h_\nu\|_V$

# Cohen-Devore-Schwab ('10)

**Theorem 3.1** (Corollary 3.11 of [3]). *Consider a parametric problem of the form*

$$\mathcal{P}(f, a) = 0, \quad (3.4)$$

*with random field  $a = \bar{a}(x) + \sum_{j \geq 1} z_j \psi_j(x) \in X$ ,  $\mathbf{z} \in U$ , where  $X$  is certain space of  $x$ . Assume the solution map  $a \rightarrow f(a)$  admits a holomorphic extension to an open set  $\mathcal{O} \in X$  which contains  $a(U) = \{a(\mathbf{z}) : \mathbf{z} \in U\}$ , with uniform bound*

$$\sup_{a \in \mathcal{O}} \|u(a)\|_V \leq C. \quad (3.5)$$

*If in addition  $(\|\psi_j\|_X)_{j \geq 1} \in \ell^p(\mathbb{N})$  for some  $p < 1$ , then for the set of indices  $\Lambda_n$  that corresponds to the  $n$  largest  $f_\nu = \left\| \int f L_\nu d\rho \right\|_V$ , one has,*

$$\left\| f - \sum_{\nu \in \Lambda_n} f_\nu L_\nu \right\|_{L^2(U, V, \rho)} \leq \frac{C}{(n+1)^s}, \quad s = \frac{1}{p} - \frac{1}{2} \quad (3.6)$$

*where  $C := \left\| \|f_\nu\|_V \right\|_{\ell^p}$ .*

- While C-D-S proved it for elliptic PDEs, we extend it to linear Vlasov-Fokker-Planck equations with random forcing
- 1) assume **isotropy**

**Condition 2.1.** Assume  $\|\partial_x E\|_{L^\infty(U, L_x^\infty)}, \|E\|_{L^\infty(U, L_x^\infty)} \leq C_E$ ;  $\|\partial_x E_j\|_{L_x^\infty}, \|E_j\|_{L_x^\infty} \leq C_j$ . Furthermore, the upper bounds  $C_E, C_j$  satisfies,

$$C_E + \sum_{j \geq 1} C_j \leq \min \left\{ \frac{2\lambda}{7}, \frac{C_s}{2} \right\}, \quad C_E \leq \frac{\lambda C_s}{48}, \quad (2.16)$$

$$\sum_{j \geq 1} \sqrt{C_j} \leq \sqrt{\frac{\lambda C_s}{8}}, \quad (C_j)_{j \geq 1} \in l^{\frac{p}{2}}(\mathbb{N}), \text{ for some } p \leq 1. \quad (2.17)$$

- 2) prove **analyticity**

**Theorem 3.2.** *Under Condition 2.1, for  $\forall \mathbf{z} \in U$ , one has the following estimate for the solution to (2.8),*

$$\|\partial^\nu h(t)\|_V \leq B(t) (|\nu|!) b^\nu. \quad (3.8)$$

where  $b$  is an infinite dimensional vector with the  $j$ -th component

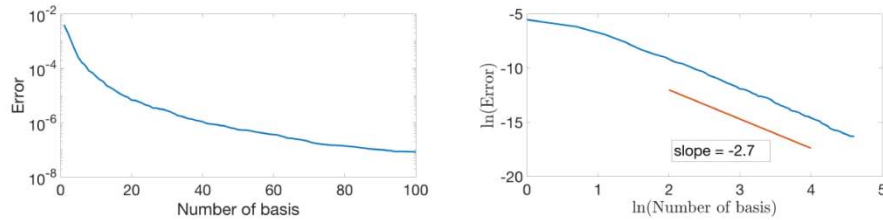
$$b_j = \sqrt{\frac{3C_j}{2C_3}}, \quad (3.9)$$

$B(t)$  is an exponential decay function in  $t$ ,

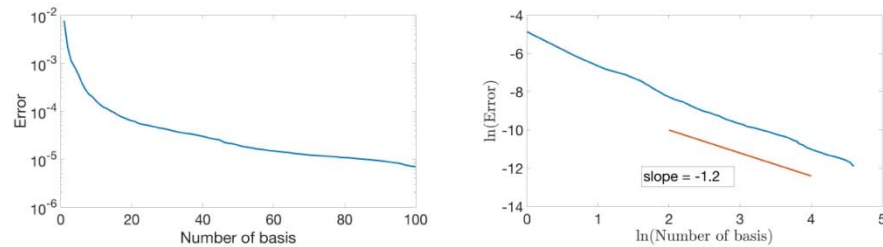
$$B(t) = \min \left\{ \frac{2}{\epsilon} \|h(0)\|_V e^{-\frac{2C_3}{\epsilon^2}t}, 2 \|h(0)\|_V e^{-2C_3t} \right\}, \quad (3.10)$$

$C_3 = \frac{\lambda C_s}{16}$ ,  $C_s, \lambda$  are constants defined in (1.1), (2.10).

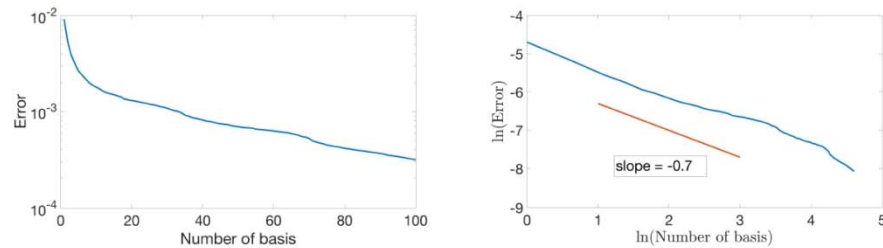
# Numerical tests



(a) The convergence rate for the case of  $E(x, \mathbf{z}) = \frac{\sin(x)}{2} + \sum_{j=1}^{100} \frac{\cos(jx)}{2^j} z_j$



(b) The convergence rate for the case of  $E(x, \mathbf{z}) = \frac{\sin(x)}{2} + \sum_{j=1}^{100} \frac{\cos(jx)}{j^2} z_j$



(c) The convergence rate for the case of  $E(x, \mathbf{z}) = \frac{\sin(x)}{2} + \sum_{j=1}^{100} \frac{\cos(jx)}{j} z_j$

**Figure 1:** This is the convergence rate of the approximate solution to (4.29) at  $t = 1$  with different parametric forcing terms obtained by Algorithm 4.1, where we set  $\epsilon = 1$ .

## Kinetic equations vs Uncertainty Quantification

- PDEs in phase space with velocity
  - Polynomial chaos based stochastic Galerkin (loss of hyperbolicity for nonlinear hyperbolic systems)
  - Dimension reduction: mean-field limit, molecular chaos-BBGKY etc.
  - Particles to kinetic equations
  - AP
- PDEs with parameters
  - Grad's thirteen moment closure (via Hermite polynomials) (loss of hyperbolicity)
  - Dimension reduction: low rank perturbation; evolution of marginal distribution, ...
  - Stochastic gradient descent to Fokker-Planck equation
  - sAP

# Open questions

- For SG for Boltzmann, in the fluid limit, one arrives at a SG for compressible Euler. **Hyperbolicity**? ( a direct application of SG for Euler loses hyperbolicity)
- Sharper estimate? Remove linearity assumption in  $z$ , stronger perturbation, more general random variables and orthogonal polynomials
- **Landau damping** under uncertainty (preliminary results by **R. Shu-J** on regularity of solution in random space)
- Control and inverse problems (regularization based or Bayesian inference theory based)
- Utilize sparsity to reduce computational costs
- Machine learning techniques
- Other applications